

# Viper-Informed Infrared Vision Sensing

Nathaniel Gabor

[qmolab.ucr.edu](http://qmolab.ucr.edu)



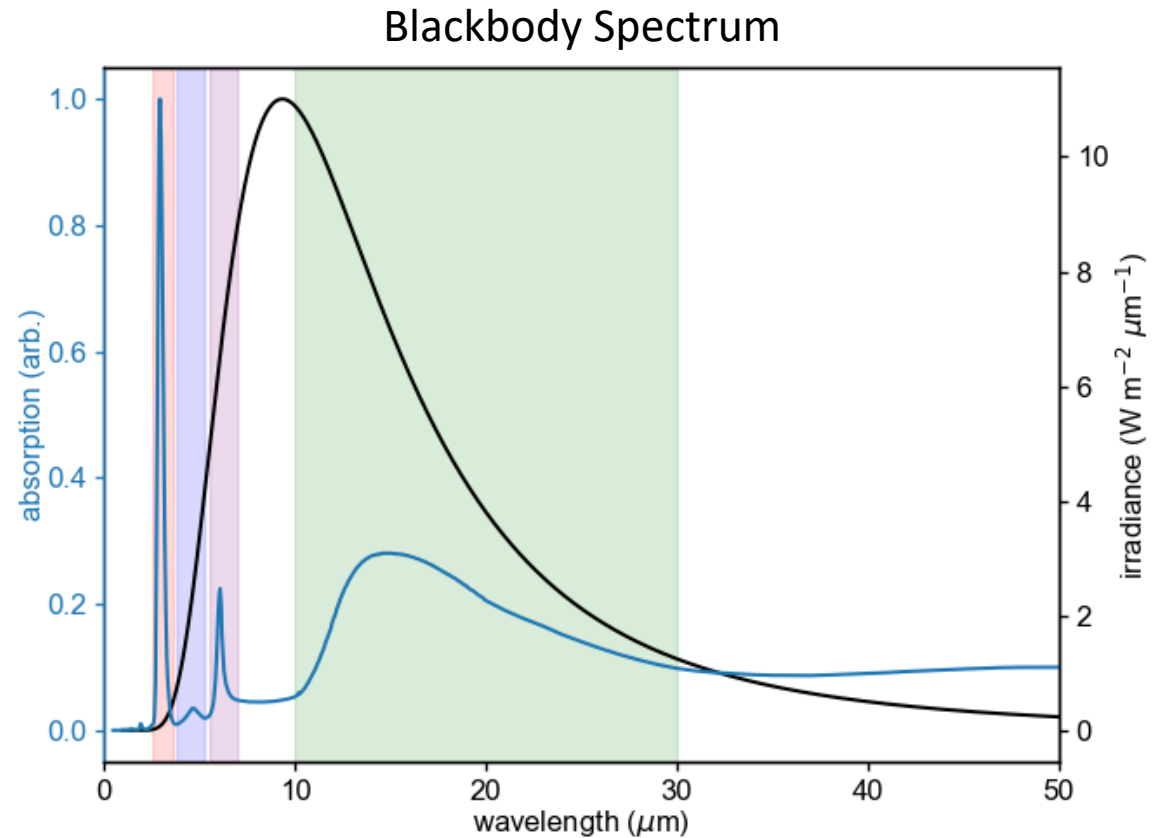
**Quantum Materials  
Optoelectronics Lab**

**UC RIVERSIDE** UNIVERSITY OF CALIFORNIA





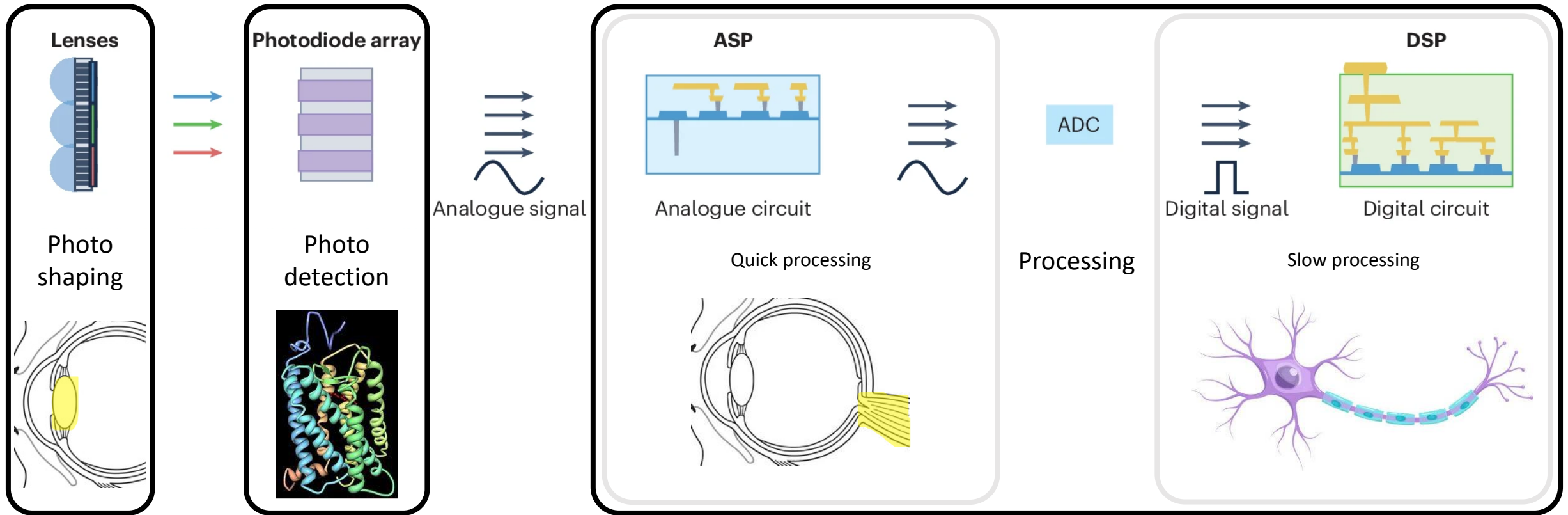
# (Nathan's) Water Bottle Conjecture



Can water be used for advanced infrared *vision sensing*?



# Layered Architecture in State-of-the-Art Vision Sensors



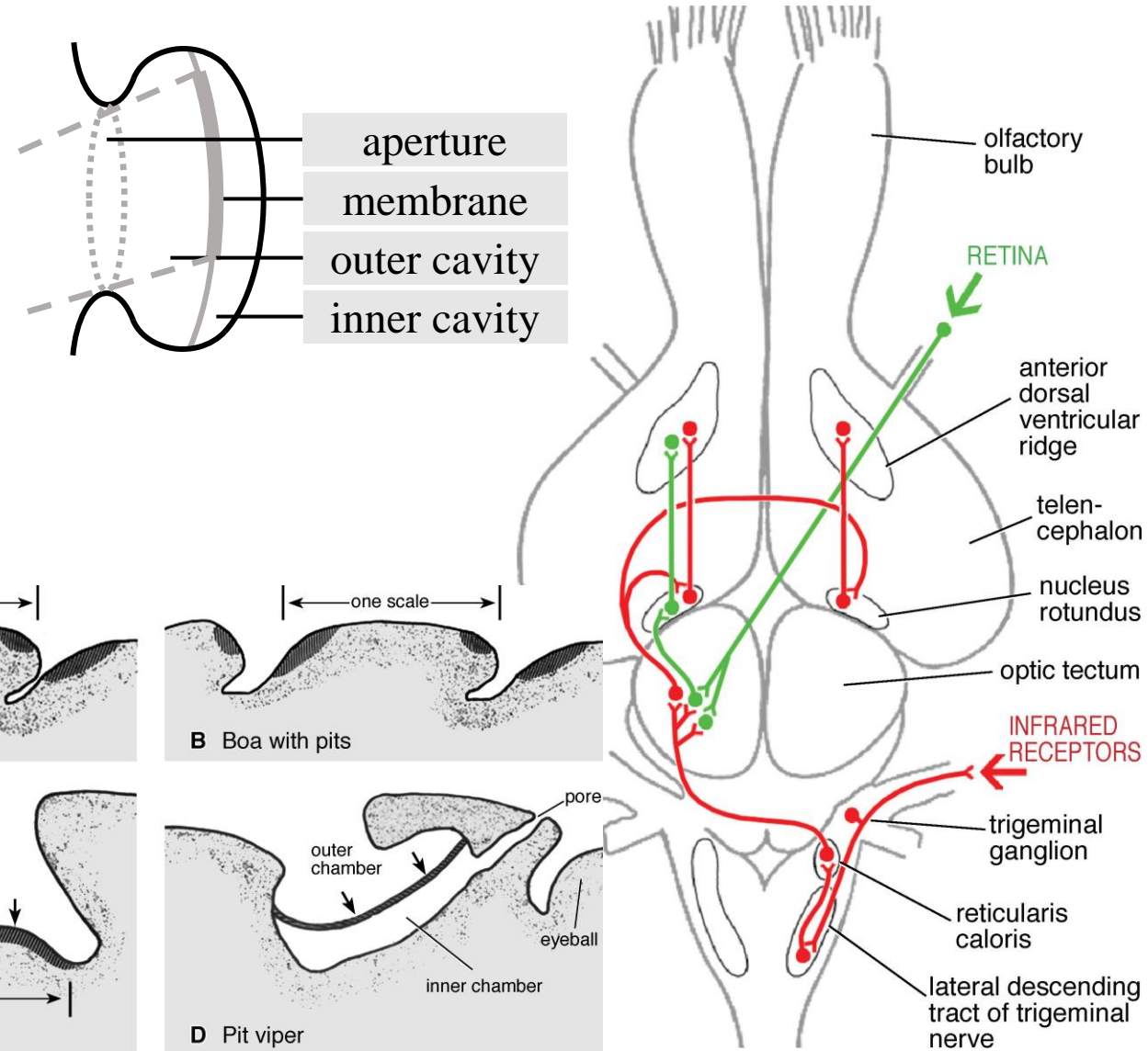
Biosystems exhibit remarkable (albeit not-fully-understood) solutions to the vision sensor challenge







# Infrared Vision Sensing in the Pit Viper

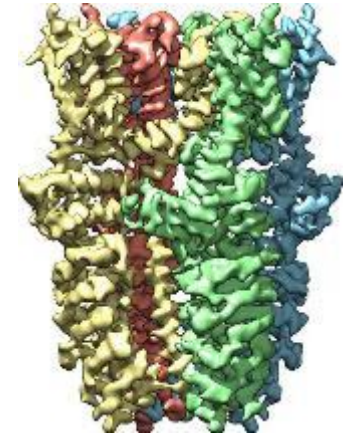
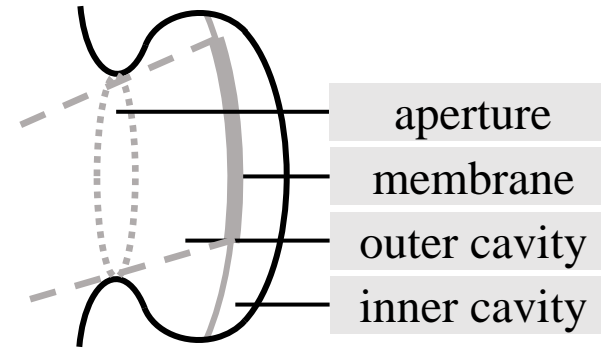


IR vision *enhances* normal vision  
multi-step interpretation  
very fast  $\sim 50 - 100$  ms

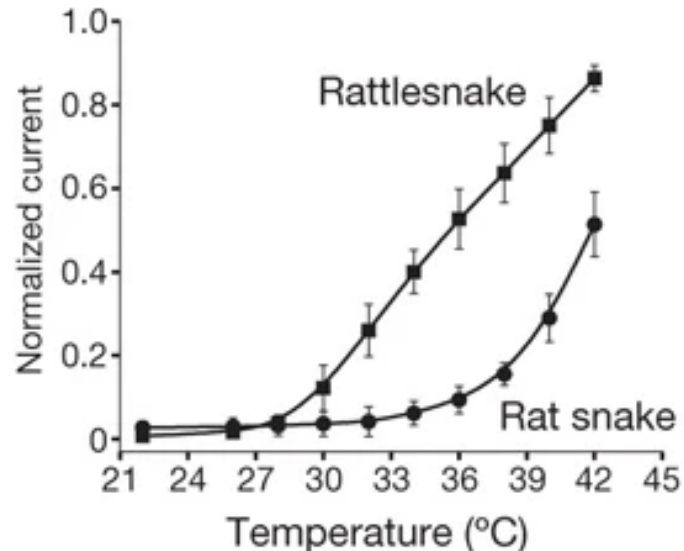




# Infrared Vision Sensing in the Pit Viper



detection mediated by  
TRPA1 ion channels



- sensitive to temperature differences of  $< 0.002^{\circ}\text{C}$
- ion channels must be  $> 27^{\circ}\text{C}$

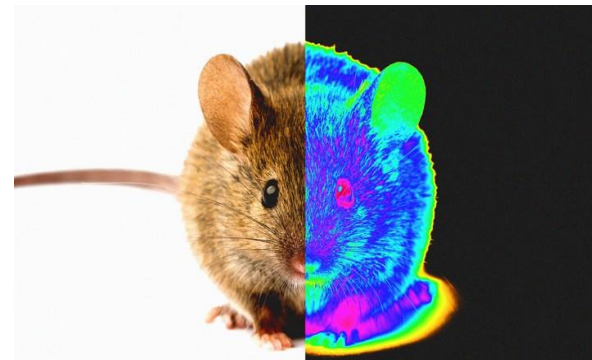
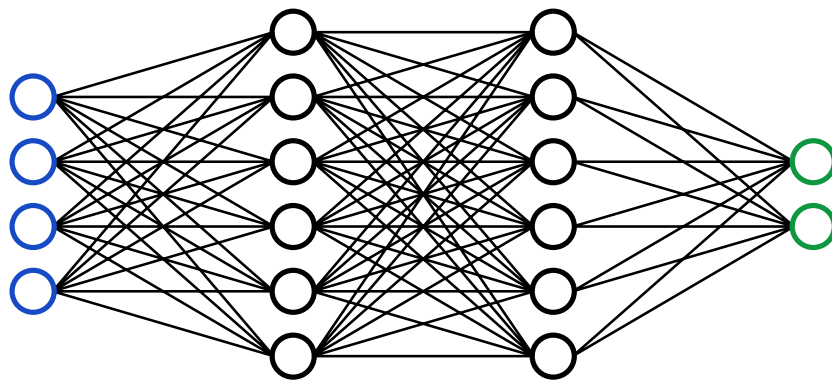
Hardware optimization problem:  
light detection  
vs.  
image resolution



# Proposal: Biologically Informed Infrared Vision

In humans, it takes  $\sim 250$  ms to respond to visual stimulus,  
 $\sim 170$  ms to respond to audio stimulus,  
 $\sim 150$  ms to respond to a touch stimulus.

A pit viper can see, decide, and strike at a distance of one foot in 70 ms.

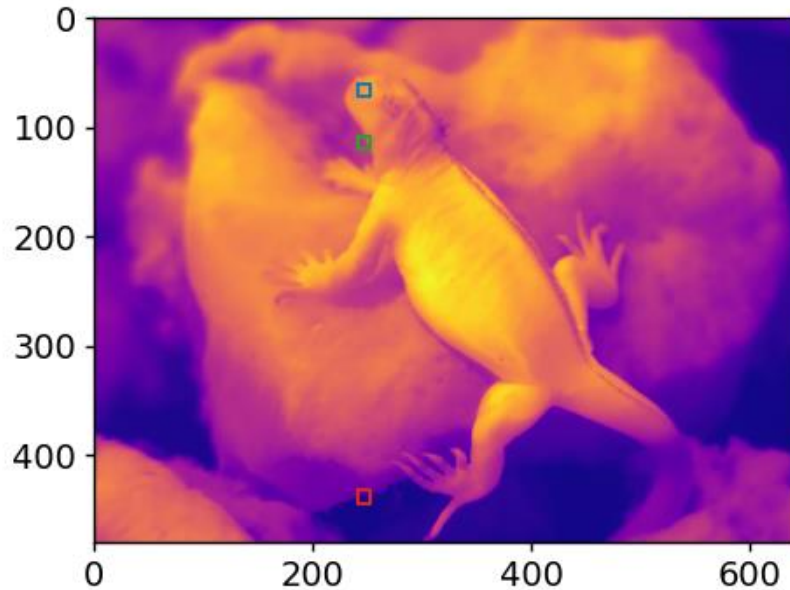


Given such seemingly low-resolution imaging hardware,  
and such little computational power consumption,  
how does the viper vision system work so efficiently?



# Water for Infrared Vision Sensing

Temperature Image

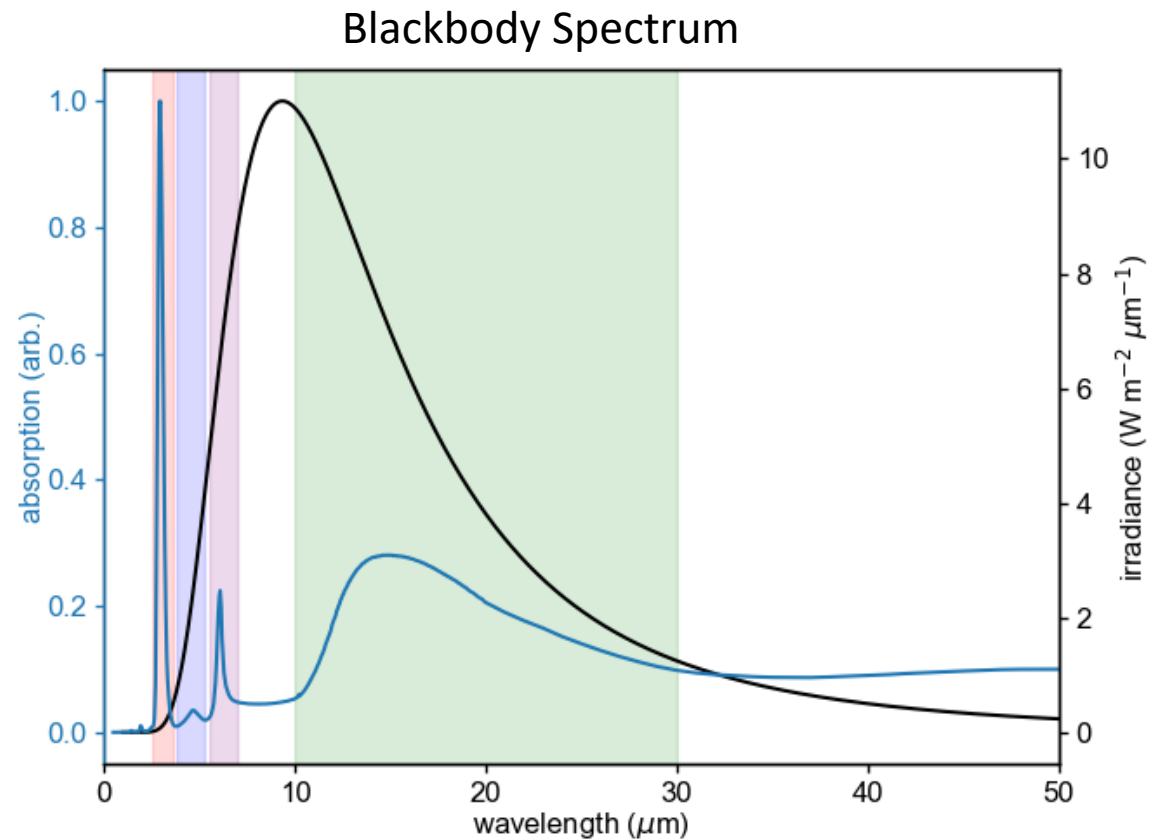
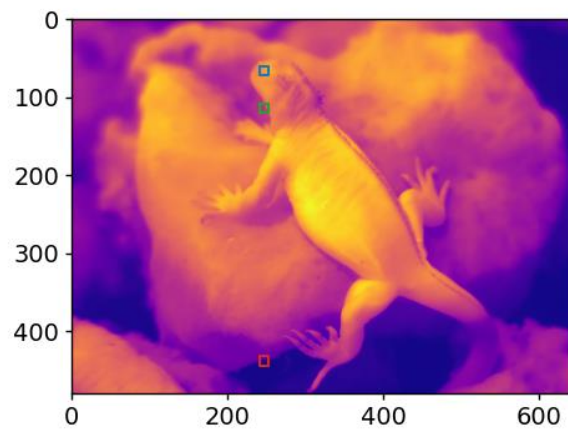


How would a biological sensor best absorb infrared light?





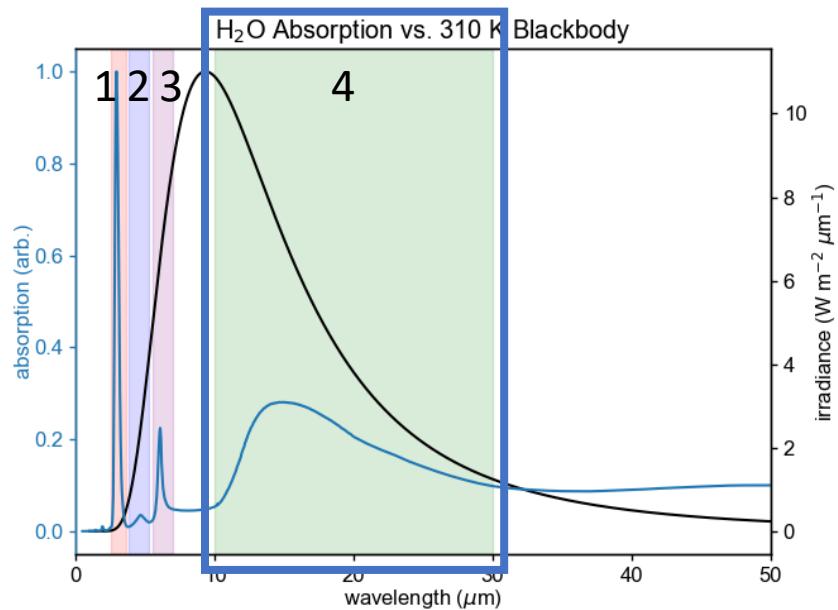
# Water for Infrared Vision Sensing



Water is an ideal IR absorber, except at the peak of the blackbody spectrum



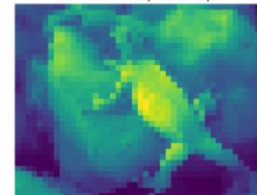
# Water for Infrared Vision Sensing



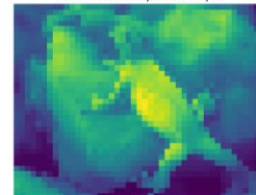
Temp. Image



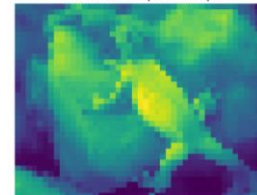
Channel 1: 2.5  $\mu\text{m}$  to 3.6  $\mu\text{m}$



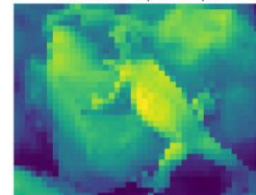
Channel 2: 3.8  $\mu\text{m}$  to 5.3  $\mu\text{m}$



Channel 3: 5.5  $\mu\text{m}$  to 7.0  $\mu\text{m}$



Channel 4: 10  $\mu\text{m}$  to 30  $\mu\text{m}$



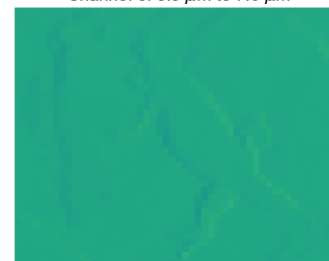
Channel 1: 2.5  $\mu\text{m}$  to 3.6  $\mu\text{m}$



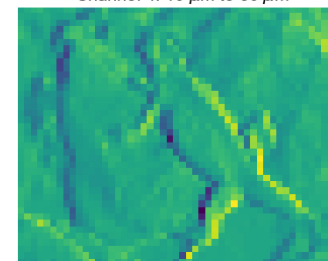
Channel 2: 3.8  $\mu\text{m}$  to 5.3  $\mu\text{m}$



Channel 3: 5.5  $\mu\text{m}$  to 7.0  $\mu\text{m}$

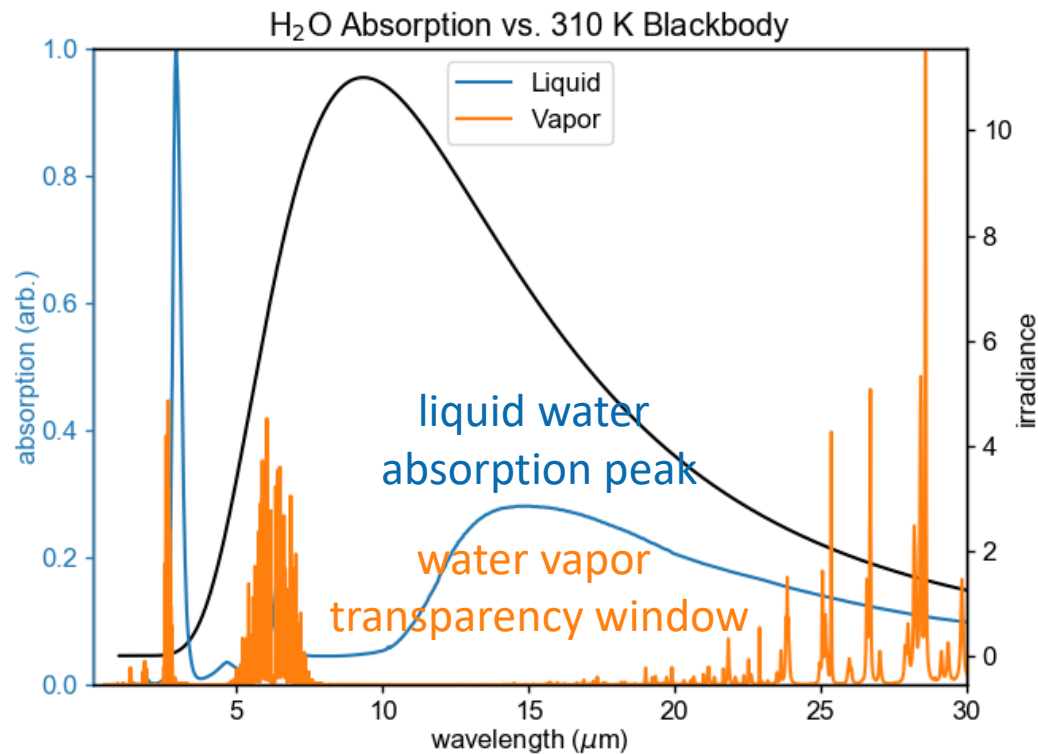


Channel 4: 10  $\mu\text{m}$  to 30  $\mu\text{m}$





# Water for Infrared Vision Sensing



Is water the solution to the biological infrared vision problem?

Hypothesis: the viper IR vision system is utilizing the molecular rotation of water!

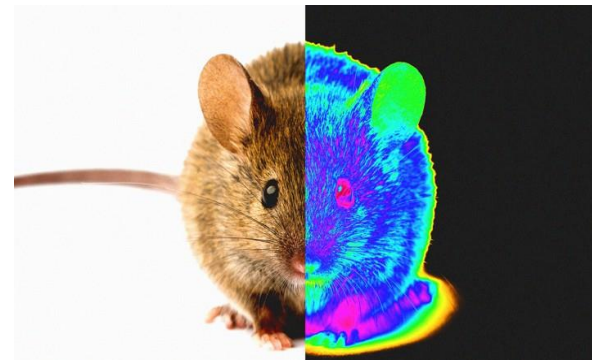
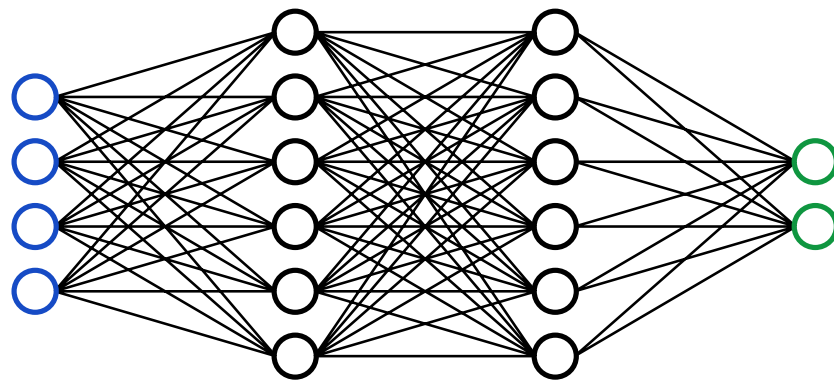




# Proposal: Biologically Informed Infrared Vision

In humans, it takes 250 ms to respond to visual stimulus,  
170 ms to respond to audio stimulus,  
150 ms to respond to a touch stimulus.

A pit viper can see, decide, and strike at a distance of one foot in 70 ms.

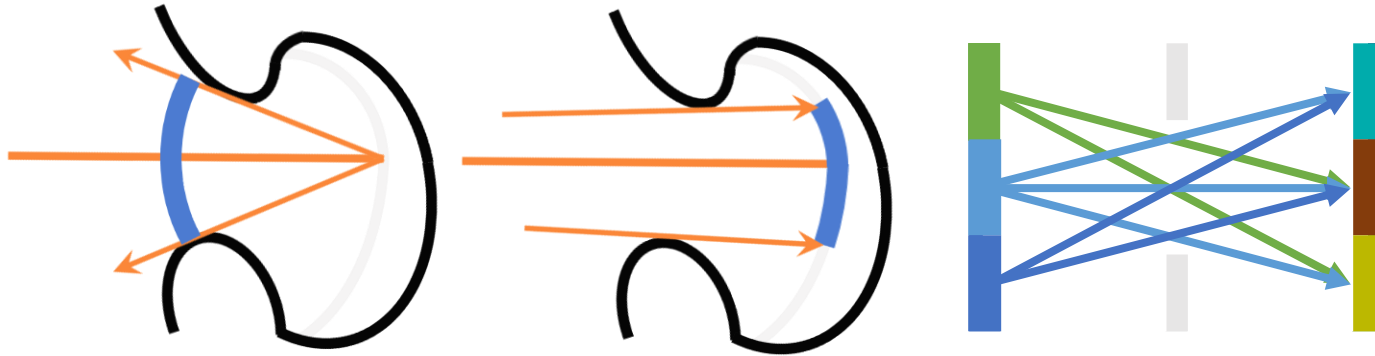


Given such seemingly low-resolution imaging hardware,  
and such little computational power consumption,  
how does the viper vision system work so efficiently?



# Lens-less Infrared Imaging

Optimization problem:  
light detection vs image resolution

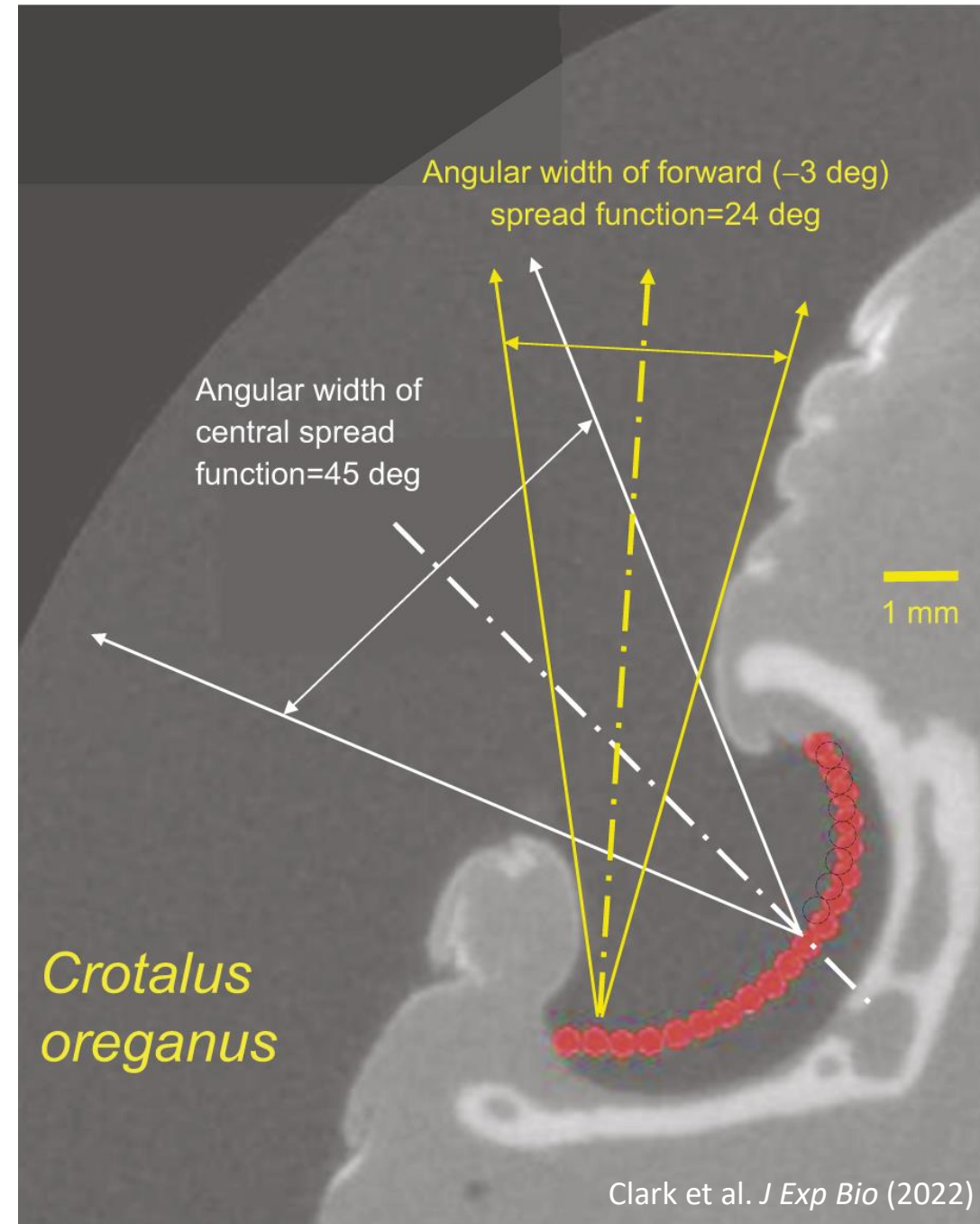


multiple emitters  $\rightarrow$  single detector  
single emitter  $\rightarrow$  multiple detectors

- Transformation matrix  $T_{\alpha}^{\beta}$
- Reconstruction:  

$$[\text{image space}]_{\beta} = R_{\alpha}^{\beta} [\text{detector space}]_{\beta}$$

Sichert et al. *PRL* (2006)

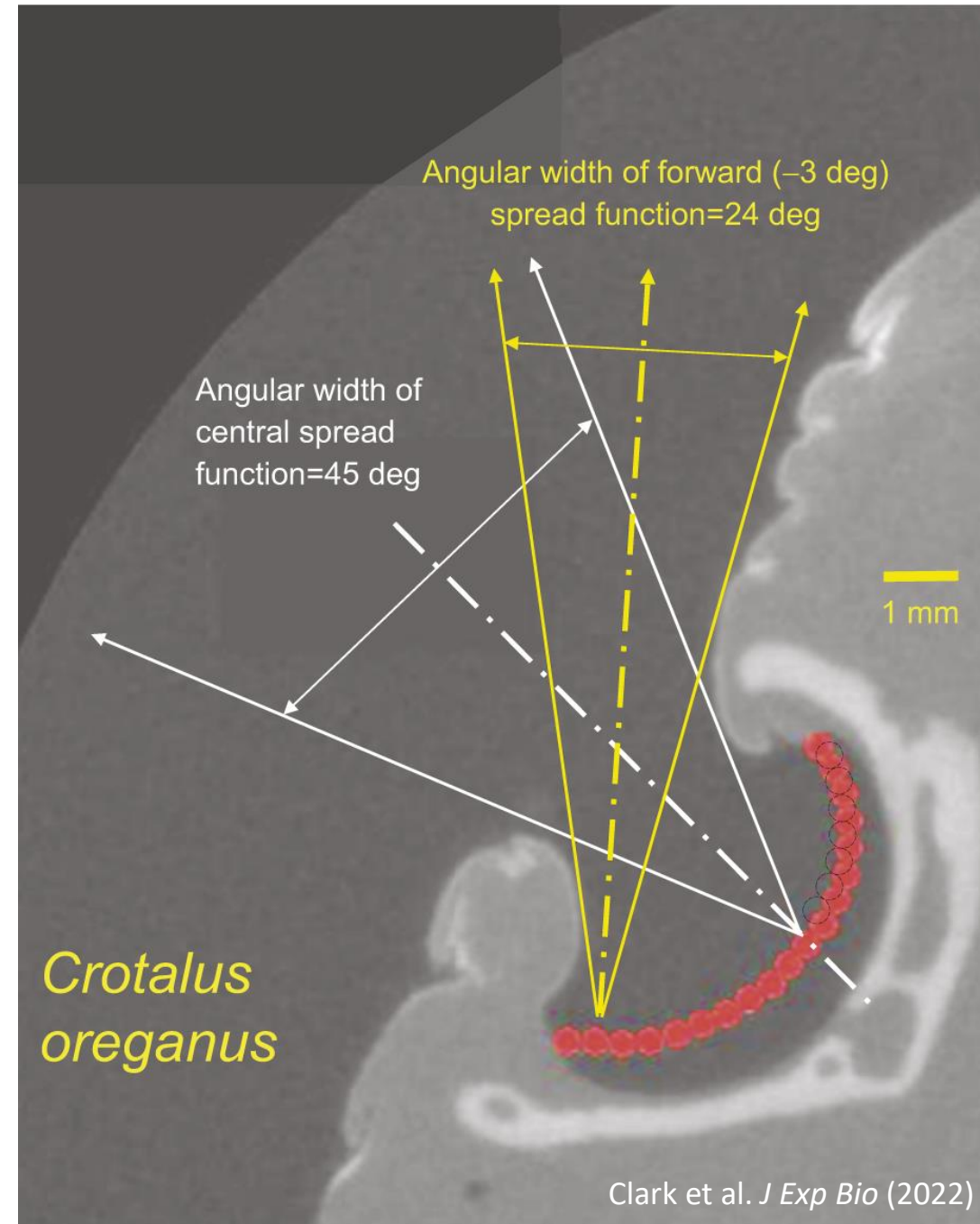
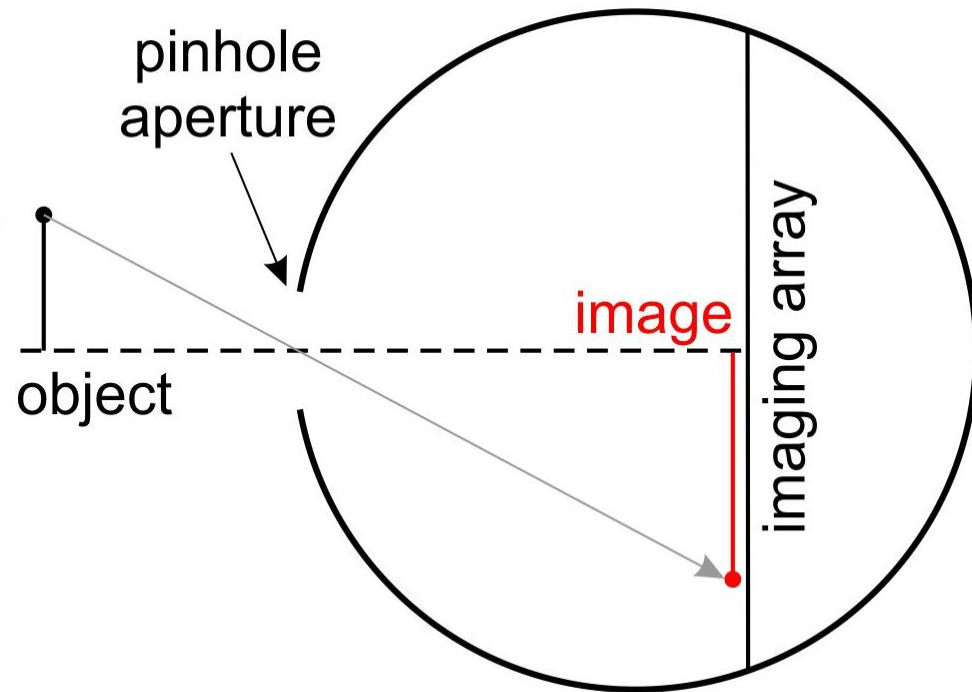


Clark et al. *J Exp Bio* (2022)



# Lens-less Infrared Imaging

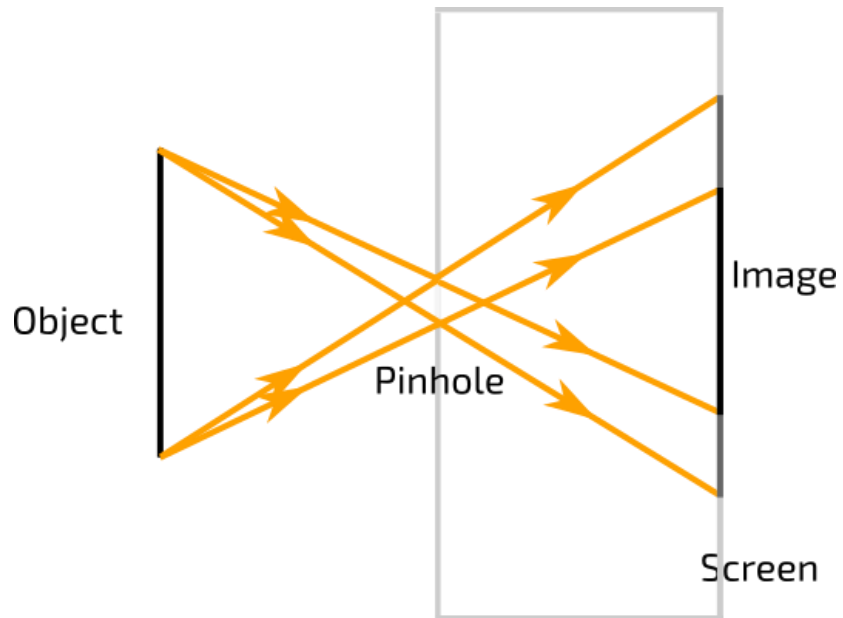
Optimization problem:  
light detection vs image resolution







# Lens-less Infrared Imaging: Pinhole Camera



$$T_{\alpha}^{\beta} = r_{\alpha\beta}^{-2} \cos \varphi_{\alpha\beta}$$

$$R^{\mu}_{\gamma} [T_{\nu}^{\delta} T^{\gamma}_{\delta} (1 + \tau^2) + \sigma^2 \delta^{\gamma}_{\nu}] = T_{\nu}^{\mu}$$

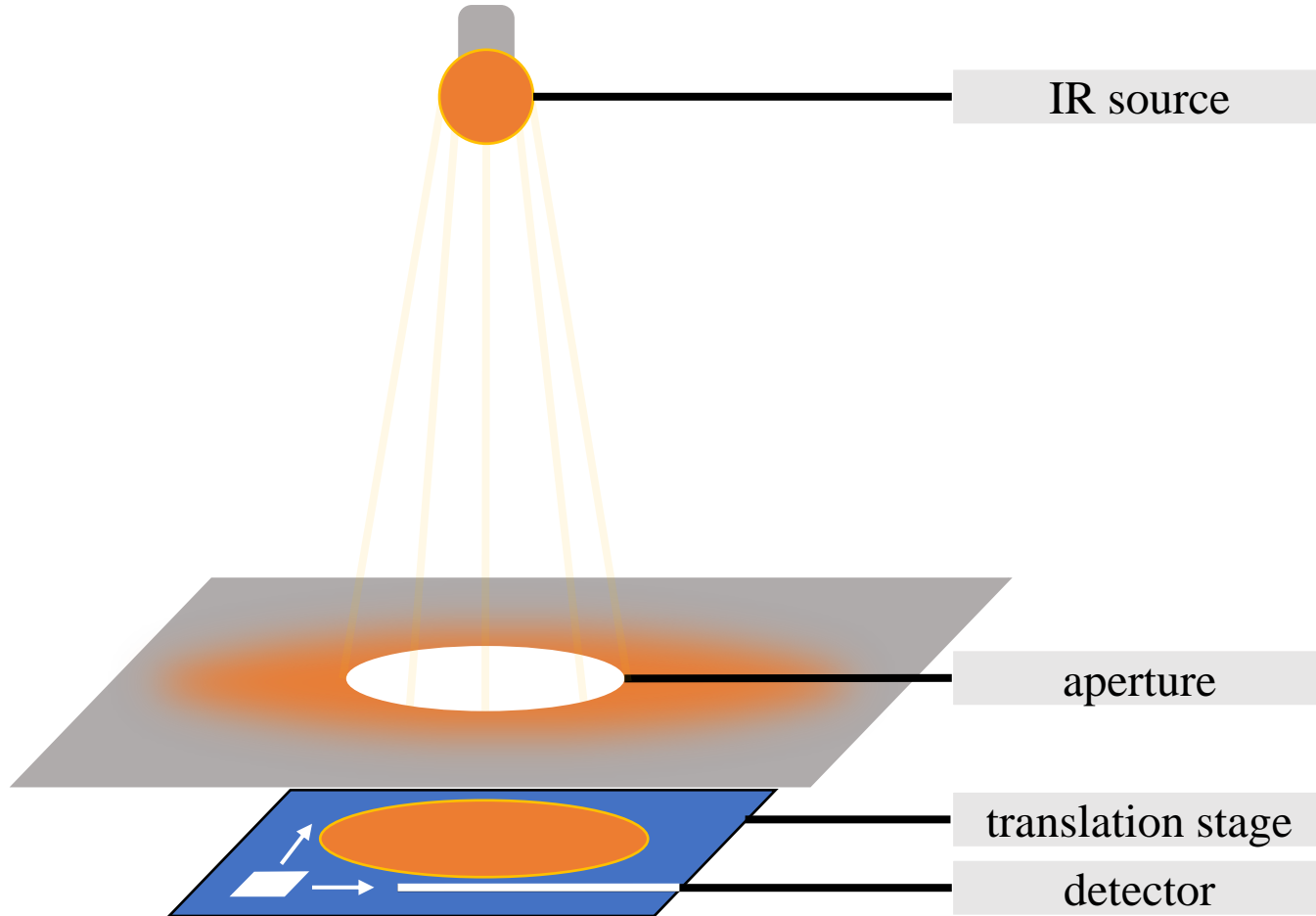
$$I_{\alpha} = R_{\alpha}^{\beta} S_{\beta}$$

At each point in space, we first calculate the heat distribution on the membrane for a given heat distribution in space.

In only one computational step, we then use stochastic reconstruction to estimate the input image from the measured response on the membrane.



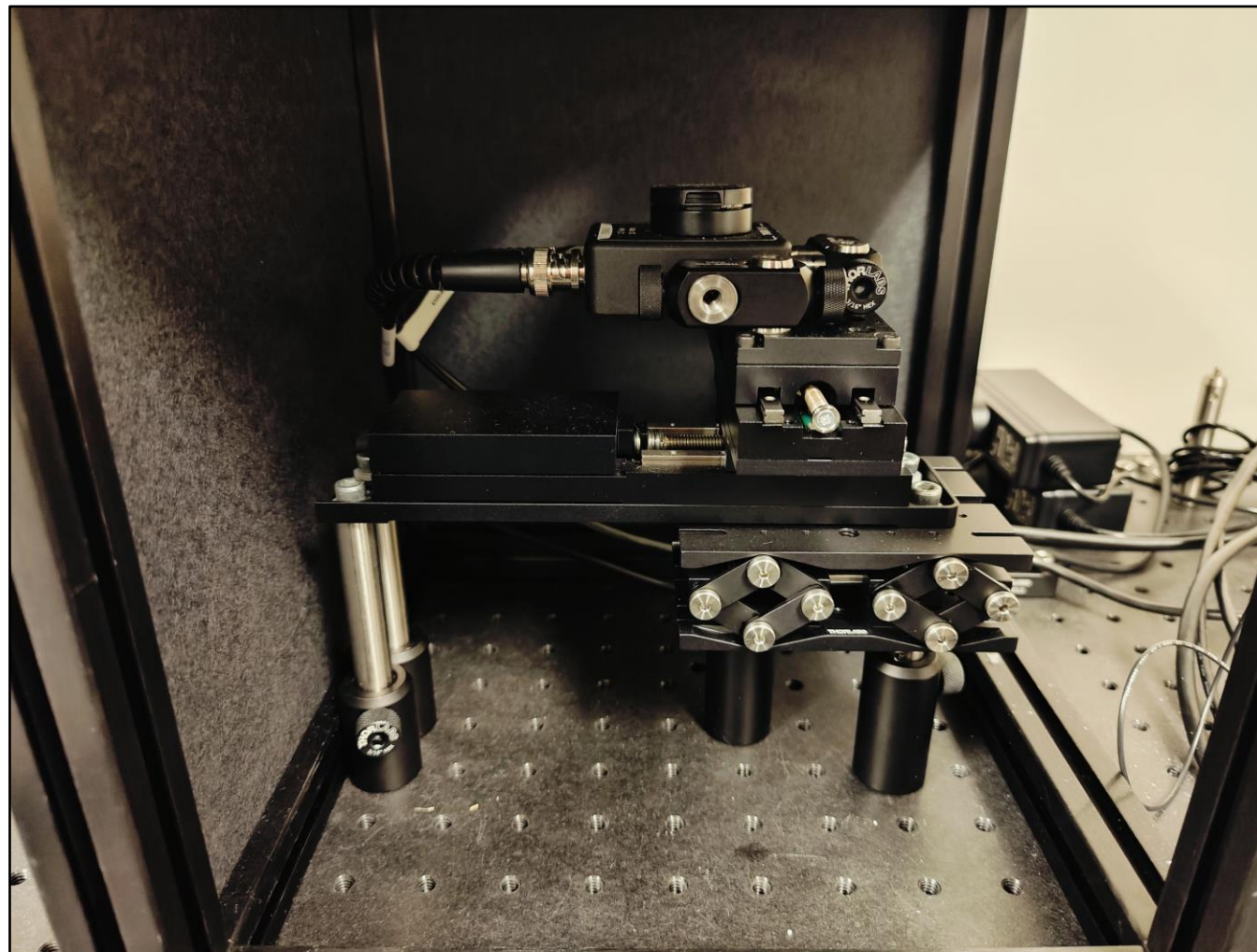
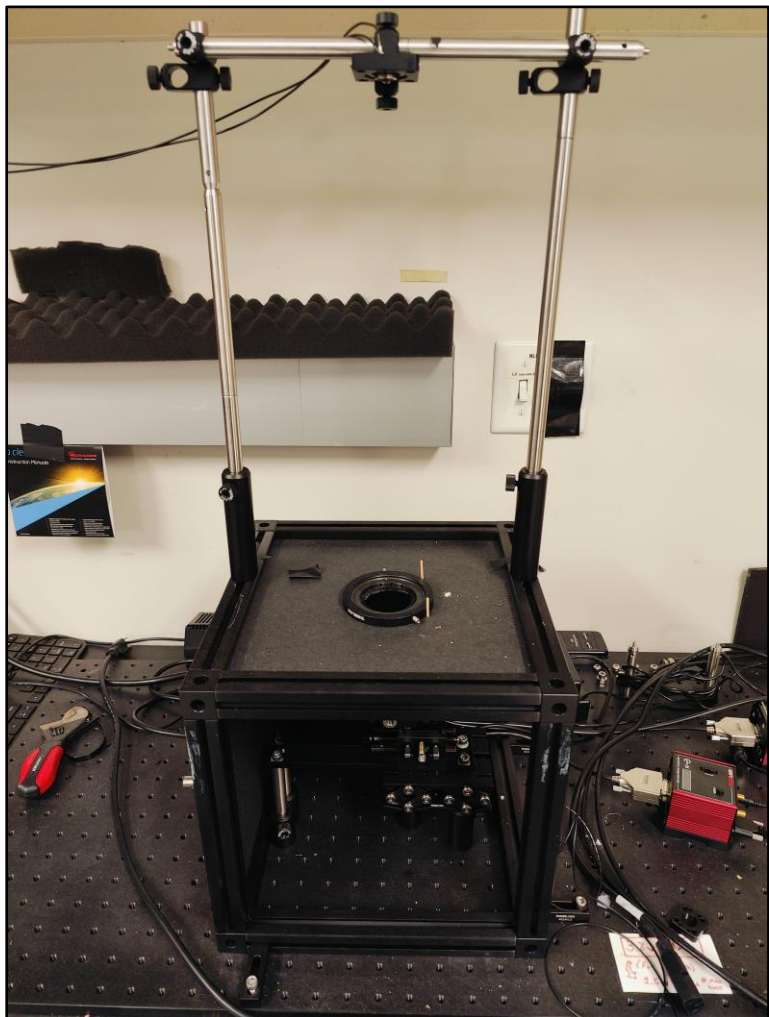
# Lens-less Infrared Imaging



Bakken et al. *J Exp Biol* (2012)



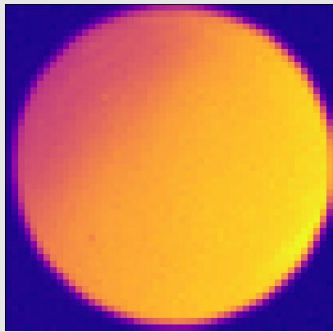
# Lens-less Infrared Imaging: Pinhole Camera



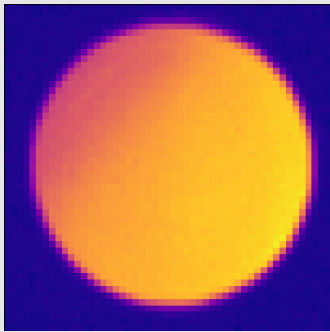




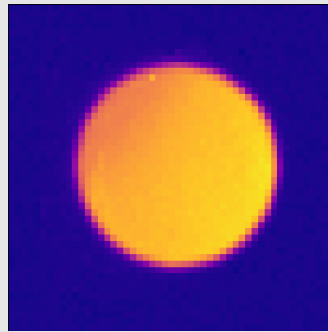
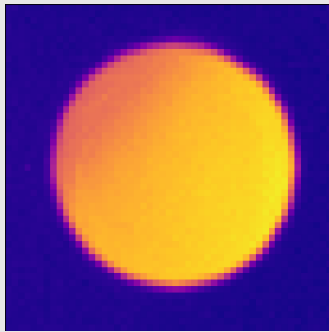
# Lens-less Infrared Imaging: Pinhole Camera



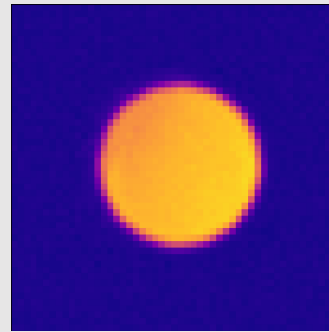
40 mm



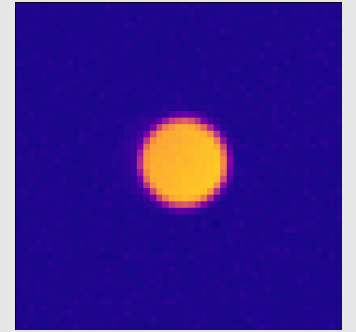
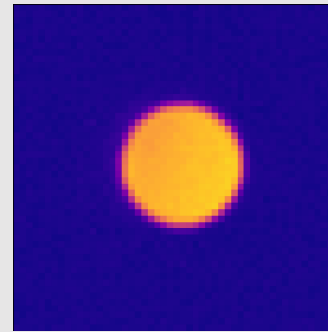
aperture diameter



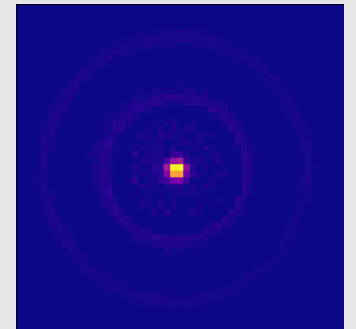
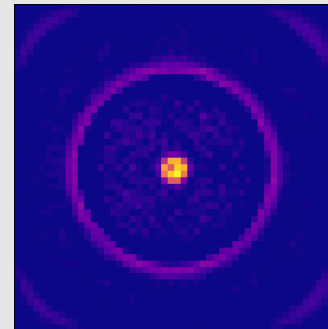
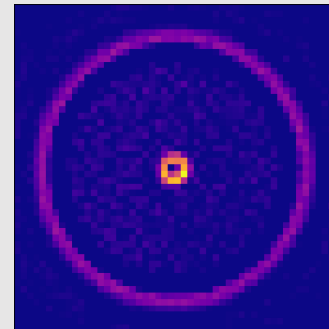
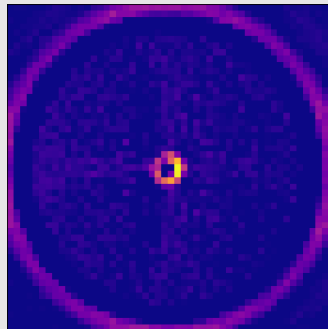
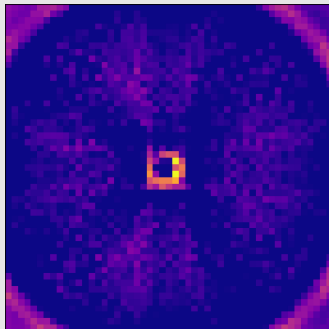
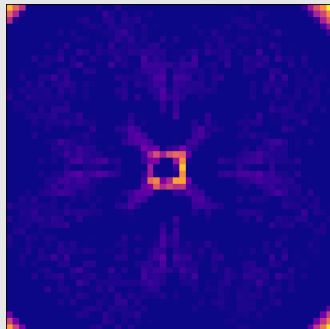
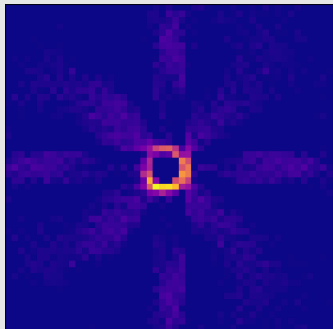
25 mm



decreasing



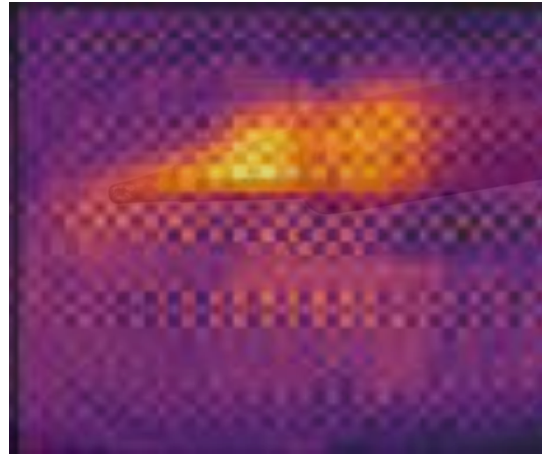
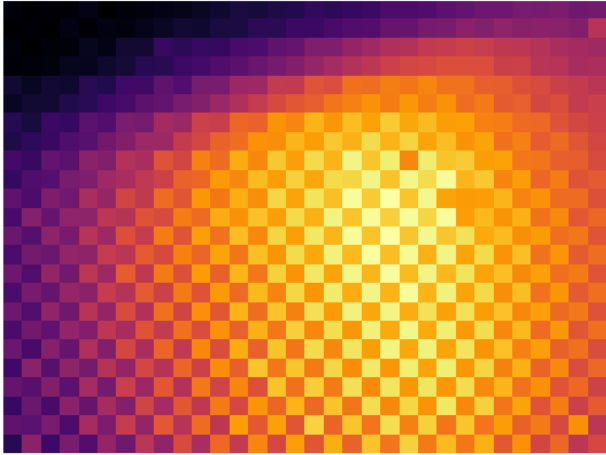
10 mm



A closed aperture (10 mm) reproduces the point source and rejects stray light,  
as expected from a pinhole camera

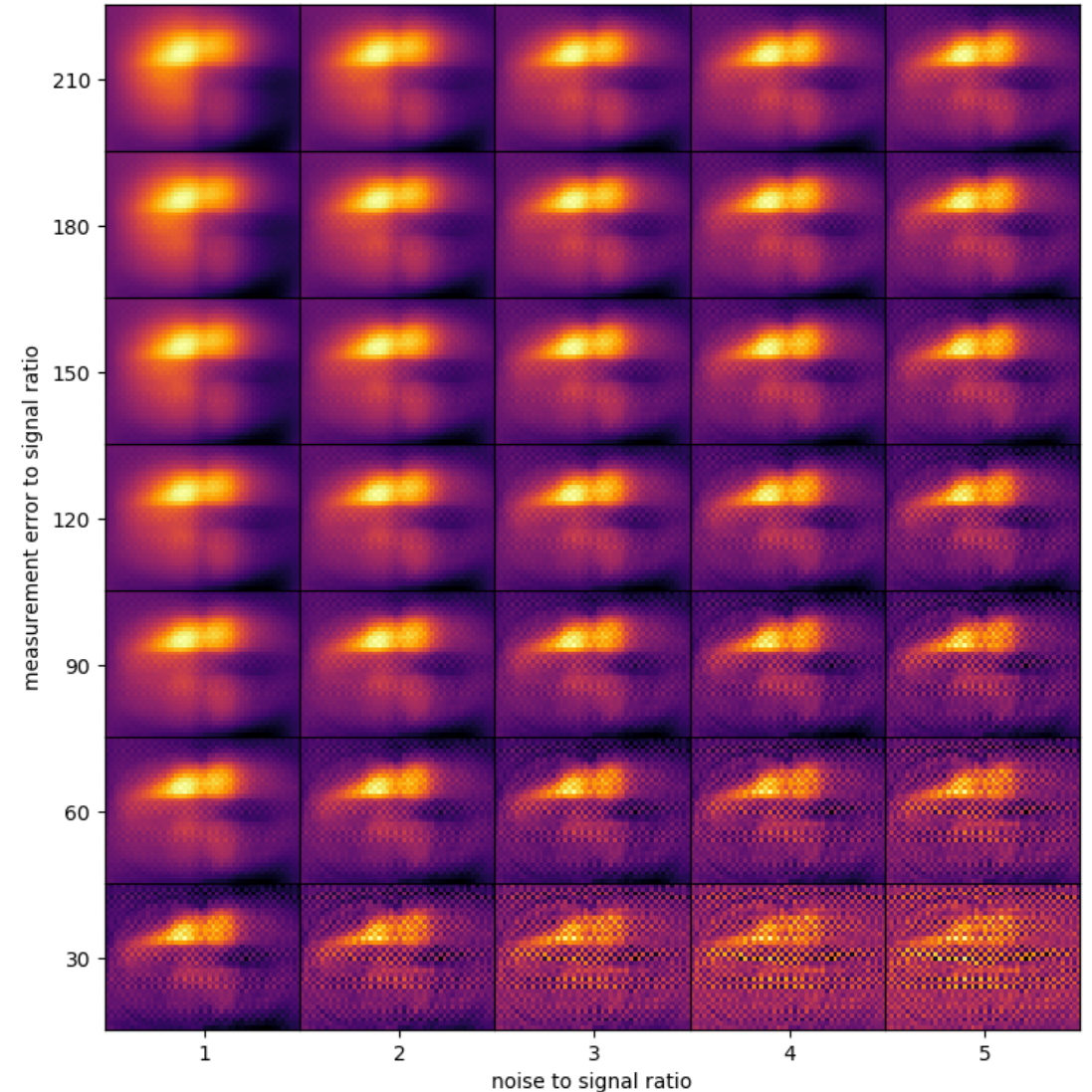


# Lens-less Infrared Imaging: Commercial Sensor



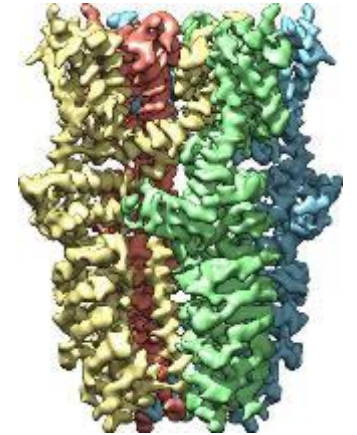
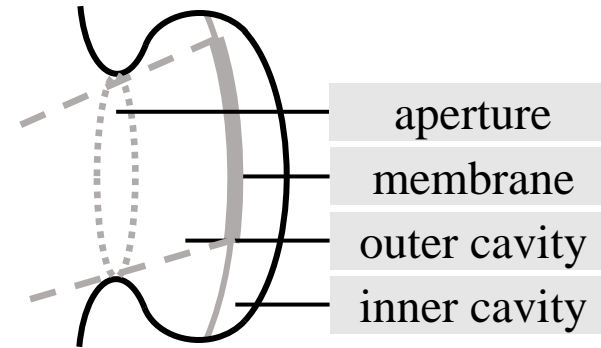
With a **lens-less** commercial IR photocell array,  
our protocol outperforms the imaging quality  
of the packaged device

With advanced sensors, can we do even better?

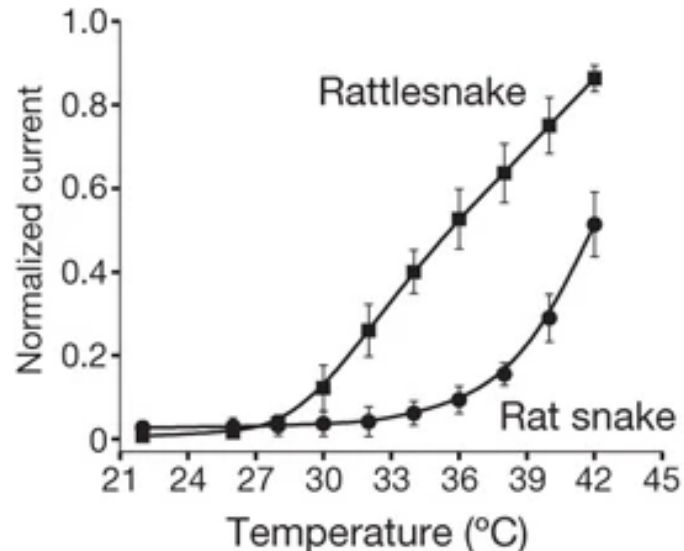




# Infrared Vision Sensing in the Pit Viper



detection mediated by  
TRPA1 ion channels



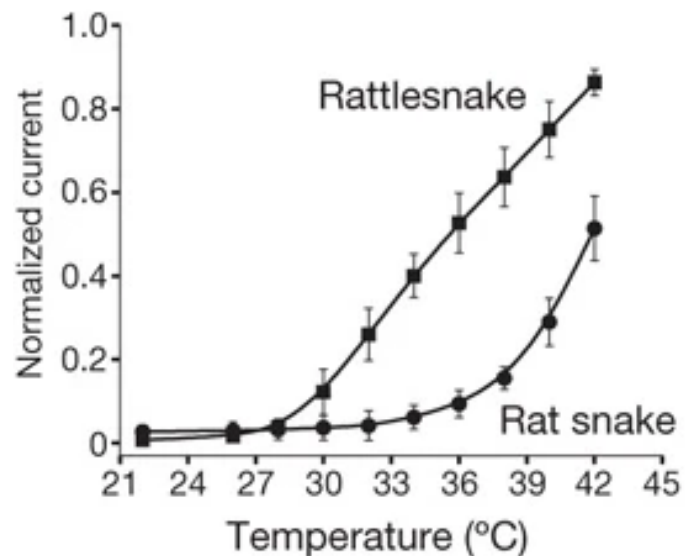
- sensitive to temperature differences of  $< 0.002^{\circ}\text{C}$
- ion channels must be  $> 27^{\circ}\text{C}$

Hardware optimization problem:  
light detection  
vs.  
image resolution





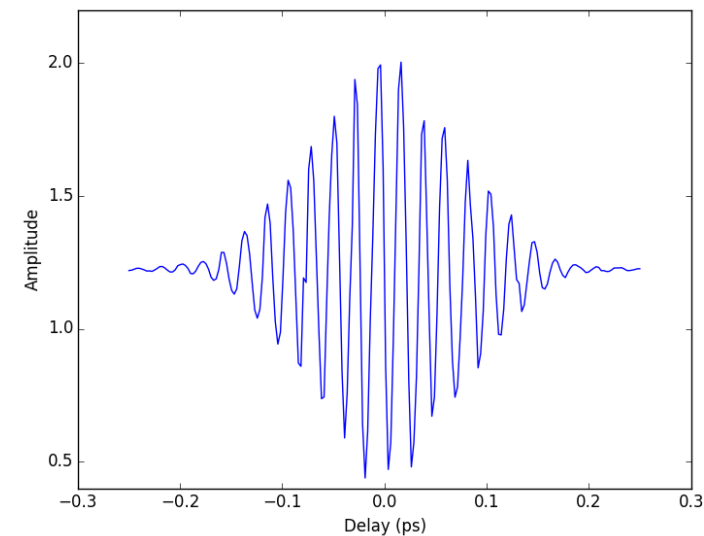
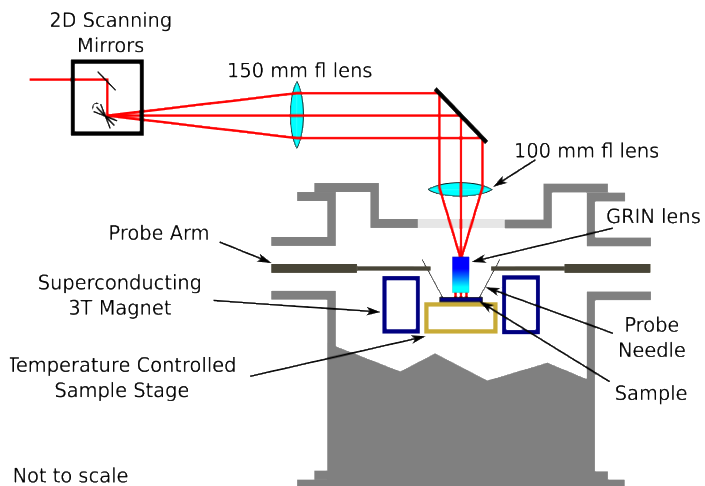
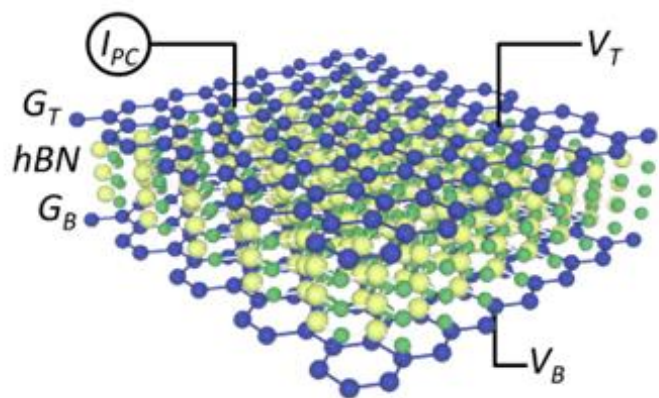
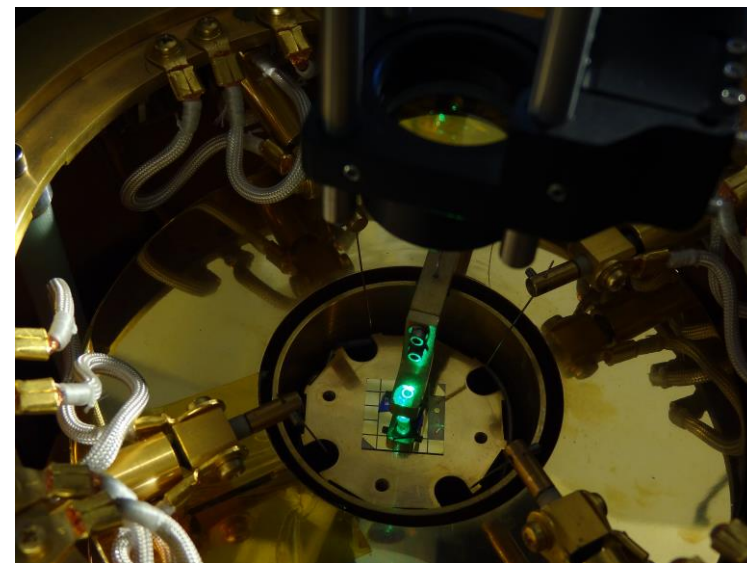
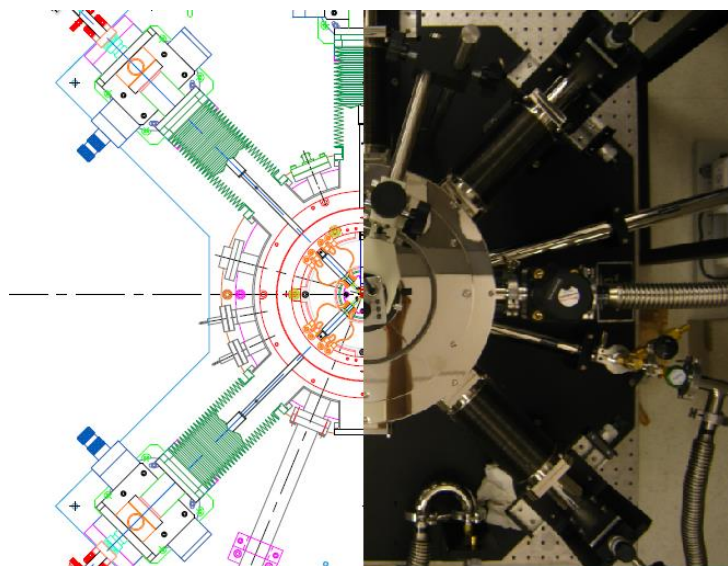
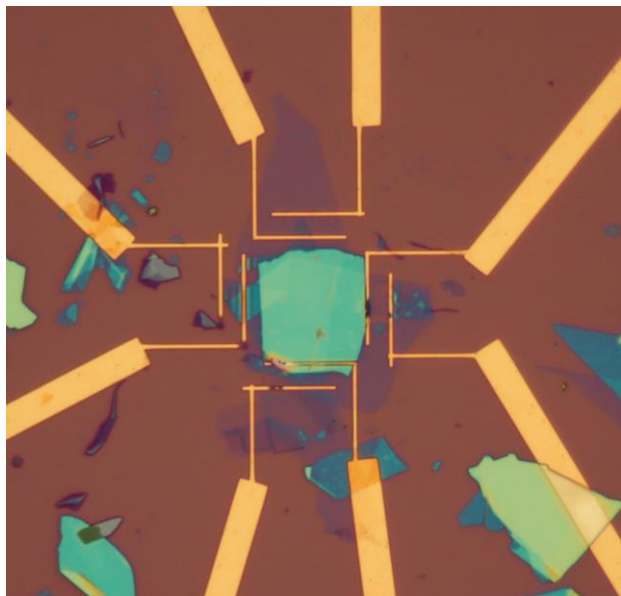
# Infrared Vision Sensing in the Pit Viper



The pit viper utilizes a fast, nanoscale temperature sensor with sharp super-linear threshold behavior

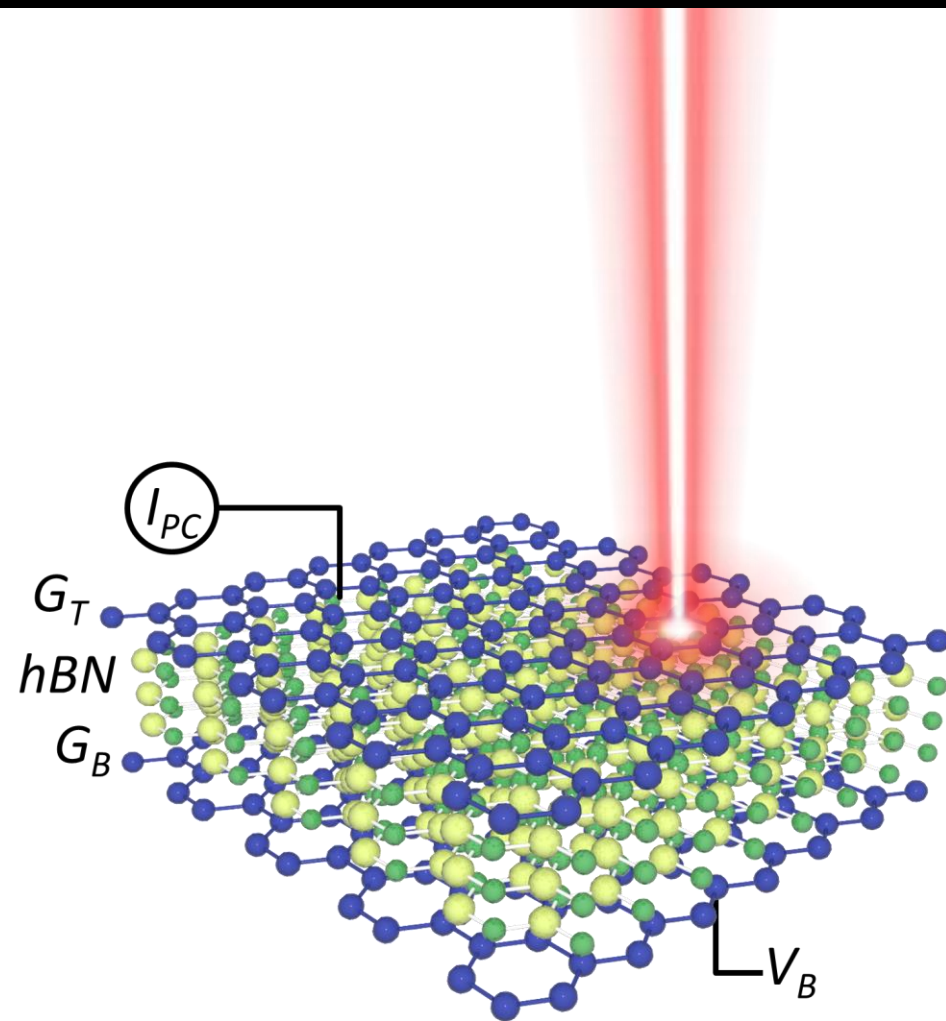
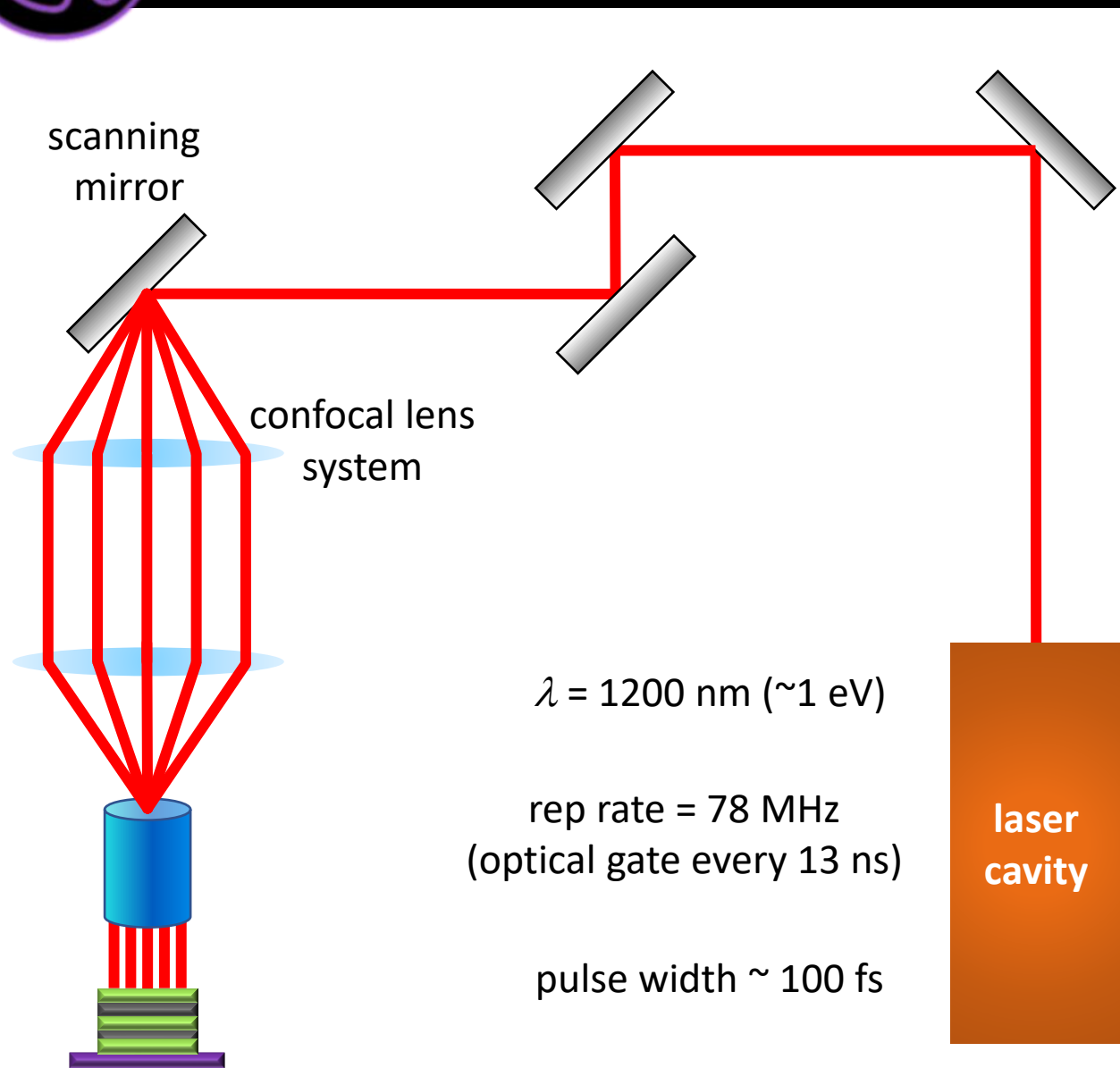


# Infrared Nanoscale Optoelectronics in the Gabor Labs



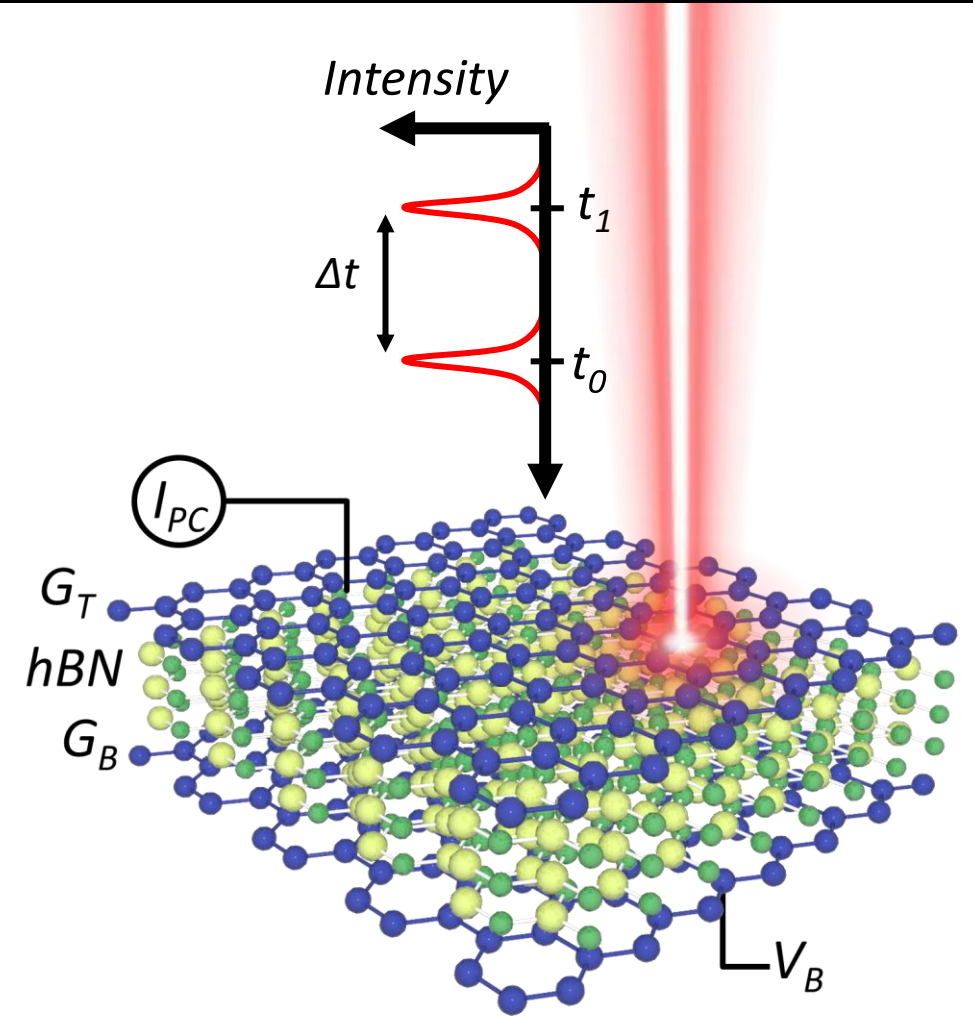
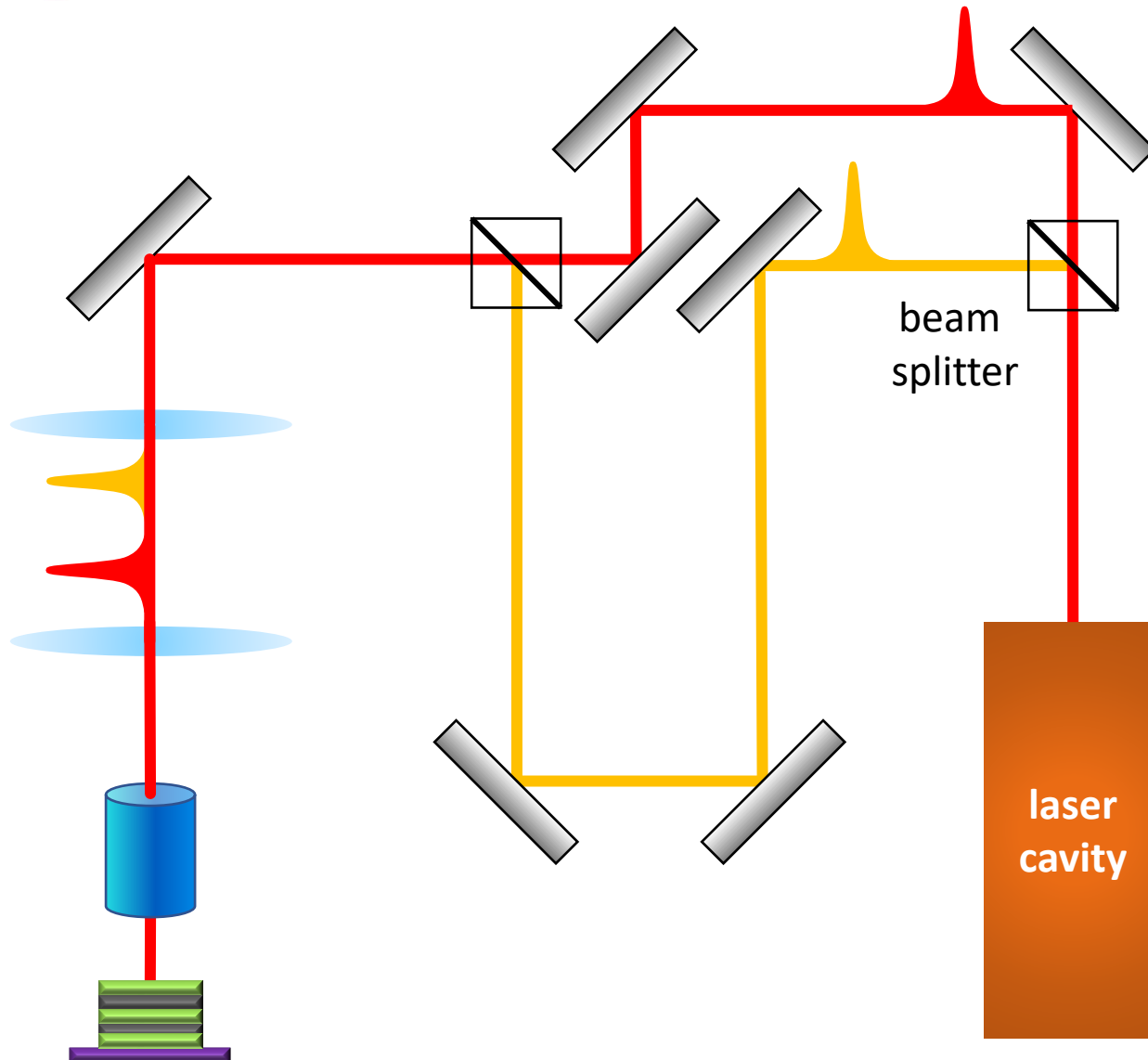


# Infrared Nanoscale Optoelectronics Based on Graphene





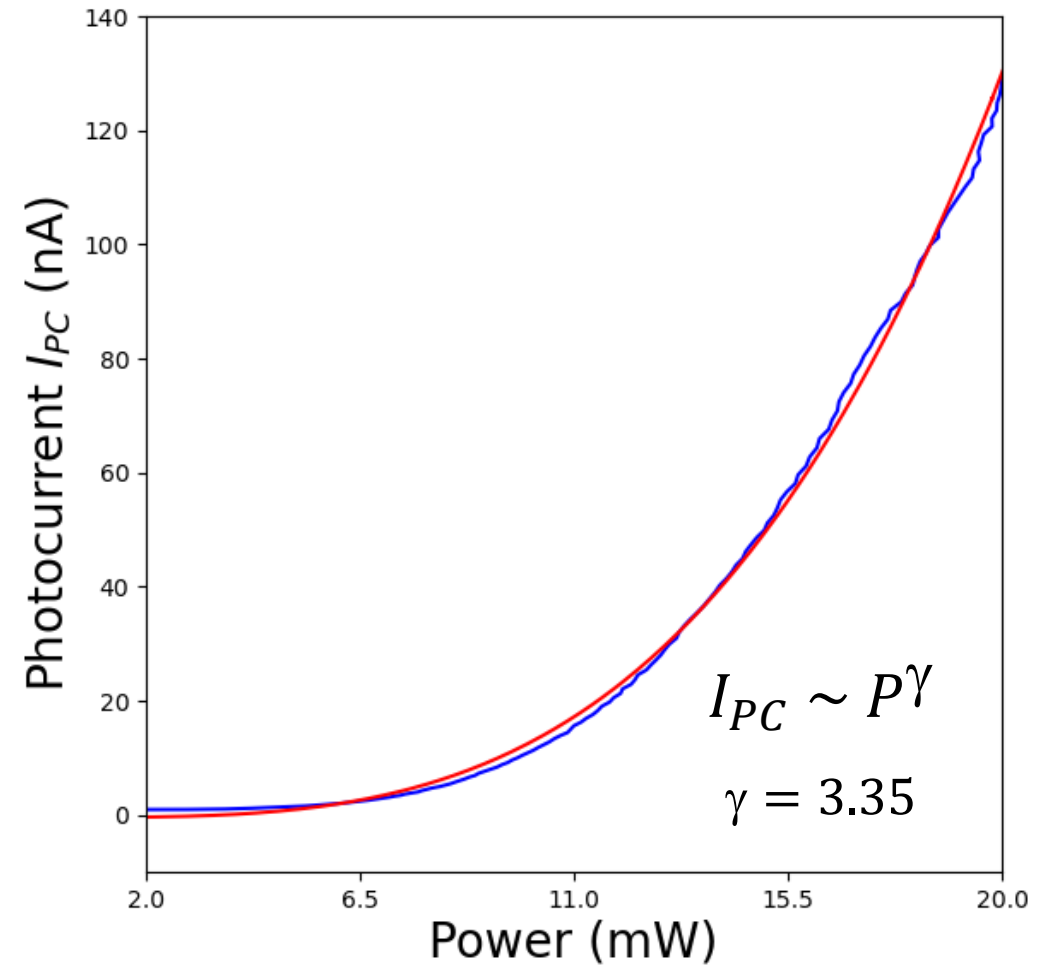
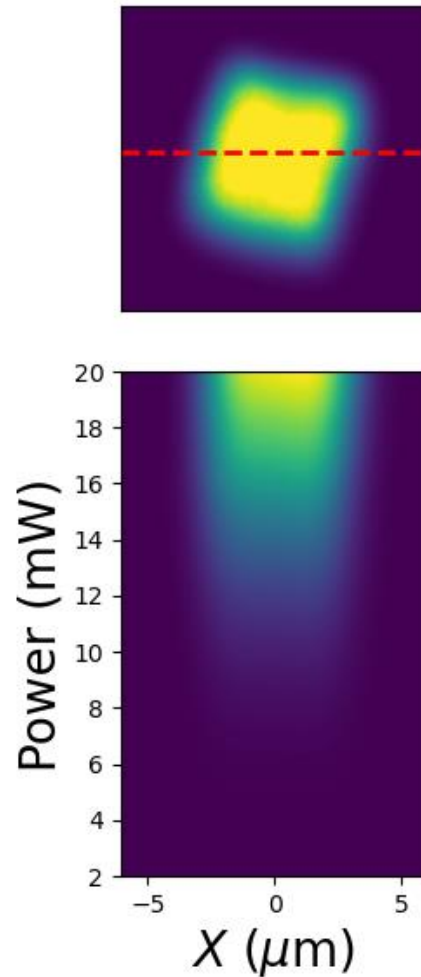
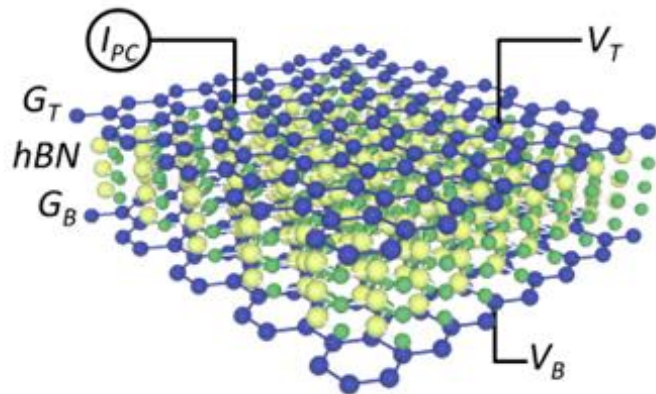
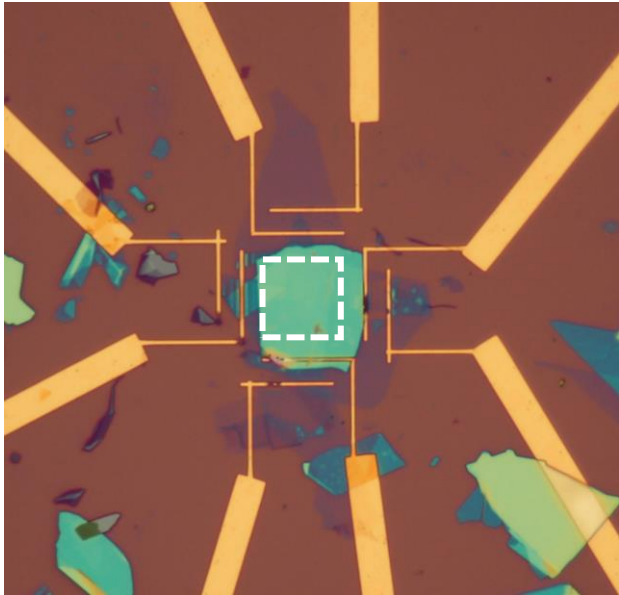
# Infrared Nanoscale Optoelectronics Based on Graphene







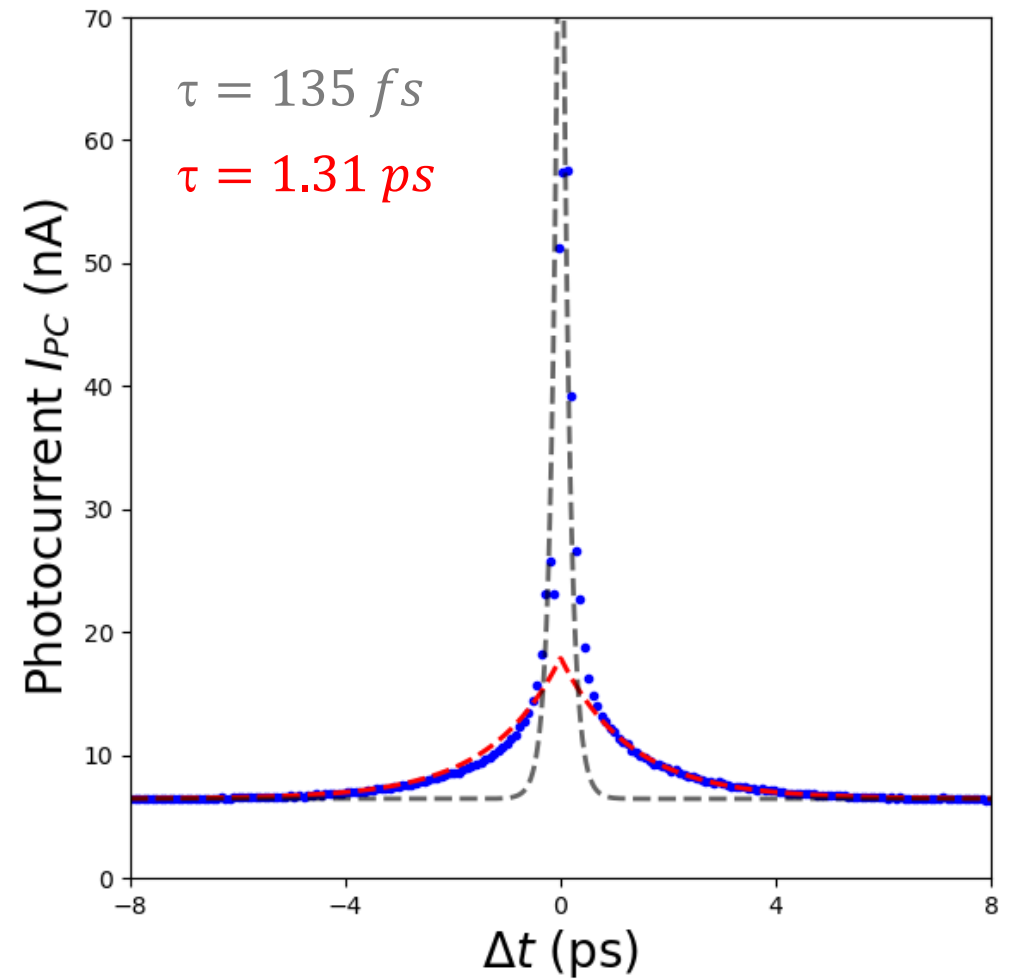
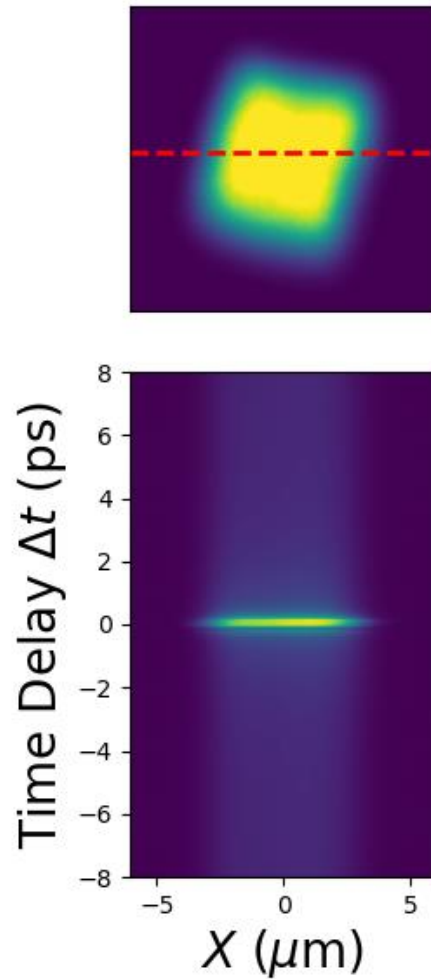
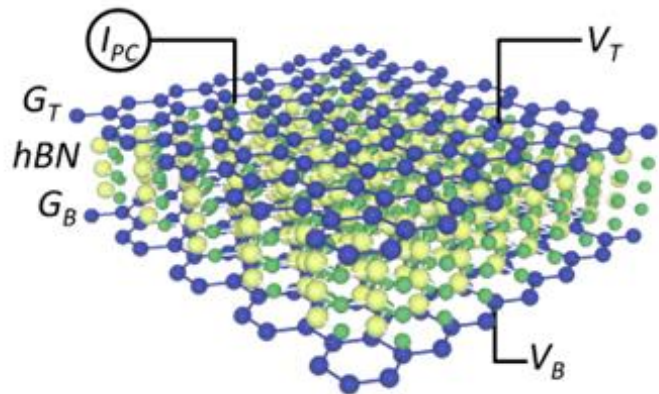
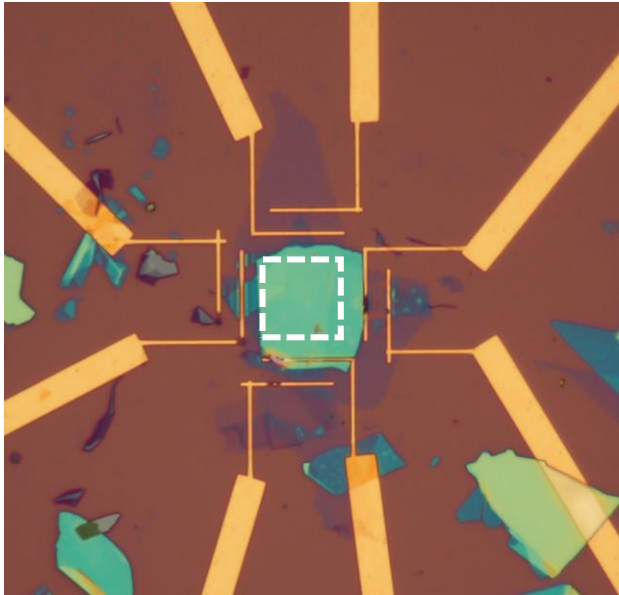
# Infrared Nanoscale Optoelectronics Based on Graphene



sharp super-linear threshold behavior



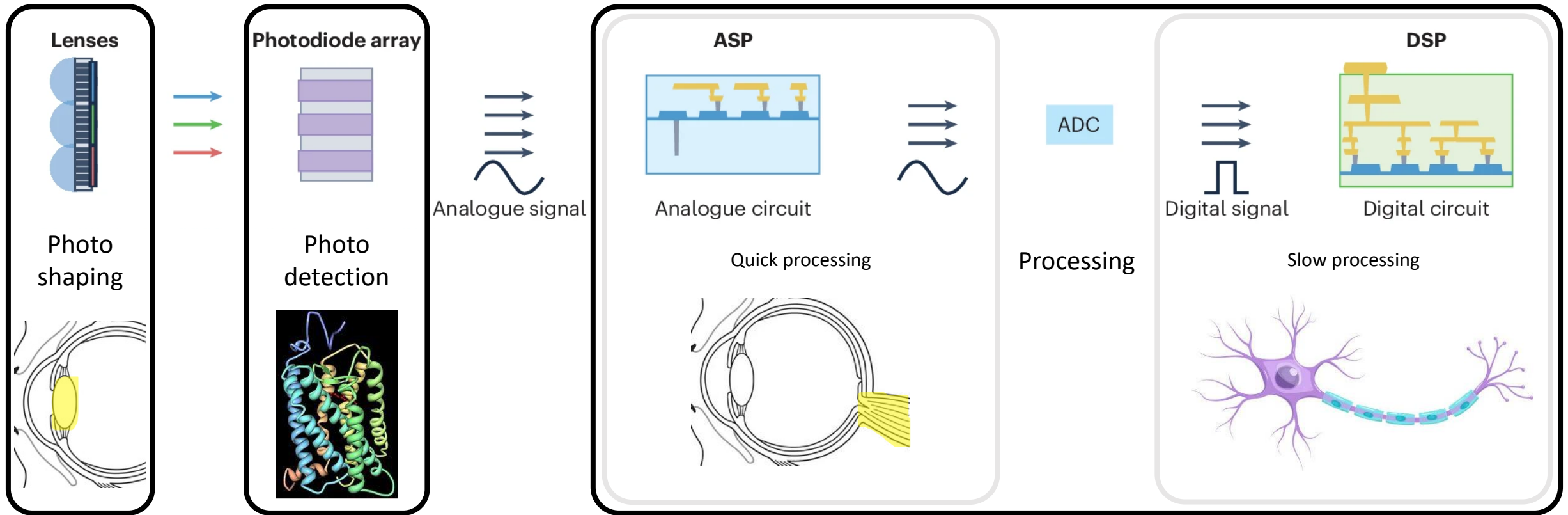
# Infrared Nanoscale Optoelectronics Based on Graphene



(ultra)fast, nanoscale temperature sensor



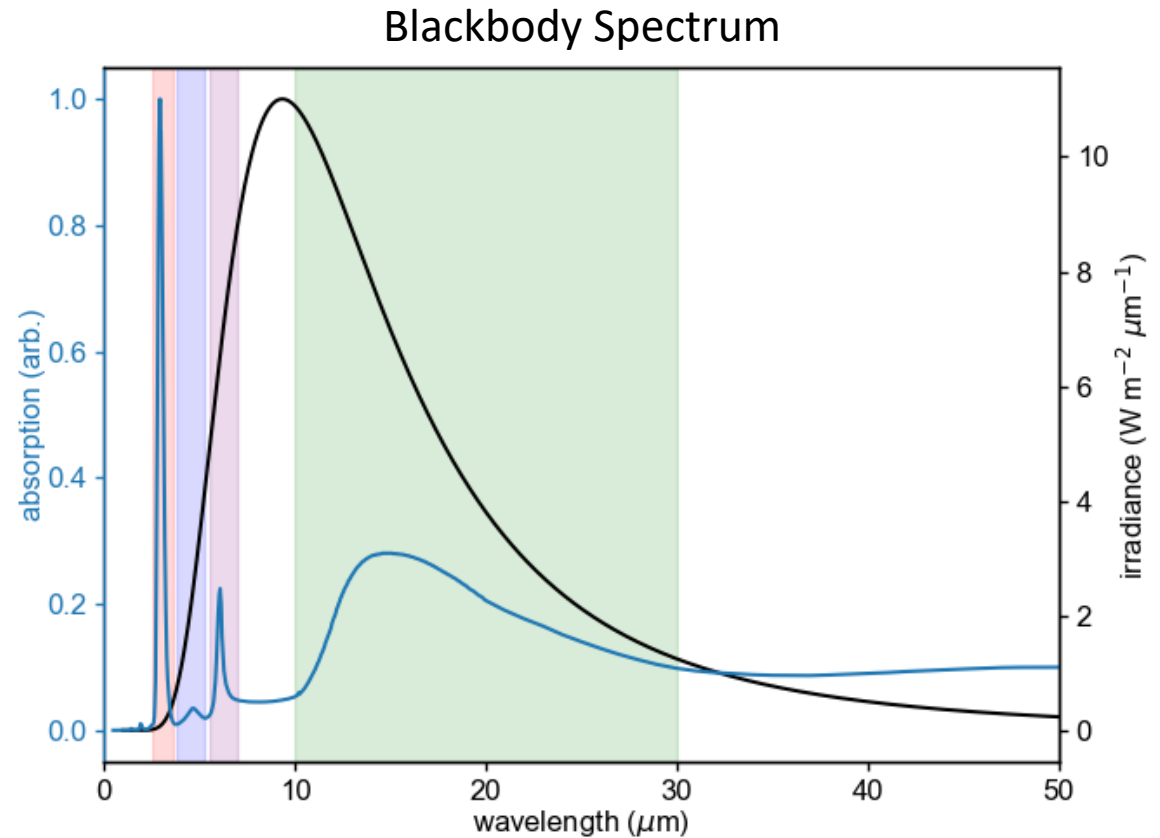
# Layered Architecture in State-of-the-Art Vision Sensors



Biosystems exhibit remarkable (albeit not-fully-understood) solutions to the vision sensor challenge



# (Nathan's) Water Bottle Conjecture



Can water be used for advanced infrared *vision sensing*?







# Acknowledgements



QMO Lab



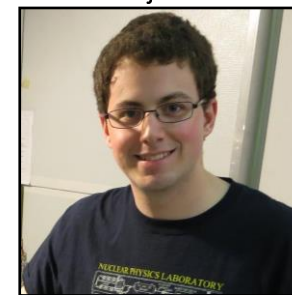
Nathaniel Gabor



Vivek Aji



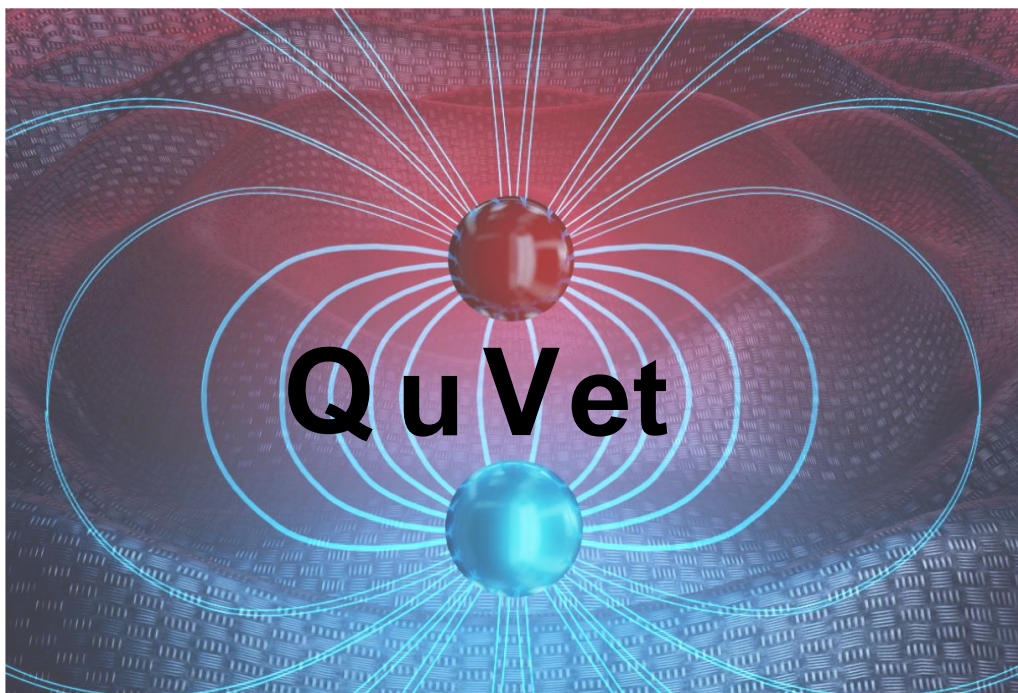
Zachary Miller



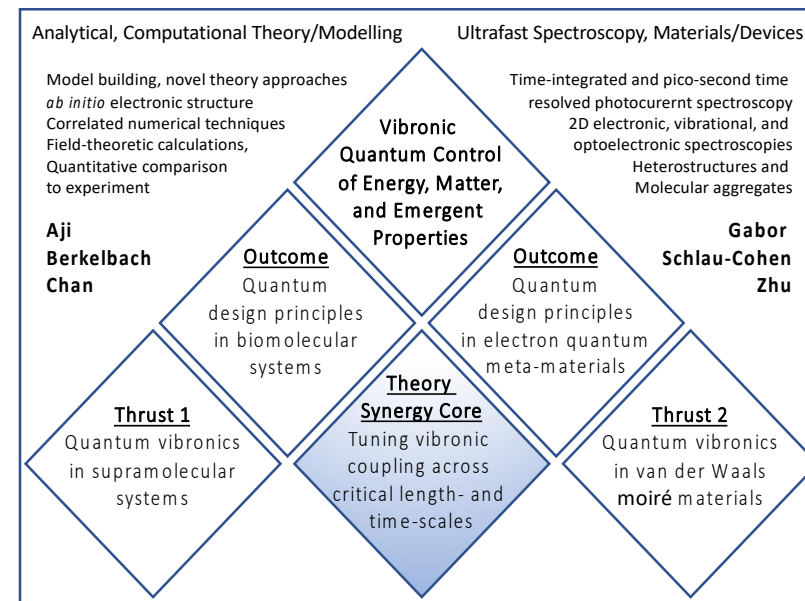
Trevor Arp







PI: Nathaniel Gabor  
(UCR)



Xiaoyang Zhu  
(Columbia)



Gabriela Schlau-Cohen  
(MIT)



Vivek Aji  
(UCR)



Tim Berkelbach  
(Columbia)



Garnet Chan  
(Caltech)