



Subspace Version of Wilks'-Lambda Test and Application to Space-Time Adaptive Processing



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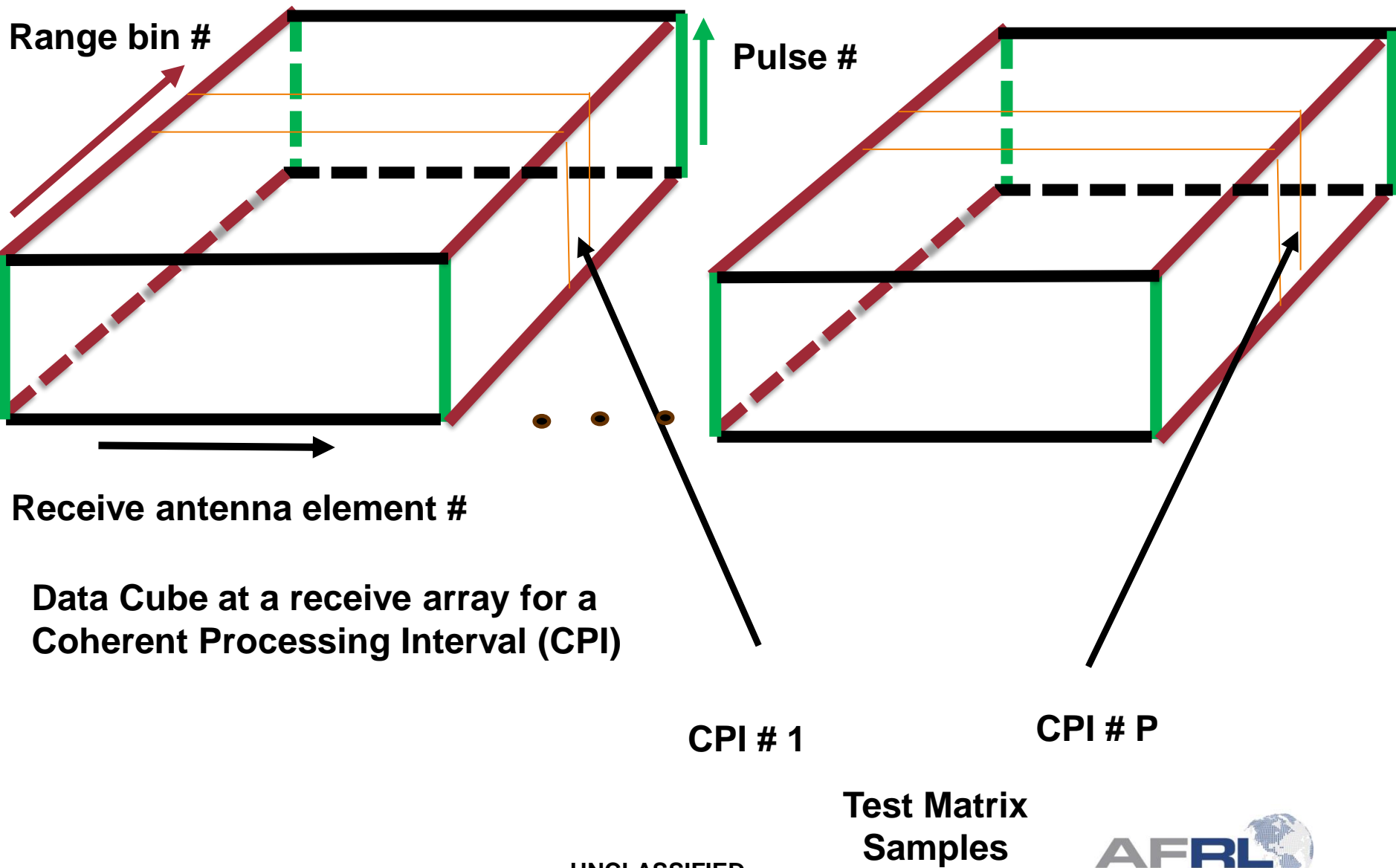
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Airborne detection geometry and Signal Subspace





Data Format



Received I/Q samples from data cube rearranged in the following manner

Test Matrix:

$$\mathbf{Z} = \begin{bmatrix} \mathbf{Z}_1 \\ \mathbf{Z}_2 \end{bmatrix} ; \quad \mathbf{Z}_1 \in \mathbb{C}^{M \times P} ; \quad \mathbf{Z}_2 \in \mathbb{C}^{(N-M) \times P}$$

Interference Training data:

$$\mathbf{Y} = \begin{bmatrix} \mathbf{Y}_1 \\ \mathbf{Y}_2 \end{bmatrix} ; \quad \mathbf{Y}_1 \in \mathbb{C}^{M \times K} ; \quad \mathbf{Y}_2 \in \mathbb{C}^{(N-M) \times K}$$

N : Length of column vectors (Number of degrees of freedom)

M : Dimension of signal subspace

P : Number of observations

K : Number of independent training vectors



Statistical Model for Test and Training Data



$$\mathbf{Z} \in C^{N \times P}; \mathbf{Z}_1 \in C^{M \times P}; \mathbf{Z}_2 \in C^{(N-M) \times P} \quad (\text{Test Matrix})$$

$$\mathbf{Y} \in C^{N \times K}; \mathbf{Y}_1 \in C^{M \times K}; \mathbf{Y}_2 \in C^{(N-M) \times K} \quad (\text{Training Vectors})$$

Data Vectors

$$\text{Vec}[\mathbf{Z}] \in \begin{cases} N_c(\mathbf{0}, \mathbf{I}_P \otimes \mathbf{R}) & : H_0 \\ N_c\left(\text{Vec}\begin{bmatrix} \mathbf{A}_1 \\ \mathbf{0}_{(N-M) \times P} \end{bmatrix}, \mathbf{I}_P \otimes \mathbf{R}\right) & : H_1 \quad \text{Tr}[\mathbf{A}_1 \mathbf{A}_1^H] > 0 \end{cases}$$

$$\text{Vec}[\mathbf{Y}] \in \begin{cases} N_c(\mathbf{0}, \mathbf{I}_K \otimes \mathbf{R}) & : H_0 \\ N_c(\mathbf{0}, \mathbf{I}_K \otimes \mathbf{R}) & : H_1 \end{cases}$$

Statistical Model



Wilks' Lambda Test for signal detection in unknown interference



Test Matrix:

$$\mathbf{Z} = \begin{bmatrix} \mathbf{Z}_1 \\ \mathbf{Z}_2 \end{bmatrix} = \begin{cases} \begin{bmatrix} \mathbf{X}_1 \\ \mathbf{X}_2 \end{bmatrix} & : H_0 \\ \begin{bmatrix} \mathbf{X}_1 \\ \mathbf{X}_2 \end{bmatrix} + \begin{bmatrix} \mathbf{A}_1 \\ \mathbf{A}_2 \end{bmatrix} & : H_1 \end{cases}$$

$$\mathbf{A}_1 \in \mathbb{C}^{M \times P} \quad ; \quad \text{Tr}[\mathbf{A}_1 \mathbf{A}_1^H] > 0 \quad ; \quad \mathbf{A}_2 = \mathbf{0}_{(N-M) \times P}$$

**Interference
Training data:**

$$\mathbf{Y} = \begin{bmatrix} \mathbf{Y}_1 \\ \mathbf{Y}_2 \end{bmatrix} \quad : \quad H_0 \text{ and } H_1$$

Wilks' Lambda Test:

$$t_{WL} = \left[\frac{|\mathbf{Y}\mathbf{Y}^\dagger + \mathbf{Z}\mathbf{Z}^\dagger|}{|\mathbf{Y}\mathbf{Y}^\dagger|} \right] \underset{H_0}{\overset{H_1}{\gtrless}} \eta_{WL}$$



Distribution of Wilks' Lambda Statistic



$$t_{WL}^{-1} \stackrel{\text{dist}}{\sim} \prod_{m=1}^N x_{\beta}(K+1-m, P) ; \text{ if } H_0,$$

Product of statistically independent central beta distributed random variables

$$\mathbf{A} = \mathbf{s} \mathbf{a}^{\dagger}, \quad \mathbf{s} \in \mathbb{C}^{N \times 1} \quad \mathbf{a} \in \mathbb{C}^{P \times 1}$$

Rank 1 signal model for Alternative Hypothesis

$$t_{WL}^{-1} \stackrel{\text{dist}}{\sim} x_{\beta}(K, P; c_0) \left[\prod_{m=2}^N x_{\beta}(K+1-m, P) \right] ; \text{ if } H_1.$$

$$c_0 = \|\mathbf{a}\|^2 \mathbf{s}^{\dagger} \mathbf{R}^{-1} \mathbf{s}.$$

Signal-to-interference-plus-noise ratio



Subspace version of the Wilks' Lambda Test



In STAP applications, the number of degrees of freedom (N) is typically large compared to signal subspace dimension (M)

Direct application of Wilks' Lambda test to STAP is not very useful

Need a signal subspace version of the Wilks' Lambda Test

All data resolved into signal subspace component and interference-plus-noise only components (contains no signal)

Use the training data and the test data from the interference-plus-noise only subspace to estimate and suppress the interference component in the signal subspace



Subspace version of Wilks' Lambda Test



$$y_{SWL} = \frac{|S_{1.2} + (Z_{1.2}(\mathbf{I}_P + Z_2^\dagger S_{22}^{-1} Z_2)^{-1} Z_{1.2}^\dagger)|}{|S_{1.2}|} \underset{H_0}{\overset{H_1}{\gtrless}} \eta.$$

$$S = \begin{bmatrix} S_{11} & S_{12} \\ S_{21} & S_{22} \end{bmatrix} = \begin{bmatrix} Y_1 Y_1^\dagger & Y_1 Y_2^\dagger \\ Y_2 Y_1^\dagger & Y_2 Y_2^\dagger \end{bmatrix}, \quad S_{1.2} = S_{11} - S_{12} S_{22}^{-1} S_{21}$$

Schur complement of S_{22}
In S

$$Z_{1.2} = Z_1 - \underbrace{S_{12} S_{22}^{-1} Z_2}$$

Conditional mean of Z1 given Z2



Distribution of subspace version of Wilks' Lambda Statistic



$$[t_{SWL}^{-1}|H_0] \stackrel{\text{dist}}{\sim} \prod_{m=1}^M x_{\beta}(K - N + M + 1 - m, P),$$

$$[t_{SWL}^{-1}|\rho, c_0, H_1] \stackrel{\text{dist}}{\sim} x_{\beta}(K - N + M, P; c_0\rho) \\ \times \left[\prod_{m=2}^M x_{\beta}(K - N + 1 + M - m, P) \right]$$

$$\rho = \hat{\mathbf{a}}^{\dagger}(\mathbf{I}_P + \mathbf{Z}_2^{\dagger}\mathbf{S}_{22}^{-1}\mathbf{Z}_2)^{-1}\hat{\mathbf{a}}, \quad \hat{\mathbf{a}} = \mathbf{a}/\|\mathbf{a}\|;$$

$$c_0 = \|\mathbf{a}\|^2 \mathbf{s}^{\dagger} \mathbf{R}^{-1} \mathbf{s}.$$

**Signal-to-interference-plus-noise
ratio**



Analytical expressions for PD and PFA



$$[y_{SWL}^{-1}|H_0] = \prod_{m=1}^M x_{\beta}(K - N + M + 1 - m, P)$$

$$f_{y_{SWL}^{-1}}(x) = \sum_{n=0}^{J_{max}} p_n(M) f_{\beta}(x; L, MP + n)$$

$$f_{\beta}(x; m, n) = \frac{\Gamma(m+n)}{\Gamma(m)\Gamma(n)} x^{m-1} (1-x)^{n-1}$$

$$f_{\beta}(x; m, n|c) = e^{-cx} \sum_{k=0}^m \binom{m}{k} \frac{c^k \Gamma(m+n)}{\Gamma(m+n+k)} f_{\beta}(x; m, n+k)$$

$$; 0 \leq x \leq 1.$$

R. S. Raghavan, "Performance comparison of two subspace based GLRTs for rank-1 signal detection in unknown interference with multiple observations," **IEEE Transactions on Aerospace and Electronic Systems**, Vol. 59, No.1, pp. 418 - 433, Feb. 2023.



Invariance to transformations of data



Detection Statistic must be invariant to following Data Transformation:

$$\begin{bmatrix} \mathbf{Z}_1 \\ \mathbf{Z}_2 \end{bmatrix} \rightarrow \begin{bmatrix} \mathbf{C}_{11} & \mathbf{C}_{12} \\ \mathbf{0} & \mathbf{C}_{22} \end{bmatrix} \begin{bmatrix} \mathbf{Z}_1 \\ \mathbf{Z}_2 \end{bmatrix} \begin{bmatrix} \mathbf{V}_1 \\ \mathbf{V}_2 \end{bmatrix}$$

$$\begin{bmatrix} \mathbf{Z}_1 \\ \mathbf{Z}_2 \end{bmatrix} \rightarrow \begin{bmatrix} \mathbf{C}_{11}\mathbf{Z}_1 + \mathbf{C}_{12}\mathbf{Z}_2 \\ \mathbf{C}_{22}\mathbf{Z}_2 \end{bmatrix} \begin{bmatrix} \mathbf{V}_1 \\ \mathbf{V}_2 \end{bmatrix}$$

$$\mathbf{C}_{11} \in \mathbb{C}^{M \times M} ; |\mathbf{C}_{11}| \neq 0$$

$$\mathbf{C}_{22} \in \mathbb{C}^{(N-M) \times (N-M)} ; |\mathbf{C}_{22}| \neq 0$$

\mathbf{V} : Unitary Matrix

$$\begin{bmatrix} \mathbf{Y}_1 \\ \mathbf{Y}_2 \end{bmatrix} \rightarrow \begin{bmatrix} \mathbf{C}_{11} & \mathbf{C}_{12} \\ \mathbf{0} & \mathbf{C}_{22} \end{bmatrix} \begin{bmatrix} \mathbf{Y}_1 \\ \mathbf{Y}_2 \end{bmatrix} \begin{bmatrix} \mathbf{U}_1 \\ \mathbf{U}_2 \end{bmatrix}$$

$$\begin{bmatrix} \mathbf{Y}_1 \\ \mathbf{Y}_2 \end{bmatrix} \rightarrow \begin{bmatrix} \mathbf{C}_{11}\mathbf{Y}_1 + \mathbf{C}_{12}\mathbf{Y}_2 \\ \mathbf{C}_{22}\mathbf{Y}_2 \end{bmatrix} \begin{bmatrix} \mathbf{U}_1 \\ \mathbf{U}_2 \end{bmatrix}$$

\mathbf{U} : Unitary matrix



Maximal Invariant Statistic

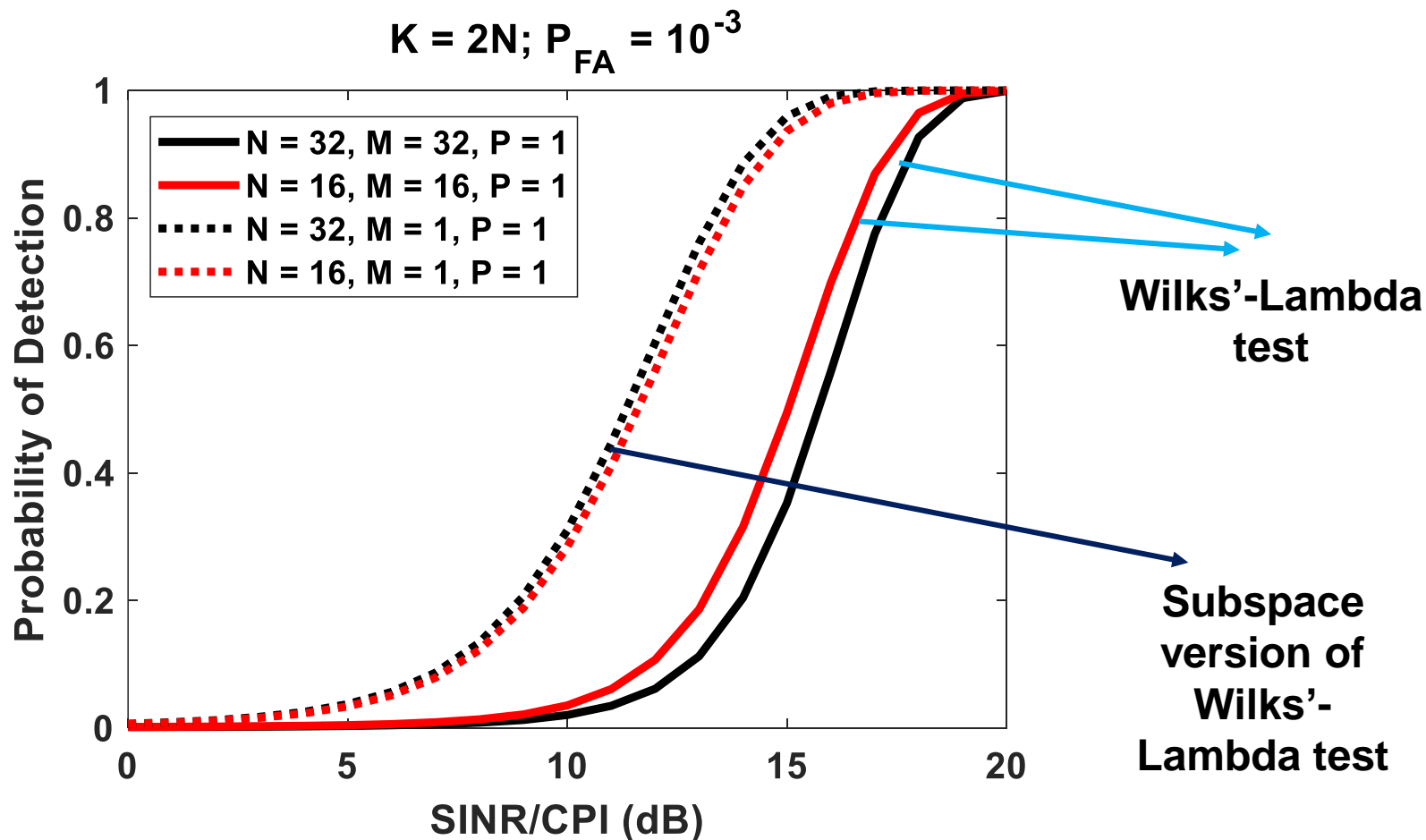


$$\begin{aligned} \mathbf{T}_{1.2} &= \mathbf{Z}_{1.2}^\dagger \mathbf{S}_{1.2}^{-1} \mathbf{Z}_{1.2} \in \mathbb{C}^{P \times P} & y_{SWL} &= |\mathbf{I}_M + \mathbf{S}_{1.2}^{-1} (\mathbf{Z}_{1.2} (\mathbf{I}_P + \mathbf{Z}_2^\dagger \mathbf{S}_{22}^{-1} \mathbf{Z}_2)^{-1} \mathbf{Z}_{1.2}^\dagger)| \\ \mathbf{T}_{22} &= \mathbf{Z}_{22}^\dagger \mathbf{S}_{22}^{-1} \mathbf{Z}_{22} \in \mathbb{C}^{P \times P} & &= |\mathbf{I}_P + [\mathbf{Z}_{1.2}^\dagger \mathbf{S}_{1.2}^{-1} \mathbf{Z}_{1.2}] [\mathbf{I}_P + \mathbf{Z}_2^\dagger \mathbf{S}_{22}^{-1} \mathbf{Z}_2]^{-1}| \\ \mathbf{T} &= \mathbf{Z}^\dagger \mathbf{S}^{-1} \mathbf{Z} \in \mathbb{C}^{P \times P} & &= |\mathbf{I}_P + \mathbf{T}_{1.2} [\mathbf{I}_P + \mathbf{T}_{22}]^{-1}| \\ \mathbf{T} &= \mathbf{T}_{1.2} + \mathbf{T}_{22} \end{aligned}$$

R. S. Raghavan, "Maximal Invariant Statistic for subspace signal detection in Unknown Interference with multiple observations," **IEEE Transactions on Aerospace and Electronic Systems**, Vol. 60, No.2, pp. 2422 – 2427, April 2024.

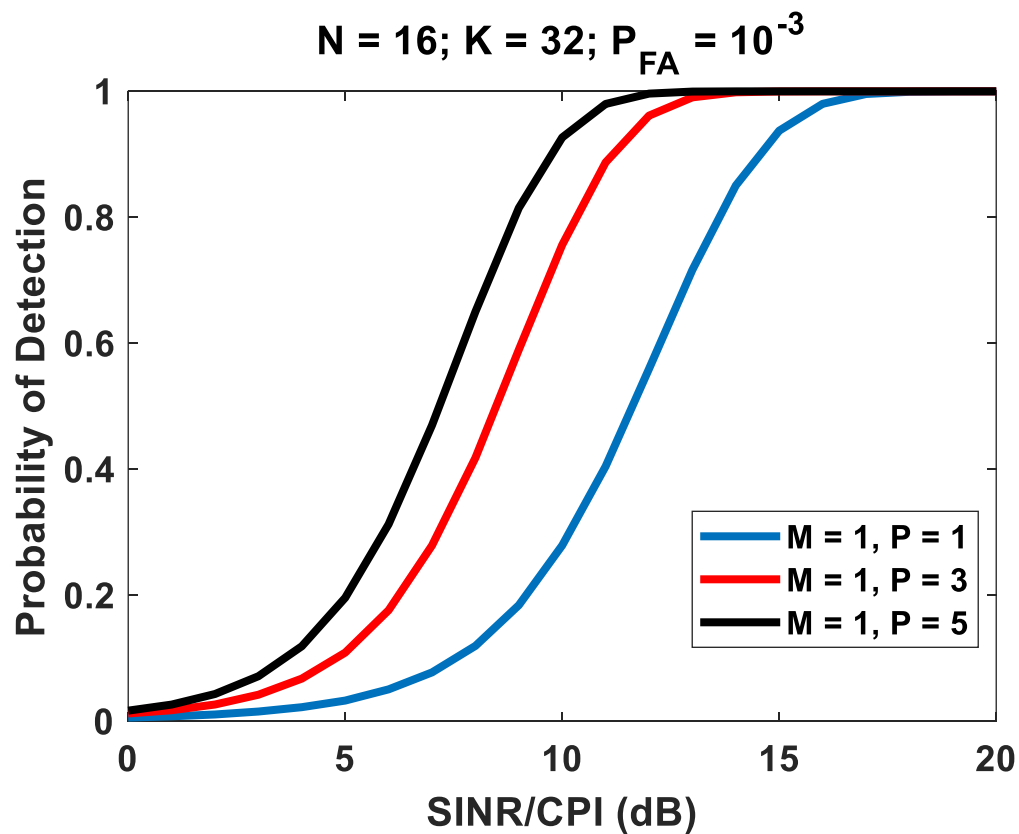


Sample Result



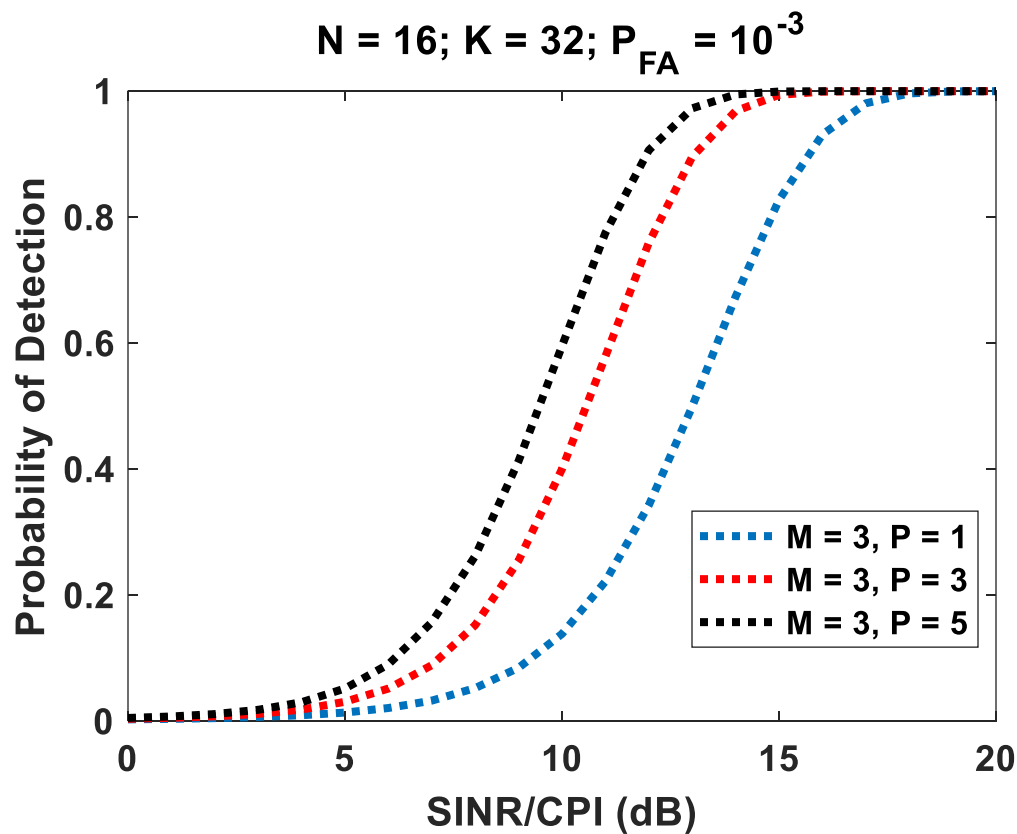


Sample Result



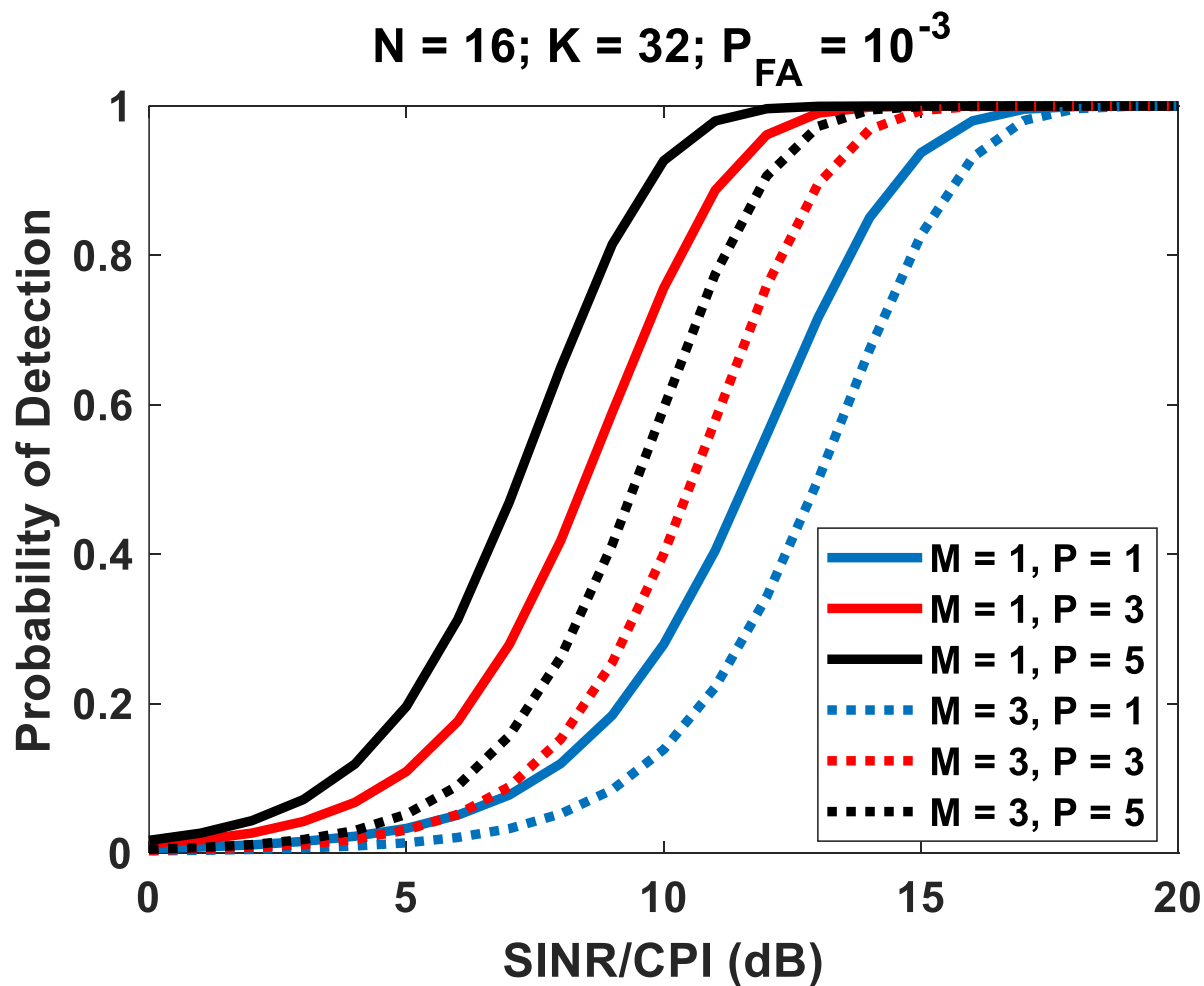


Sample Result





Sample Result





Summary



- Subspace version of Wilks-Lambda test derived for STAP ($N \gg M$).
- Test used to detect a subspace signal in unknown interference for multiple observations.
- Test statistic shown to be expressed in terms of maximal invariant statistic - required for Constant False Alarm Rate (CFAR) property.
- Inverse of test statistic shown to be expressed as a product of statistically independent central beta random variables (rvs).
- Analytical expressions for probability of false alarm derived by expressing product of rvs as a mixture of independent central beta rvs.
- Similar approach used to derive expressions for probability of detection.



Referred Journal Publications



1. R. S. Raghavan, "Performance comparison of two subspace based GLRTs for rank-1 signal detection in unknown interference with multiple observations," **IEEE Transactions on Aerospace and Electronic Systems**, Vol. 59, No.1, pp. 418 - 433, Feb. 2023.
2. R. S. Raghavan, "Maximal Invariant Statistic for subspace signal detection in Unknown Interference with multiple observations," **IEEE Transactions on Aerospace and Electronic Systems**, Vol. 60, No.2, pp. 2422 – 2427, April 2024.