

Viper-Informed Infrared Vision Sensing

Nathaniel Gabor

qmolab.ucr.edu



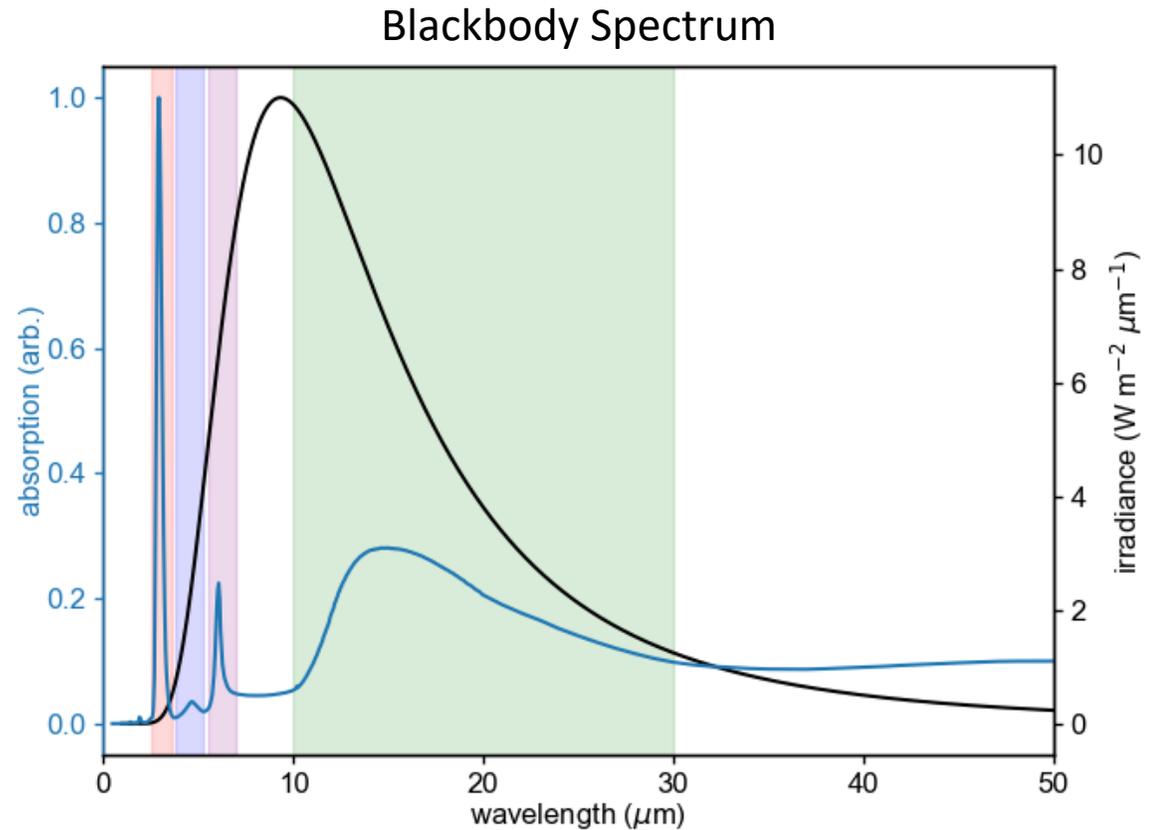
**Quantum Materials
Optoelectronics Lab**

UC RIVERSIDE UNIVERSITY OF CALIFORNIA





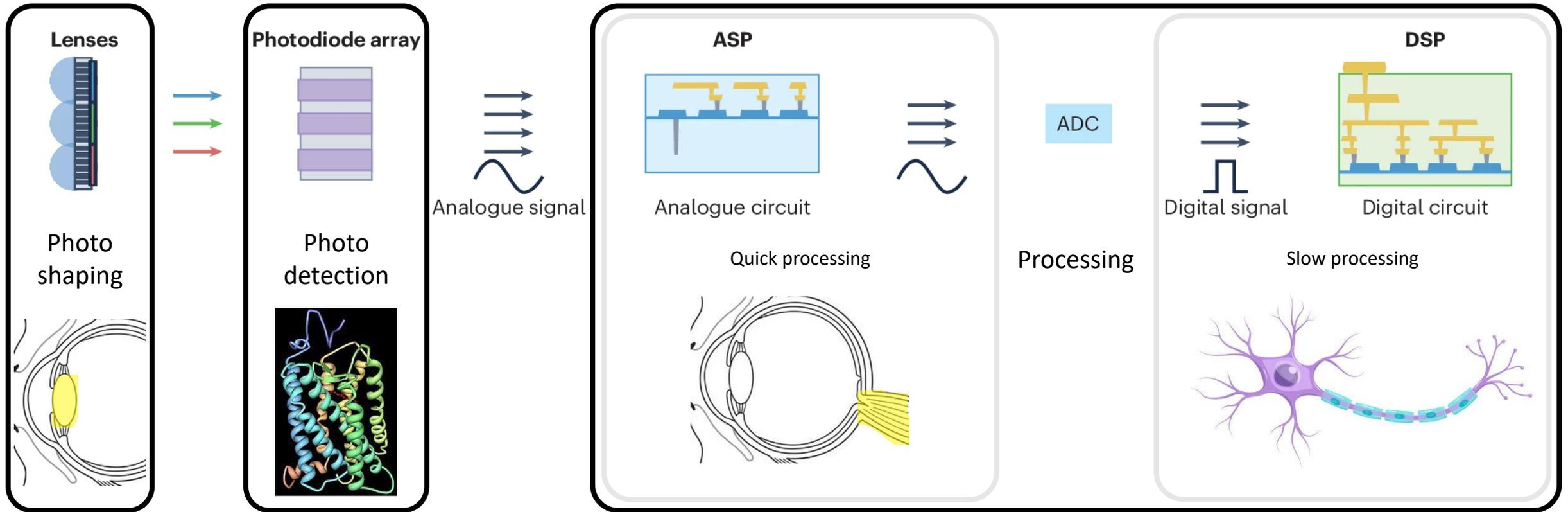
(Nathan's) Water Bottle Conjecture



Can water be used for advanced infrared *vision sensing*?



Layered Architecture in State-of-the-Art Vision Sensors

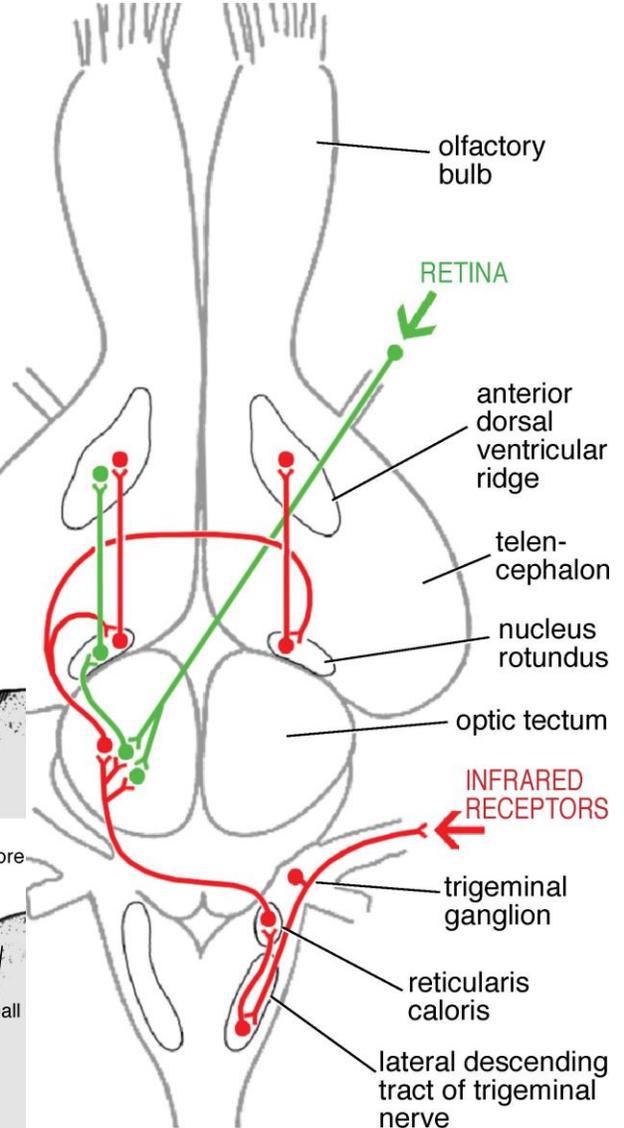
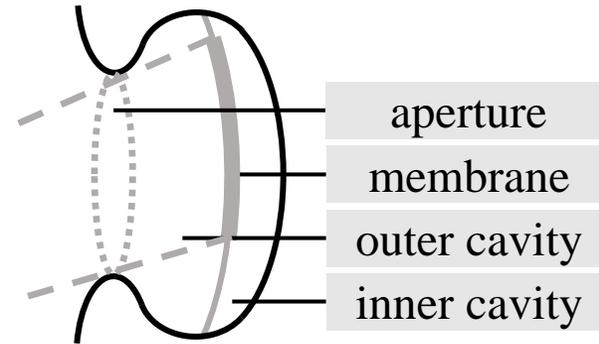


Biosystems exhibit remarkable (albeit not-fully-understood) solutions to the vision sensor challenge

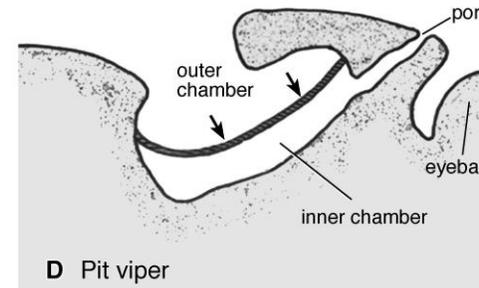
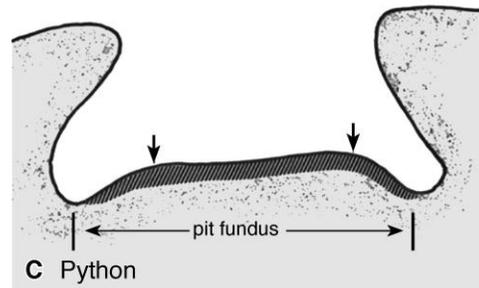
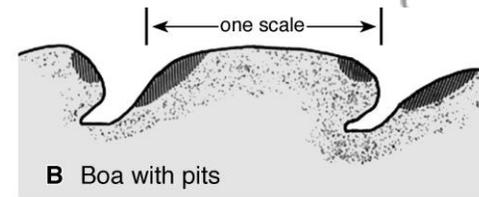
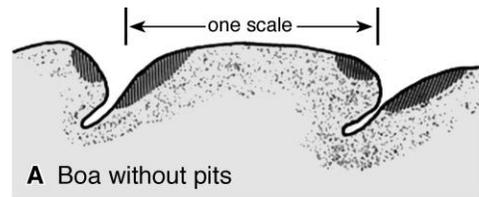




Infrared Vision Sensing in the Pit Viper

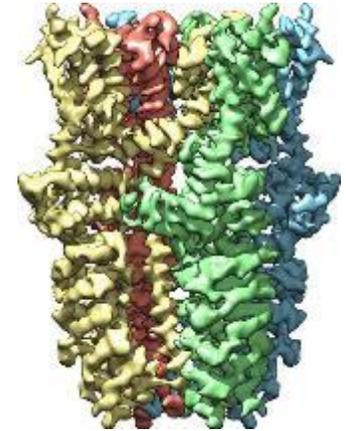
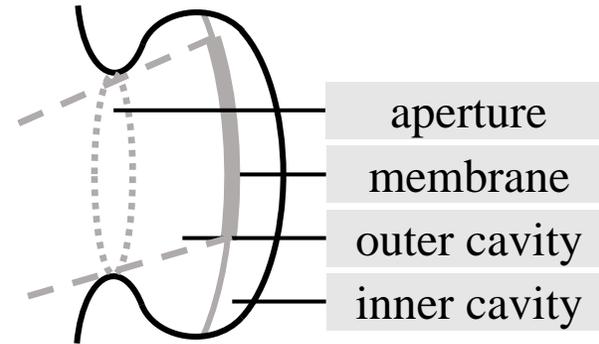


IR vision *enhances* normal vision
 multi-step interpretation
 very fast ~ 50 – 100 ms

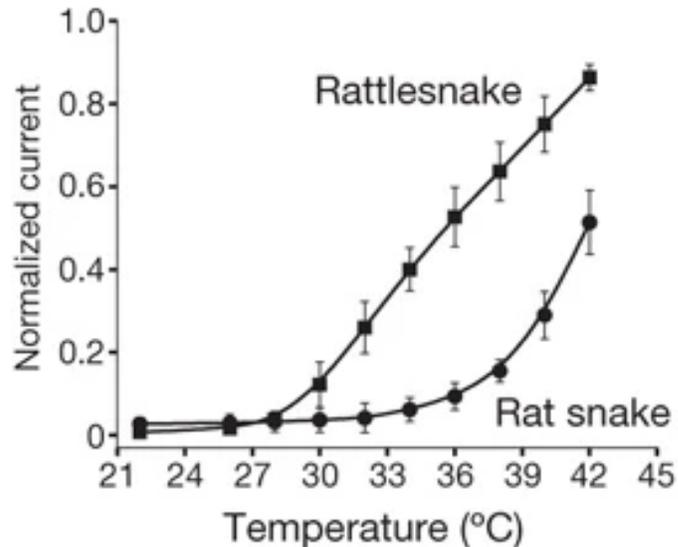




Infrared Vision Sensing in the Pit Viper



detection mediated by TRPA1 ion channels



- sensitive to temperature differences of $< 0.002^{\circ}\text{C}$
- ion channels must be $> 27^{\circ}\text{C}$

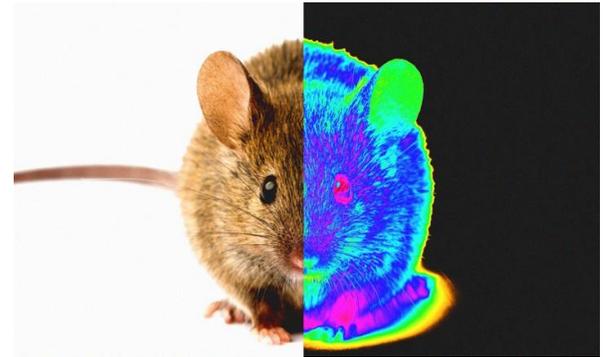
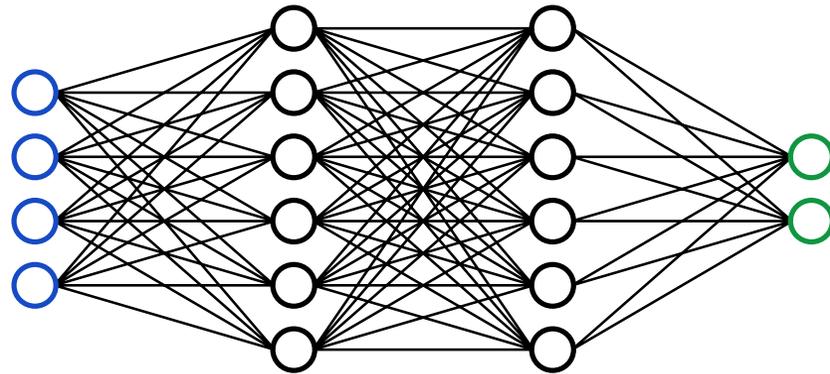
Hardware optimization problem:
light detection
vs.
image resolution



Proposal: Biologically Informed Infrared Vision

In humans, it takes ~250 ms to respond to visual stimulus,
~170 ms to respond to audio stimulus,
~150 ms to respond to a touch stimulus.

A pit viper can see, decide, and strike at a distance of one foot in 70 ms.

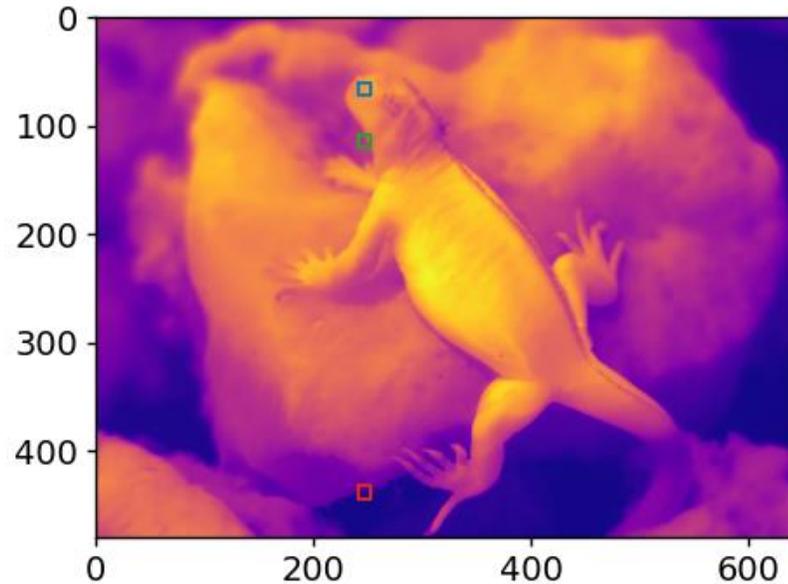


Given such seemingly low-resolution imaging hardware,
and such little computational power consumption,
how does the viper vision system work so efficiently?



Water for Infrared Vision Sensing

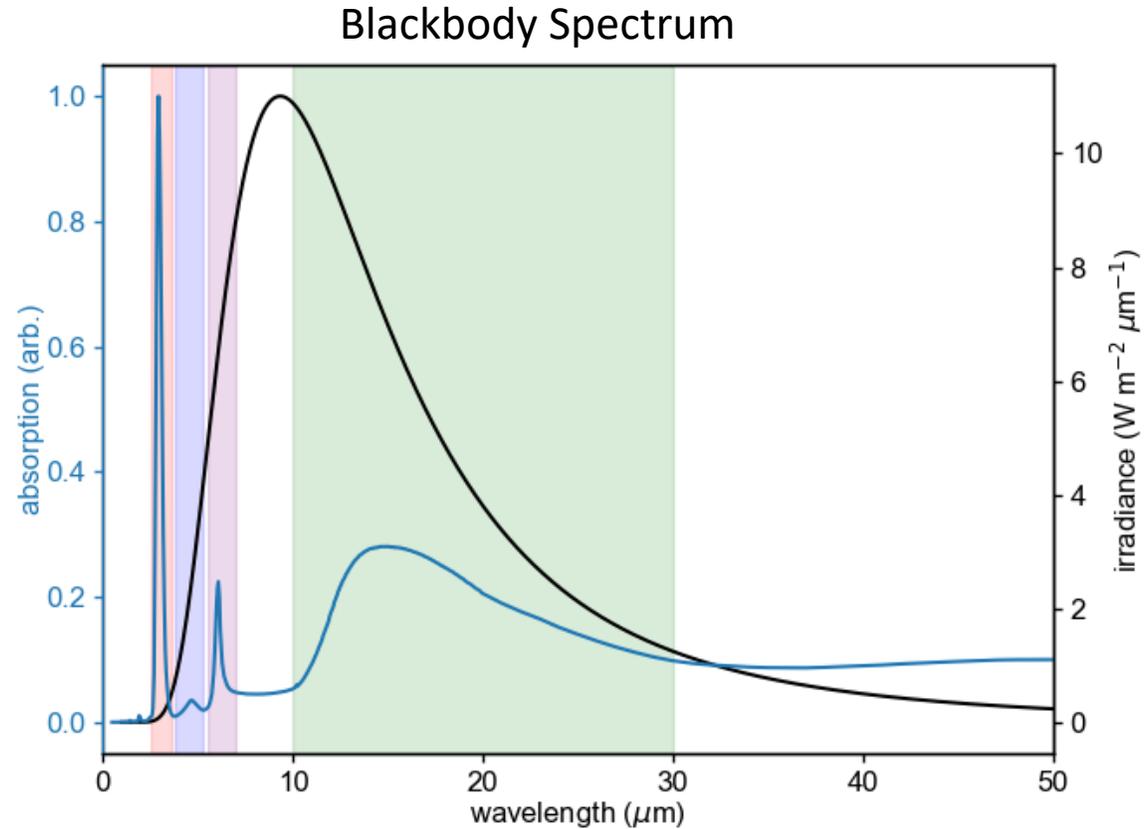
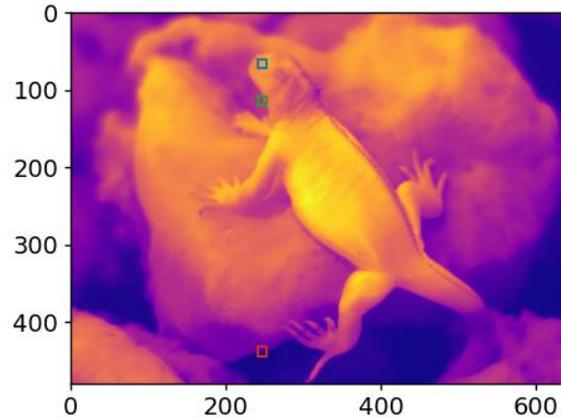
Temperature Image



How would a biological sensor best absorb infrared light?



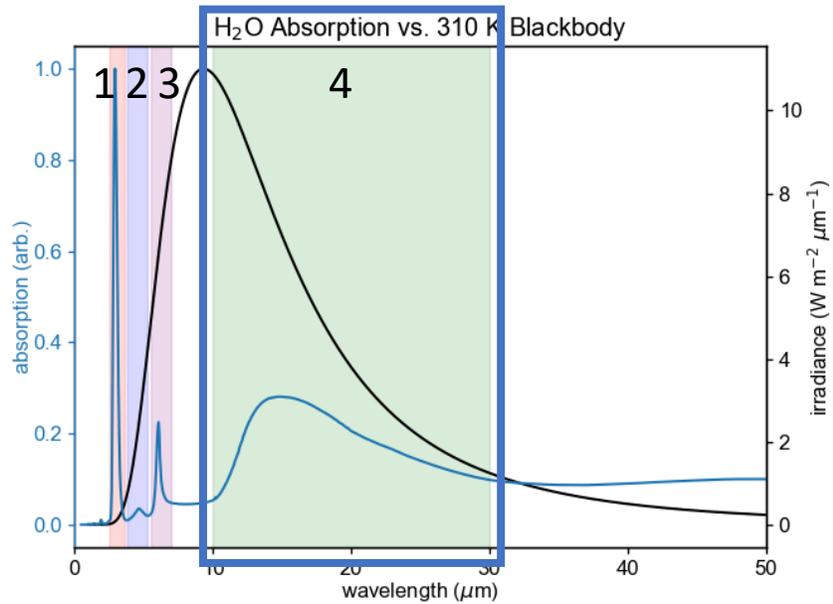
Water for Infrared Vision Sensing



Water is an ideal IR absorber, except at the peak of the blackbody spectrum



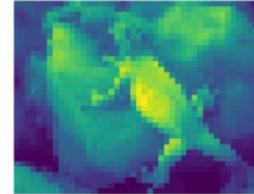
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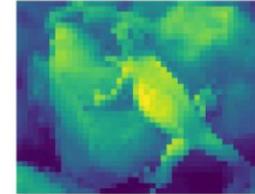
Temp. Image



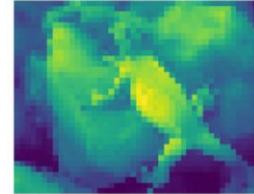
Channel 1: 2.5 μm to 3.6 μm



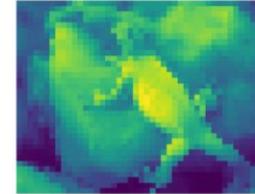
Channel 2: 3.8 μm to 5.3 μm



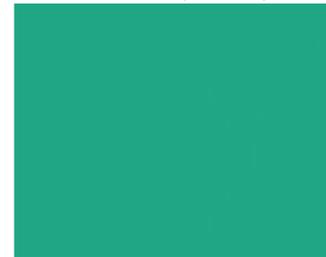
Channel 3: 5.5 μm to 7.0 μm



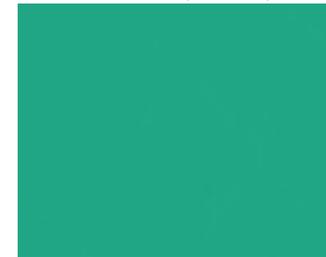
Channel 4: 10 μm to 30 μm



Channel 1: 2.5 μm to 3.6 μm



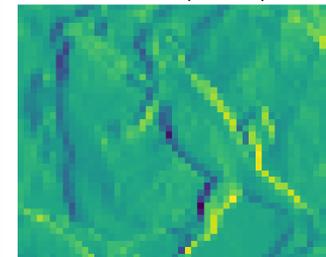
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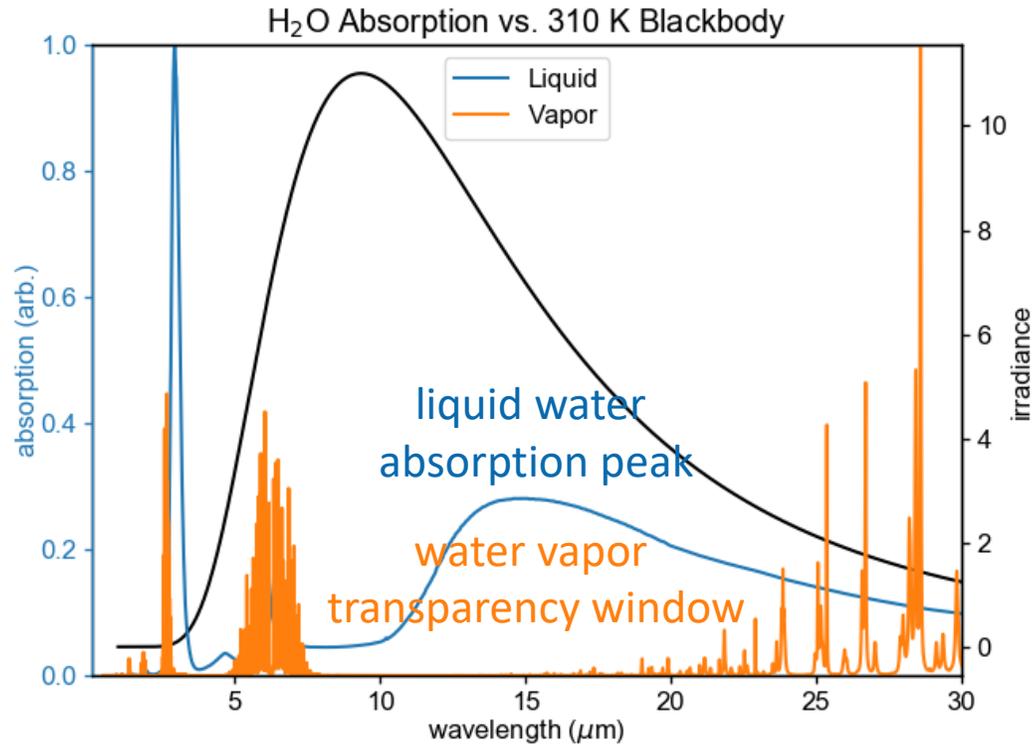


Channel 4: 10 μm to 30 μm





Water for Infrared Vision Sensing



Is water the solution to the biological infrared vision problem?

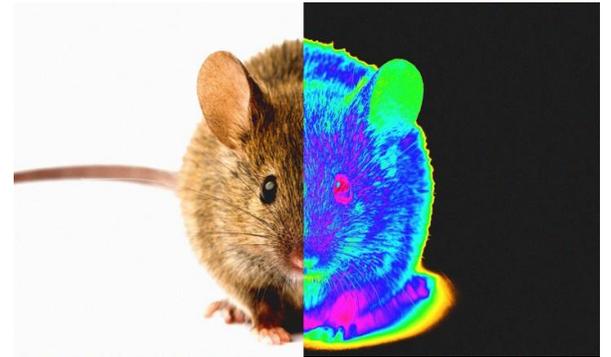
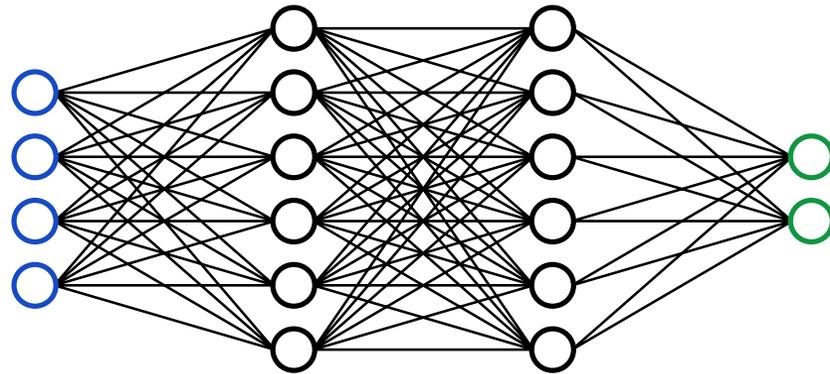
Hypothesis: the viper IR vision system is utilizing the molecular rotation of water!



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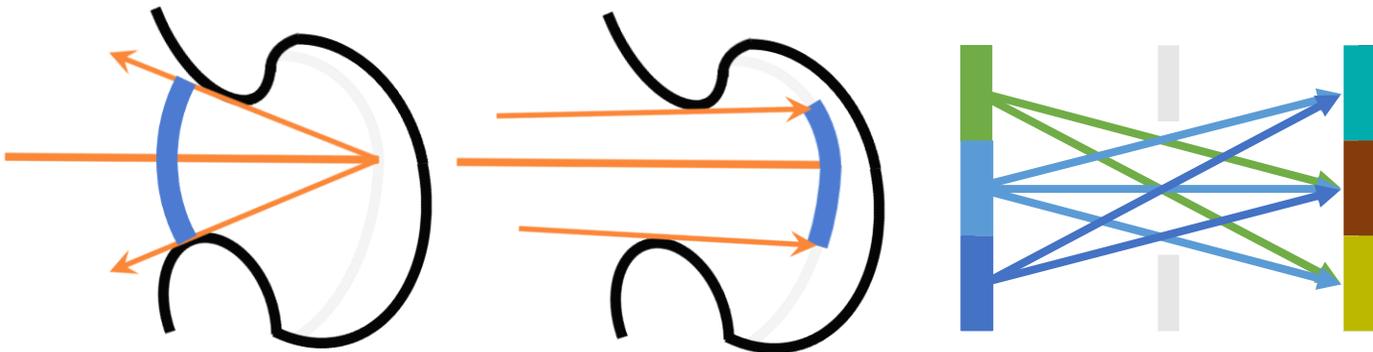


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Lens-less Infrared Imaging

Optimization problem:
light detection vs image resolution



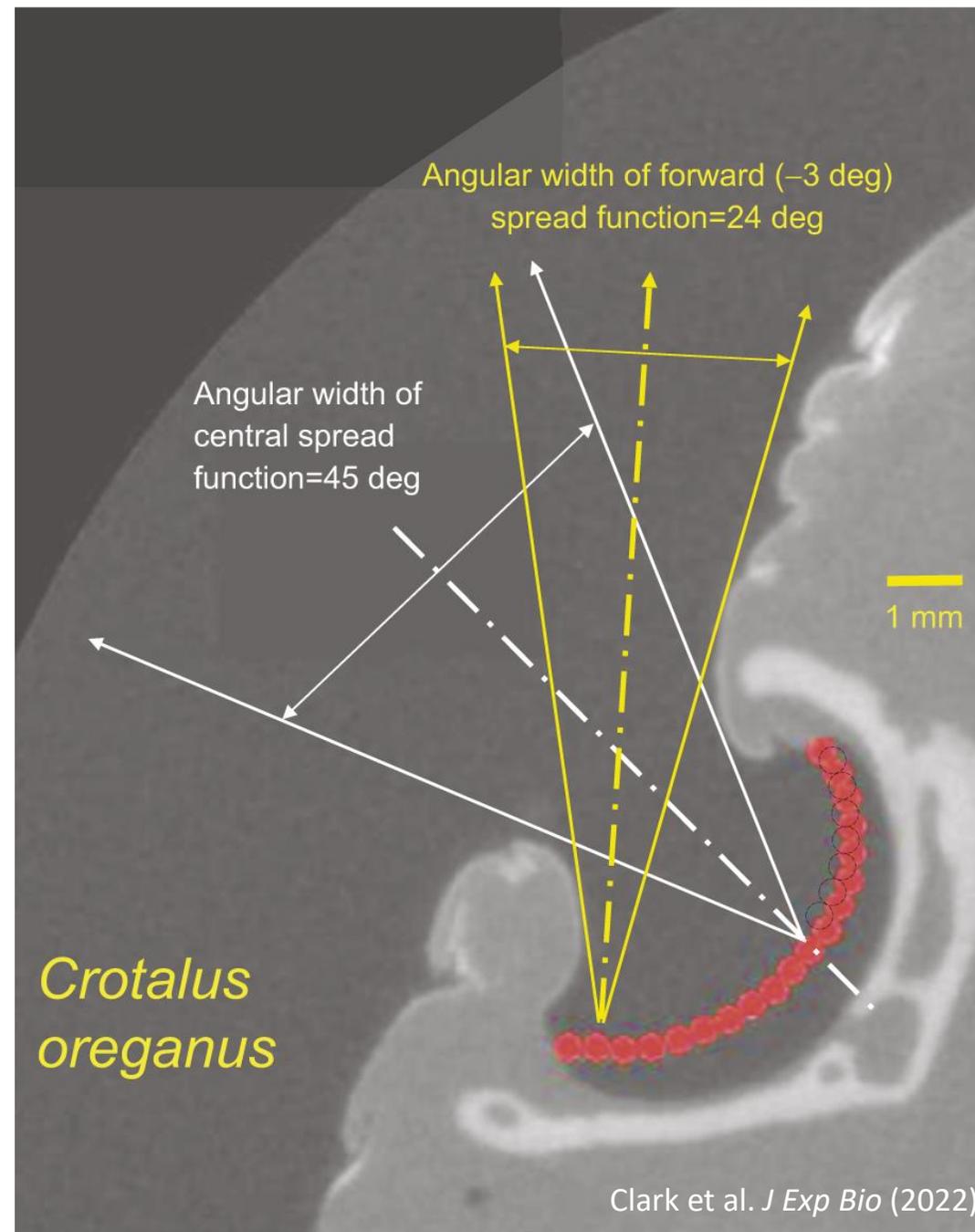
multiple emitters \rightarrow single detector
single emitter \rightarrow multiple detectors

- Transformation matrix T_{α}^{β}

- Reconstruction:

$$[\text{image space}]_{\beta} = R_{\alpha}^{\beta} [\text{detector space}]_{\beta}$$

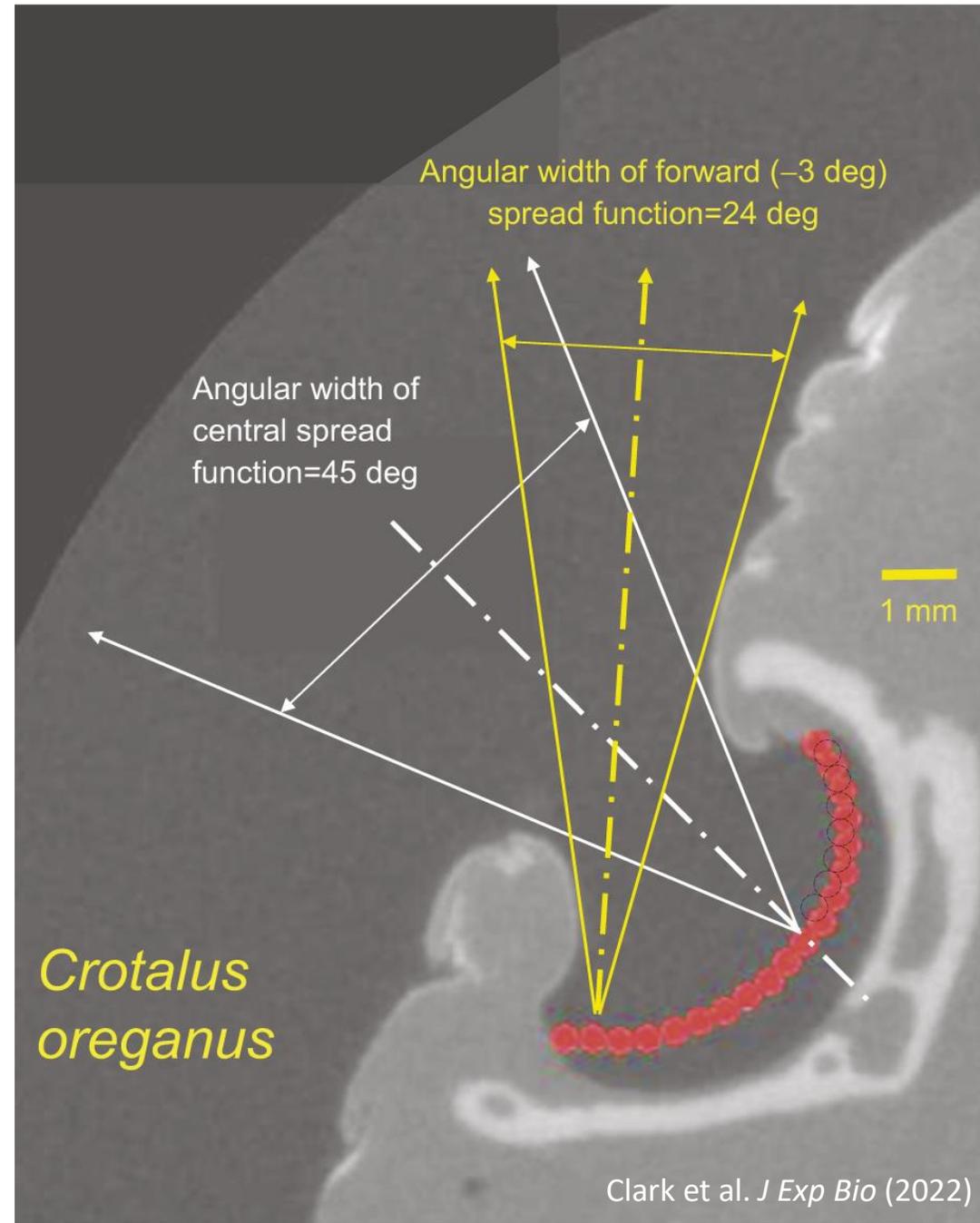
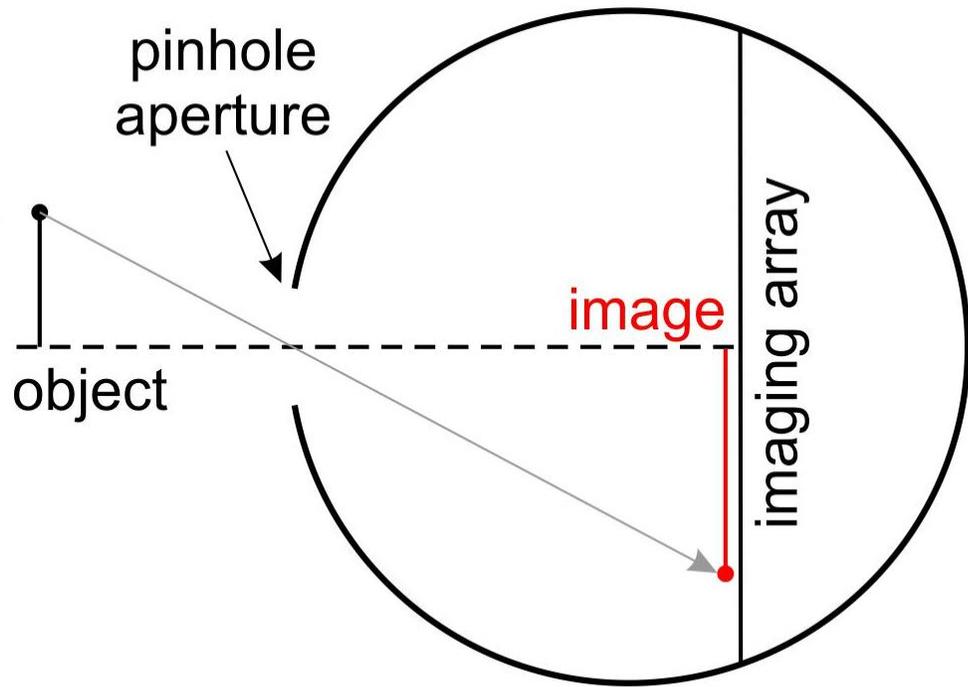
Sichert et al. *PRL* (2006)





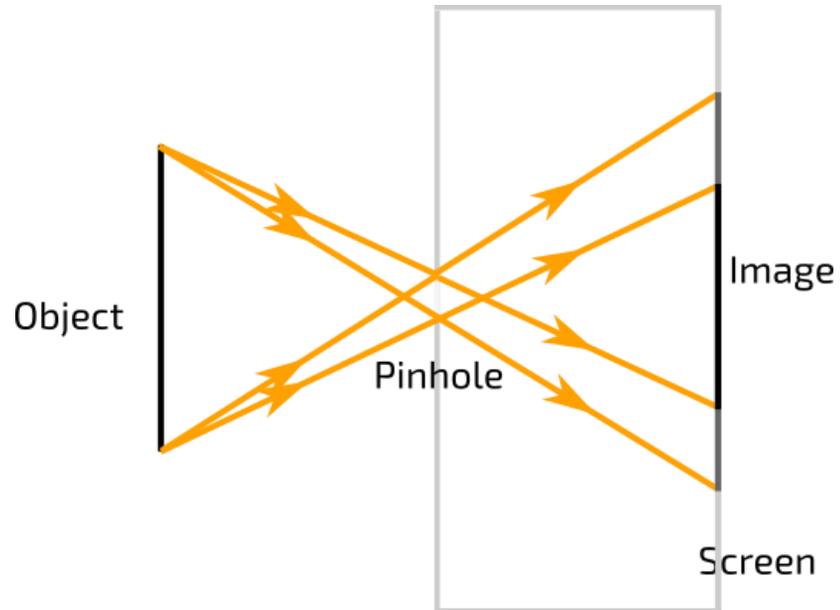
Lens-less Infrared Imaging

Optimization problem:
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Lens-less Infrared Imaging: Pinhole Camera



$$T_{\alpha}^{\beta} = r_{\alpha\beta}^{-2} \cos \varphi_{\alpha\beta}$$

$$R^{\mu}_{\gamma} [T_{\nu}^{\delta} T^{\gamma}_{\delta} (1 + \tau^2) + \sigma^2 \delta_{\nu}^{\gamma}] = T_{\nu}^{\mu}$$

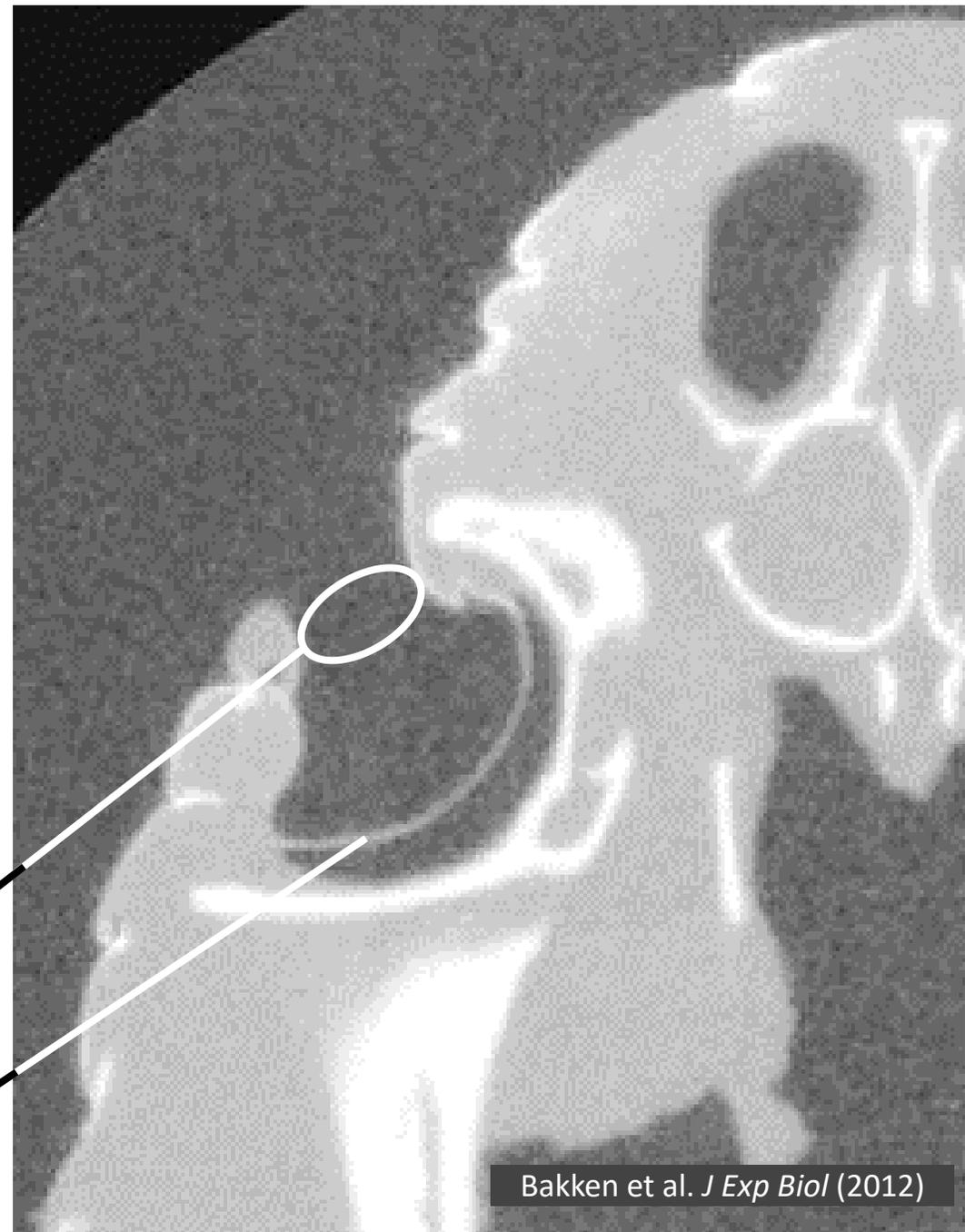
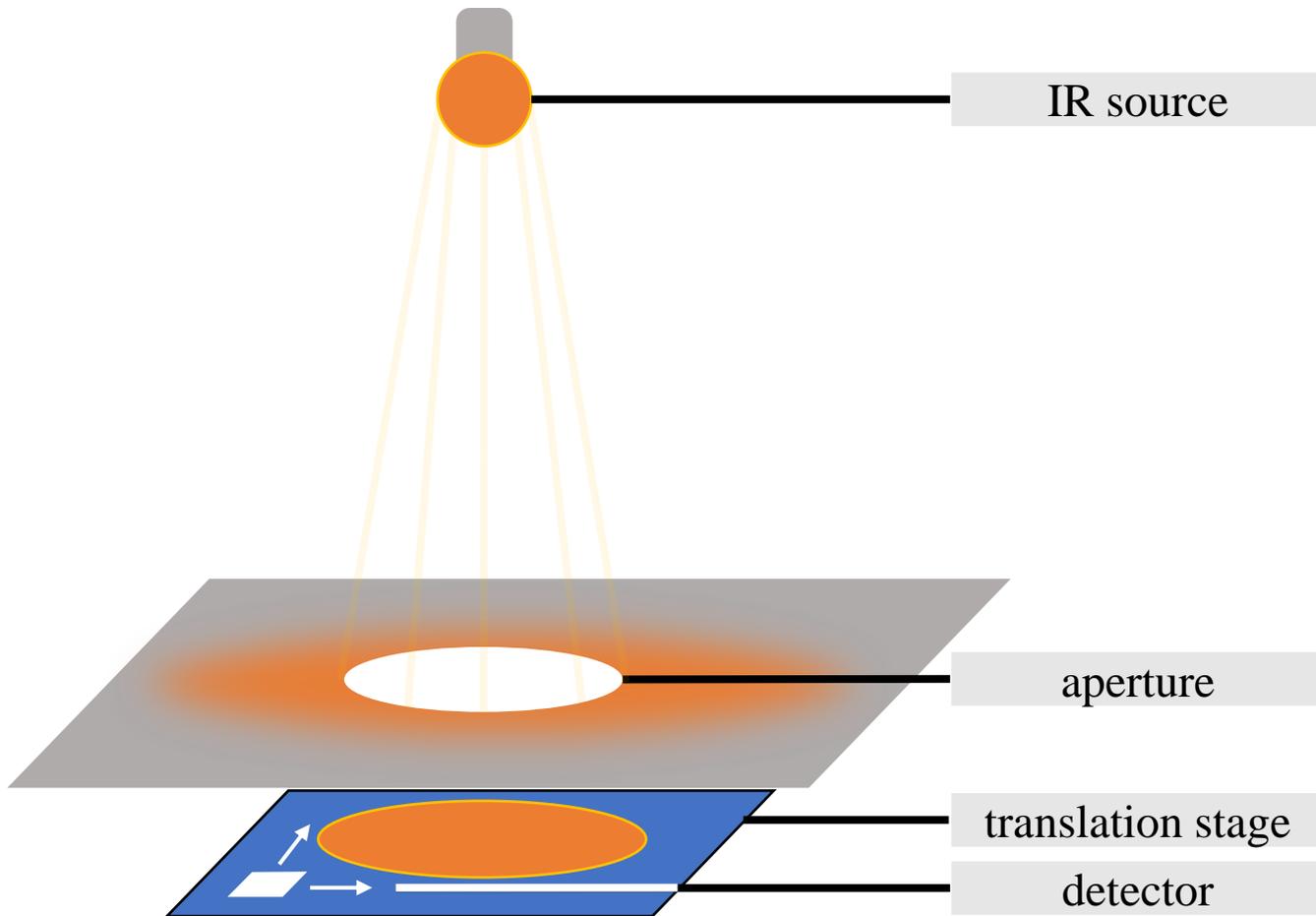
$$I_{\alpha} = R_{\alpha}^{\beta} S_{\beta}$$

At each point in space, we first calculate the heat distribution on the membrane for a given heat distribution in space.

In only one computational step, we then use stochastic reconstruction to estimate the input image from the measured response on the membrane.

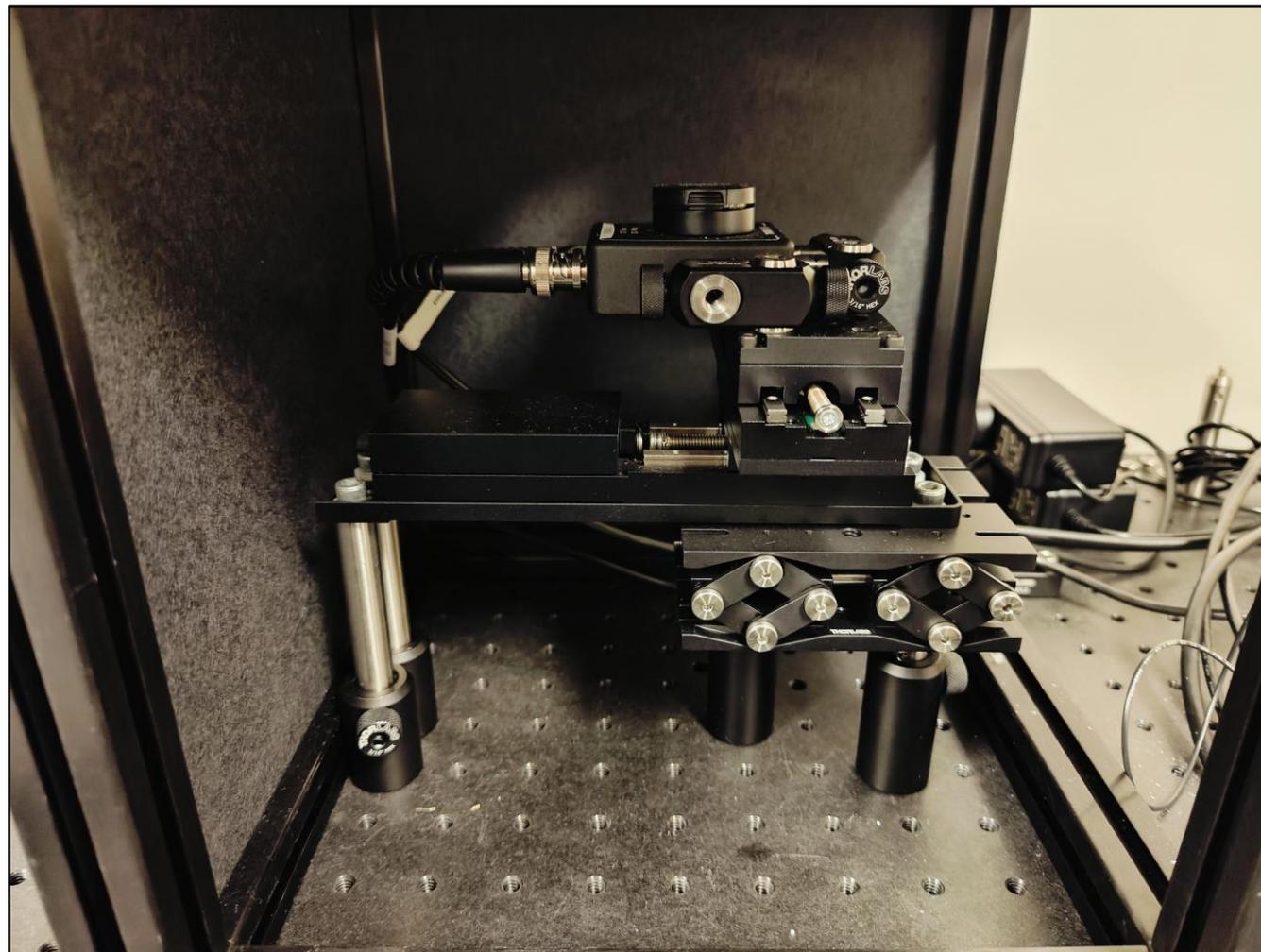
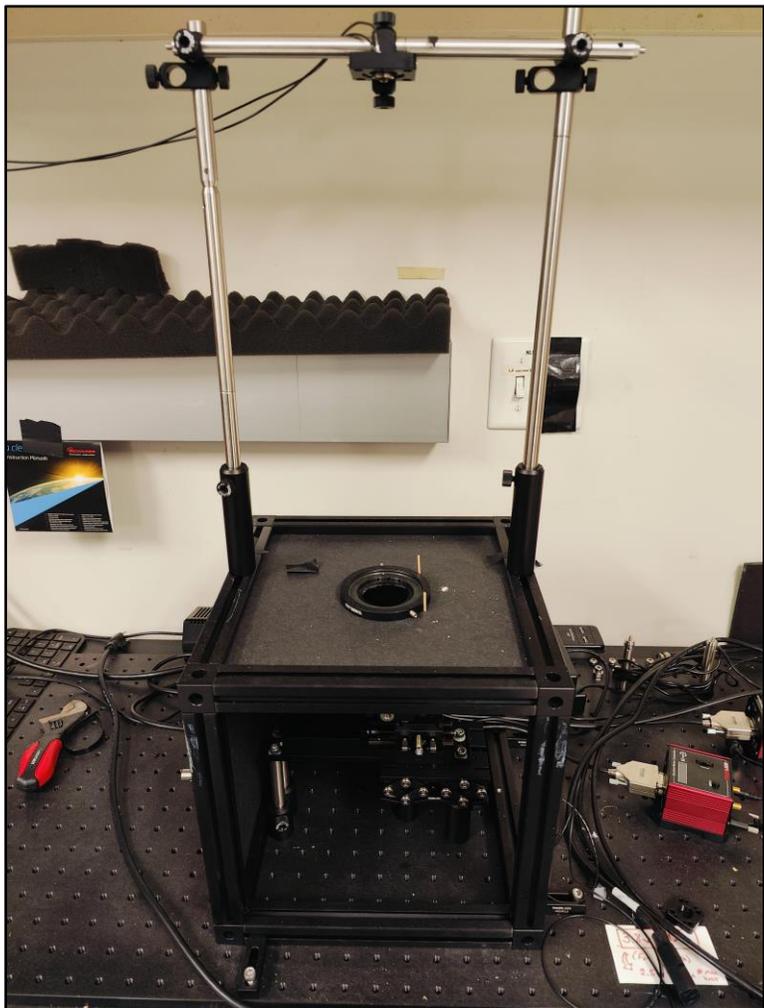


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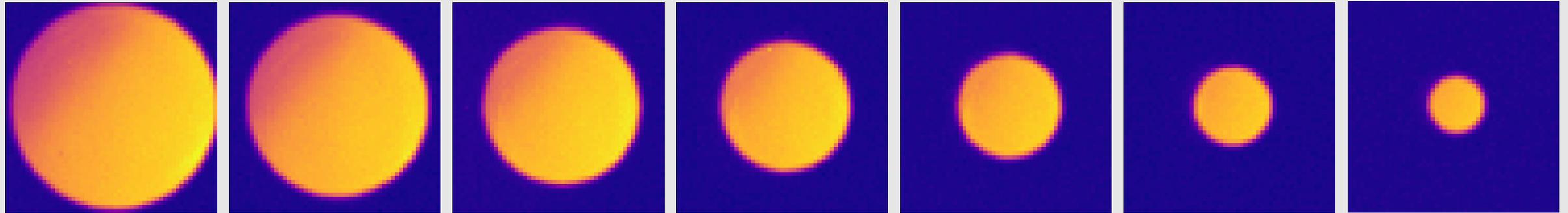


Lens-less Infrared Imaging: Pinhole Camera





Lens-less Infrared Imaging: Pinhole Camera



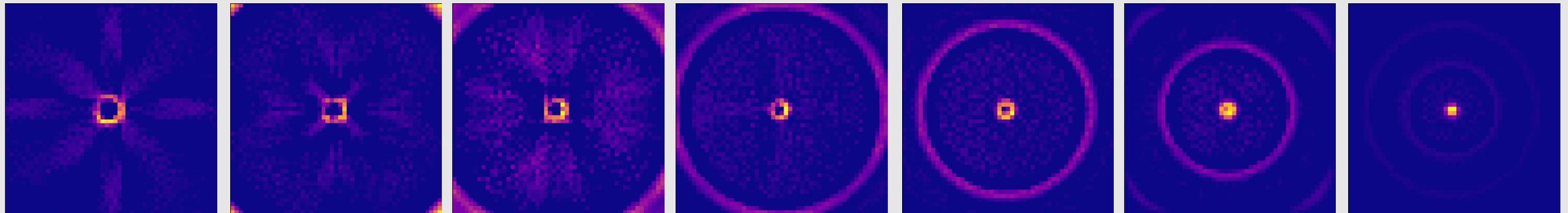
40 mm

aperture diameter

25 mm

decreasing

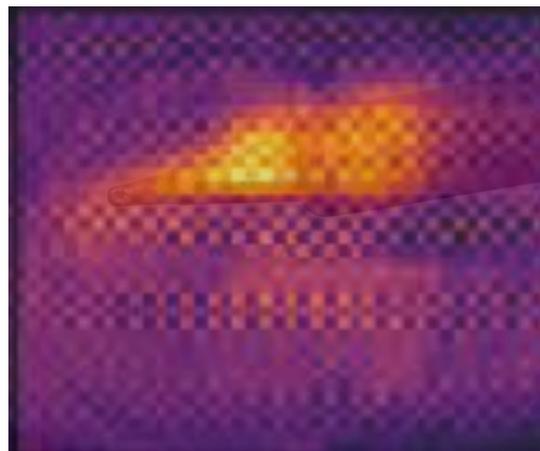
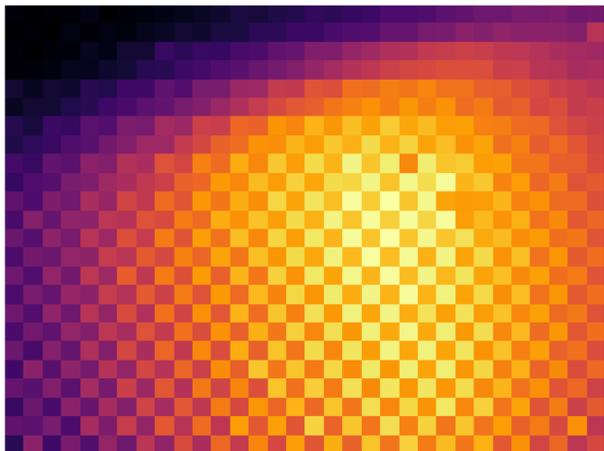
10 mm



A closed aperture (10 mm) reproduces the point source and rejects stray light, as expected from a pinhole camera

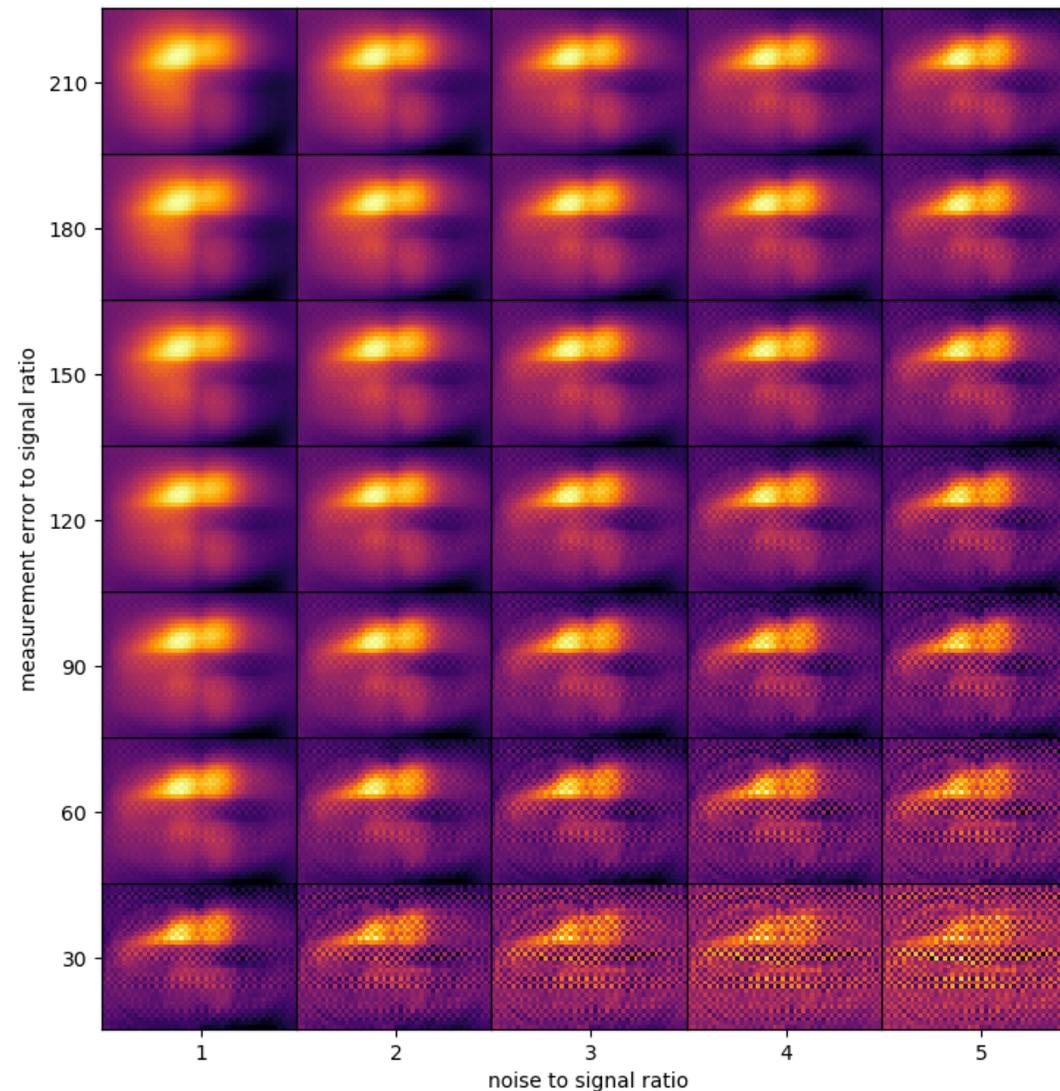


Lens-less Infrared Imaging: Commercial Sensor



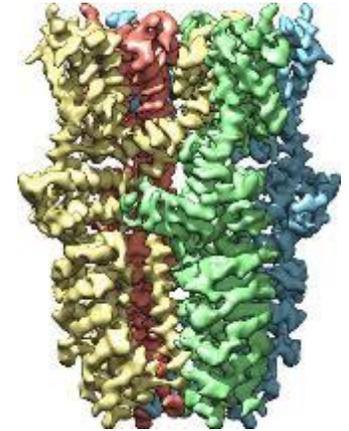
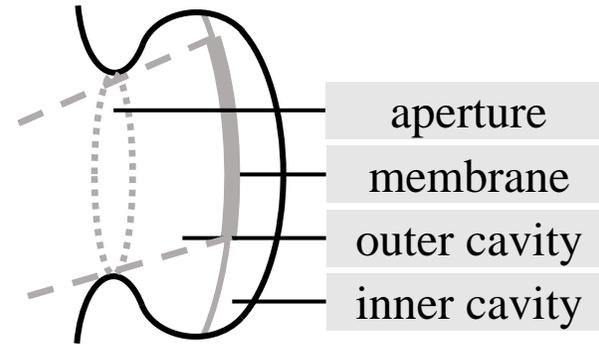
With a **lens-less** commercial IR photocell array, our protocol outperforms the imaging quality of the packaged device

With advanced sensors, can we do even better?

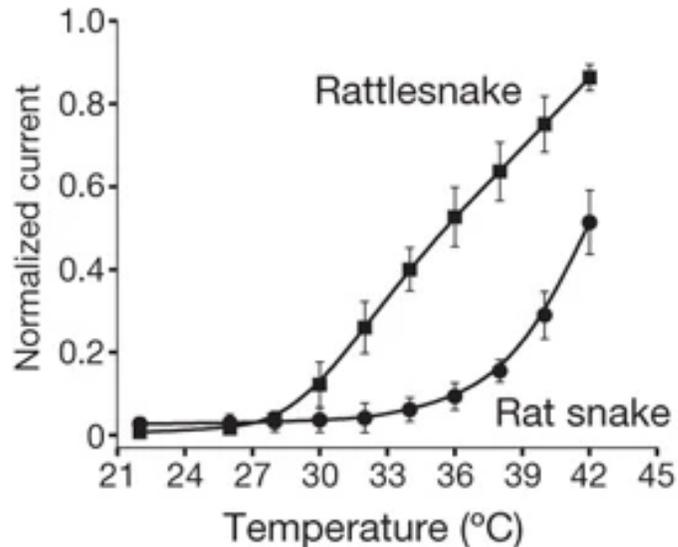




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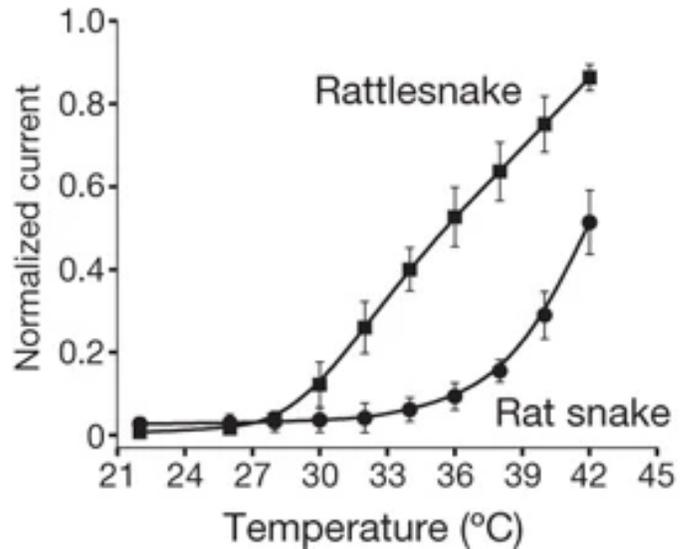


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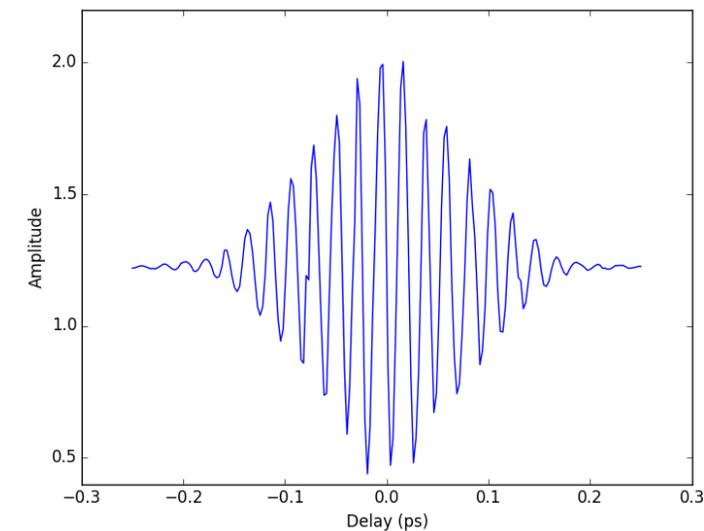
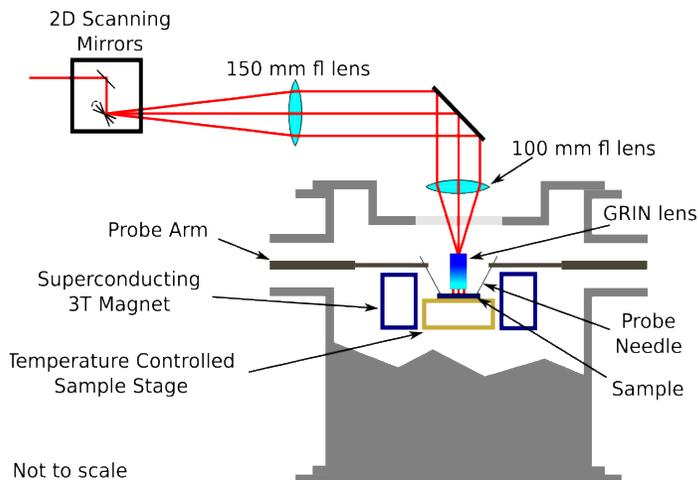
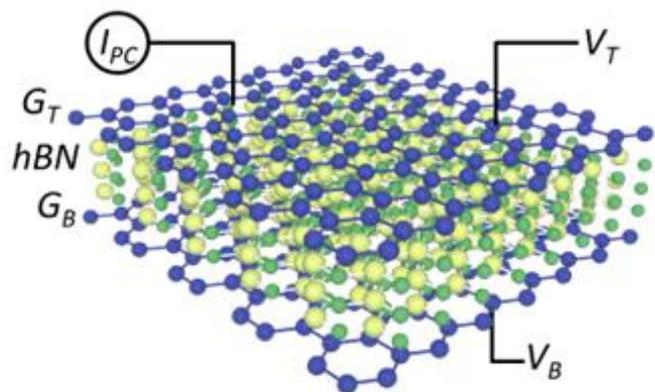
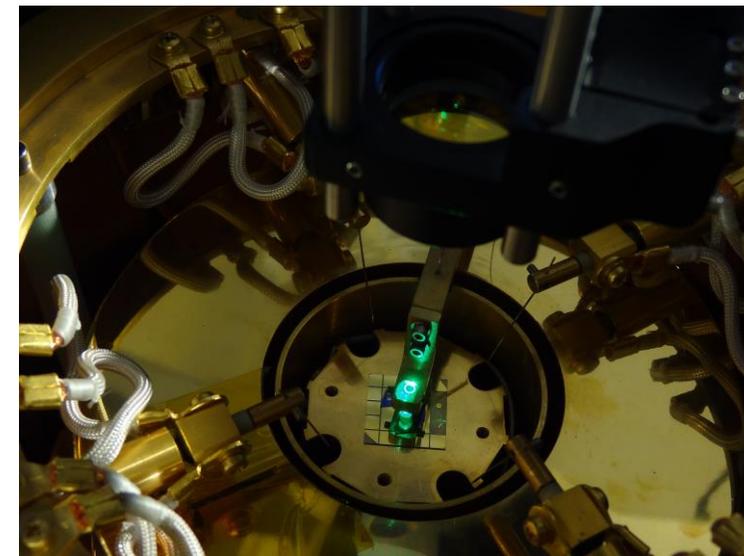
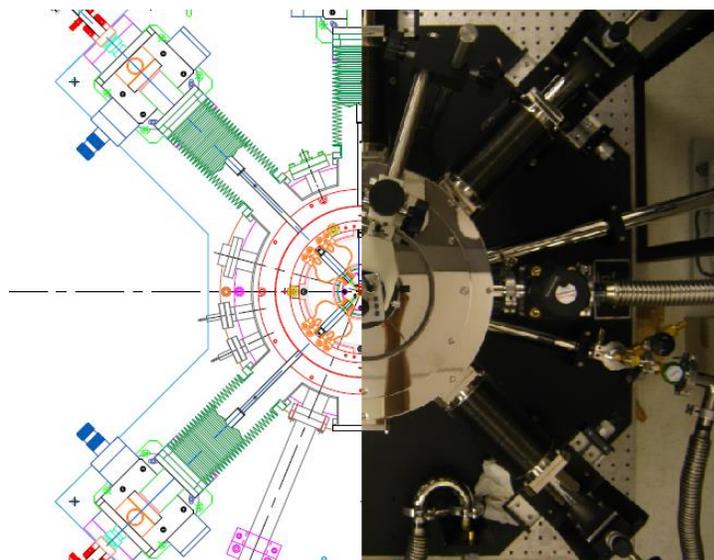
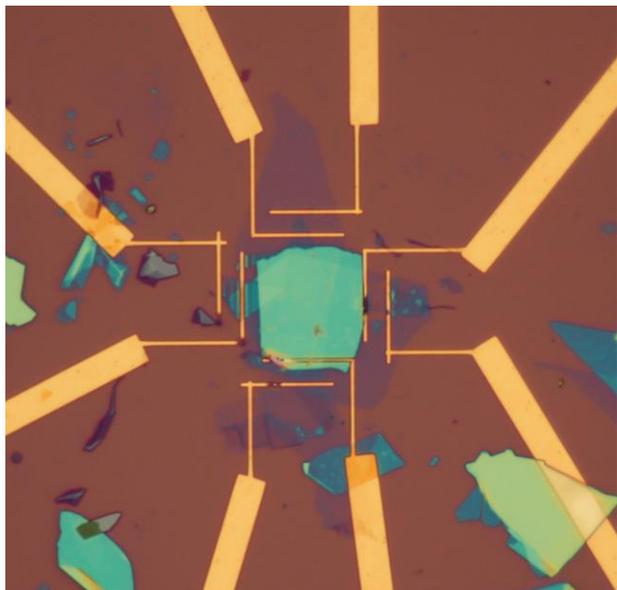
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The pit viper utilizes a fast, nanoscale temperature sensor with sharp super-linear threshold behavior

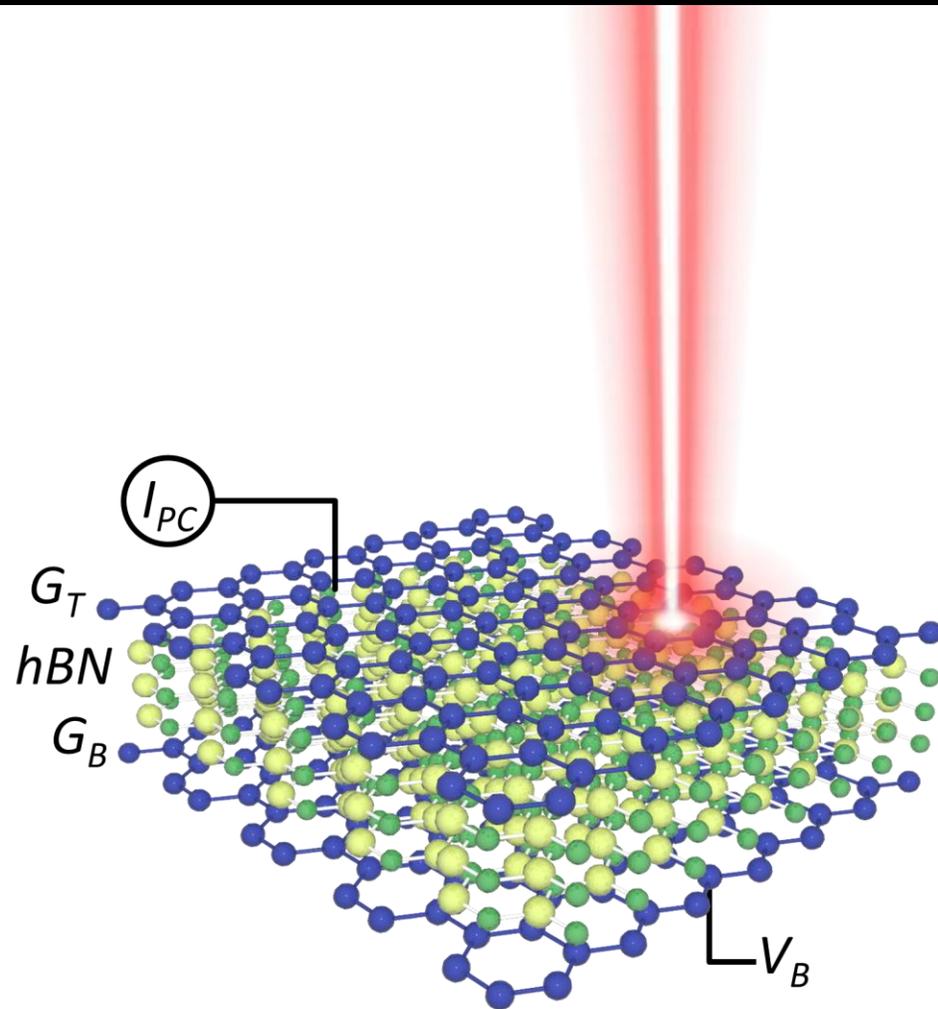
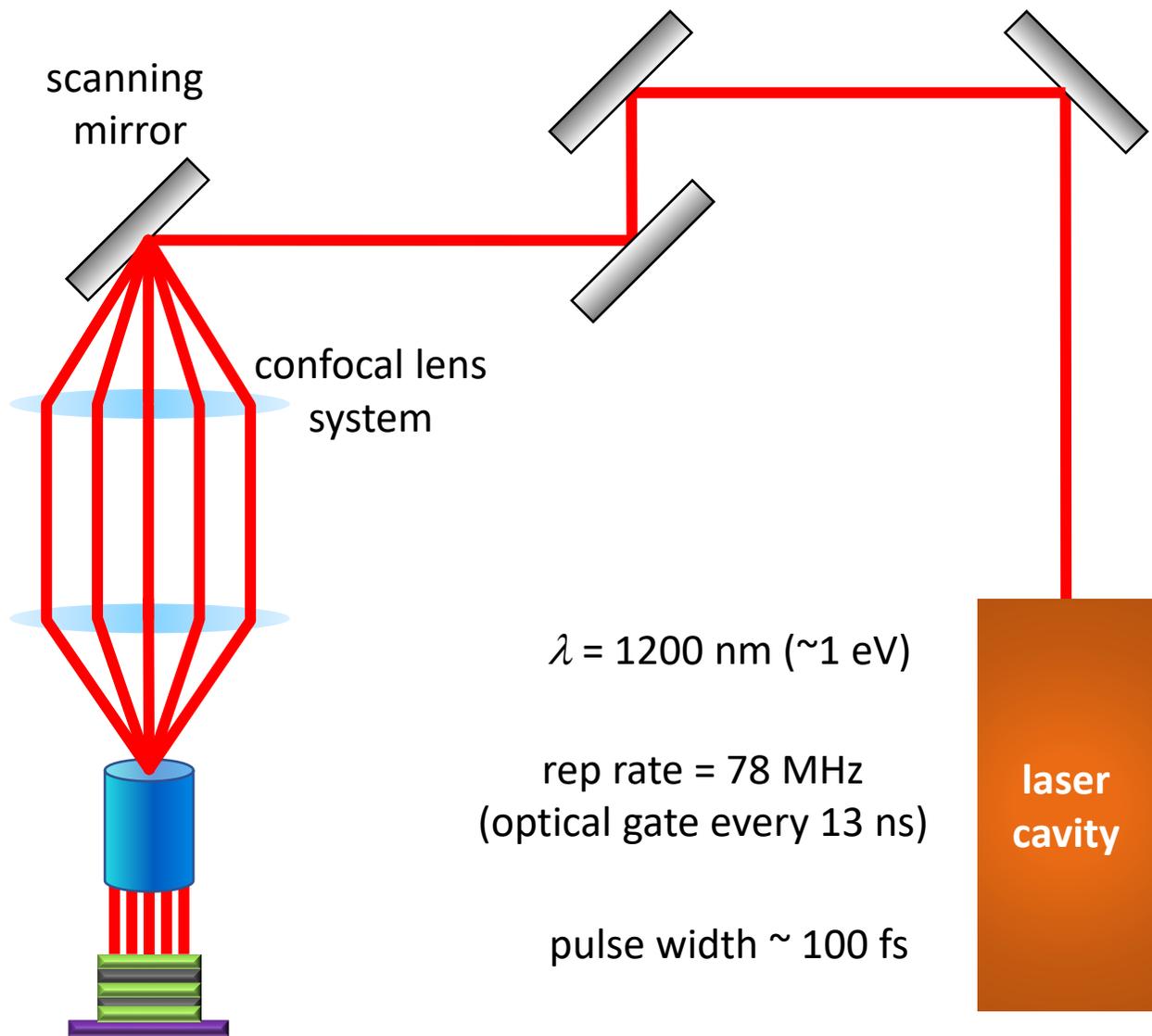


Infrared Nanoscale Optoelectronics in the Gabor Labs



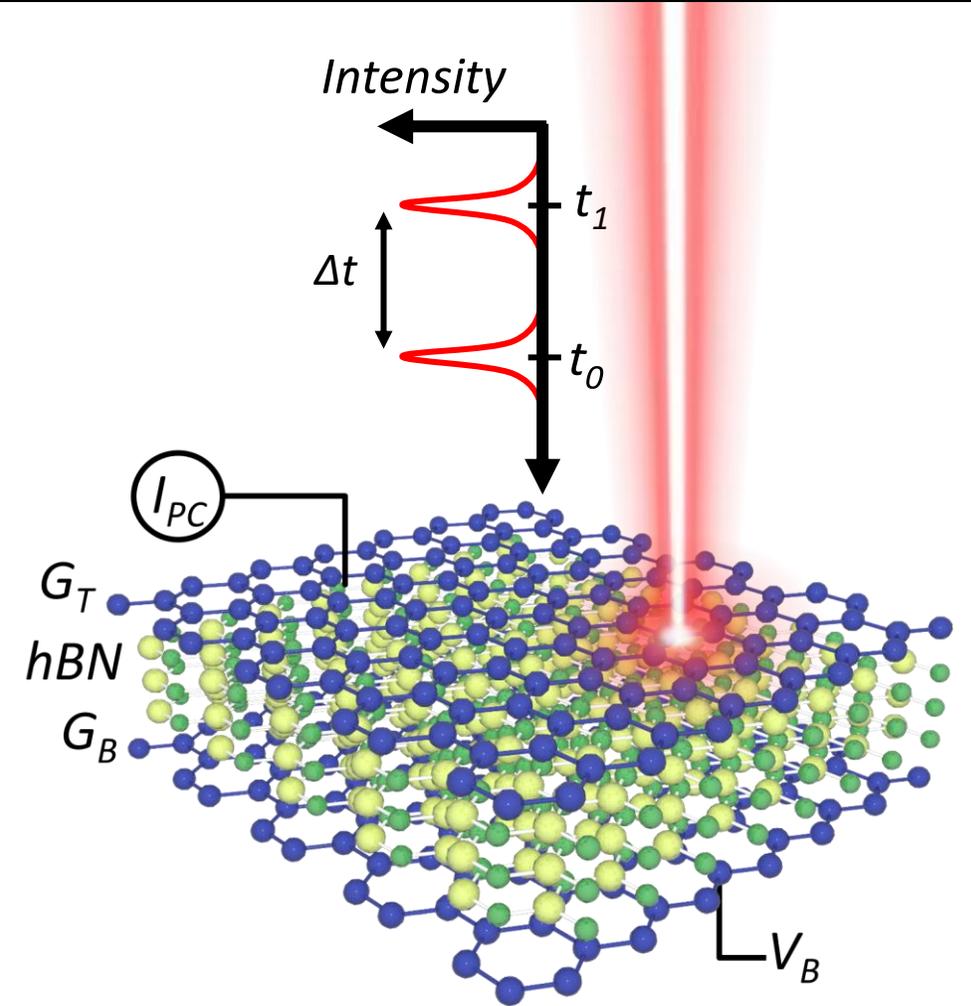
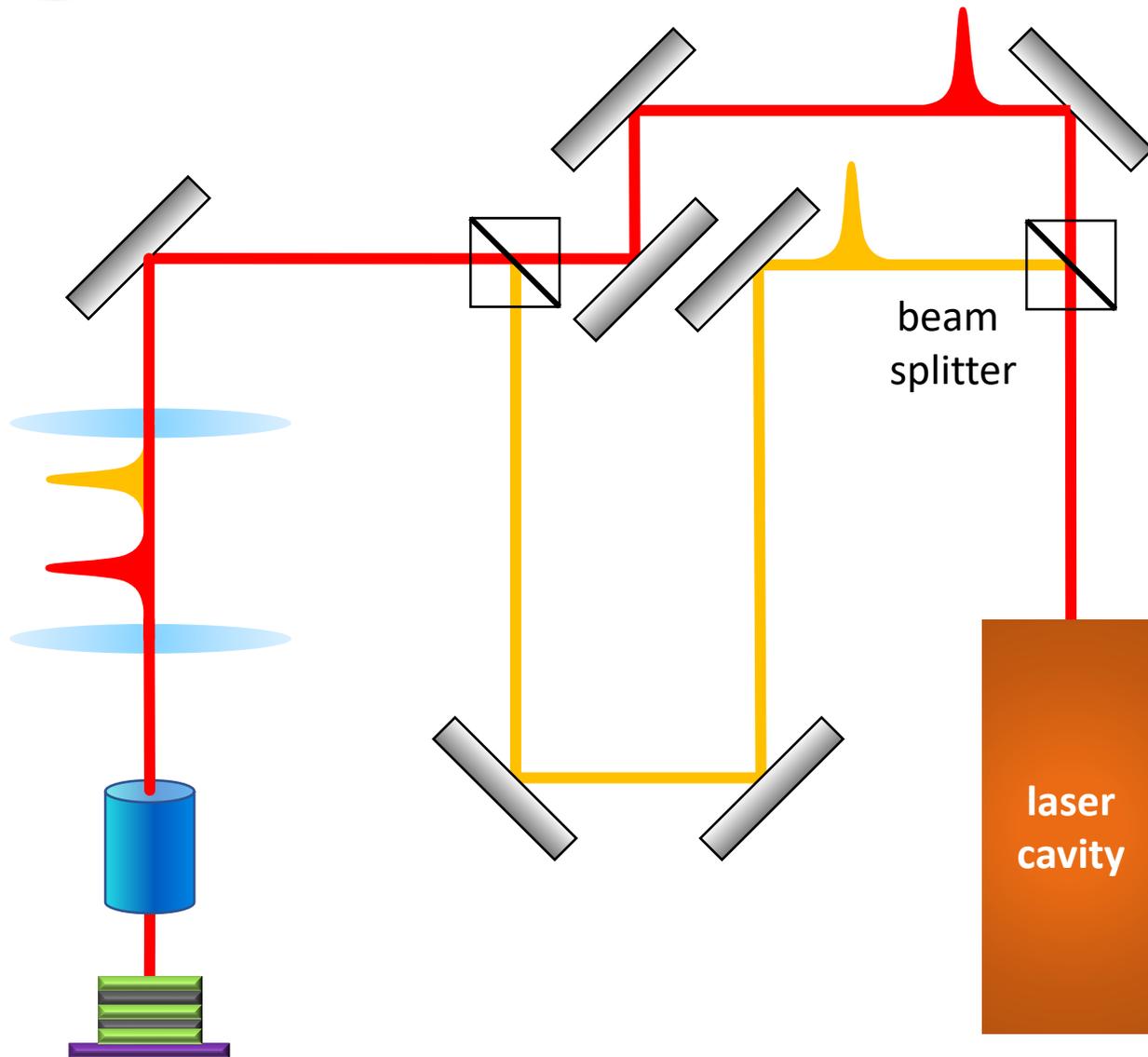


Infrared Nanoscale Optoelectronics Based on Graphene



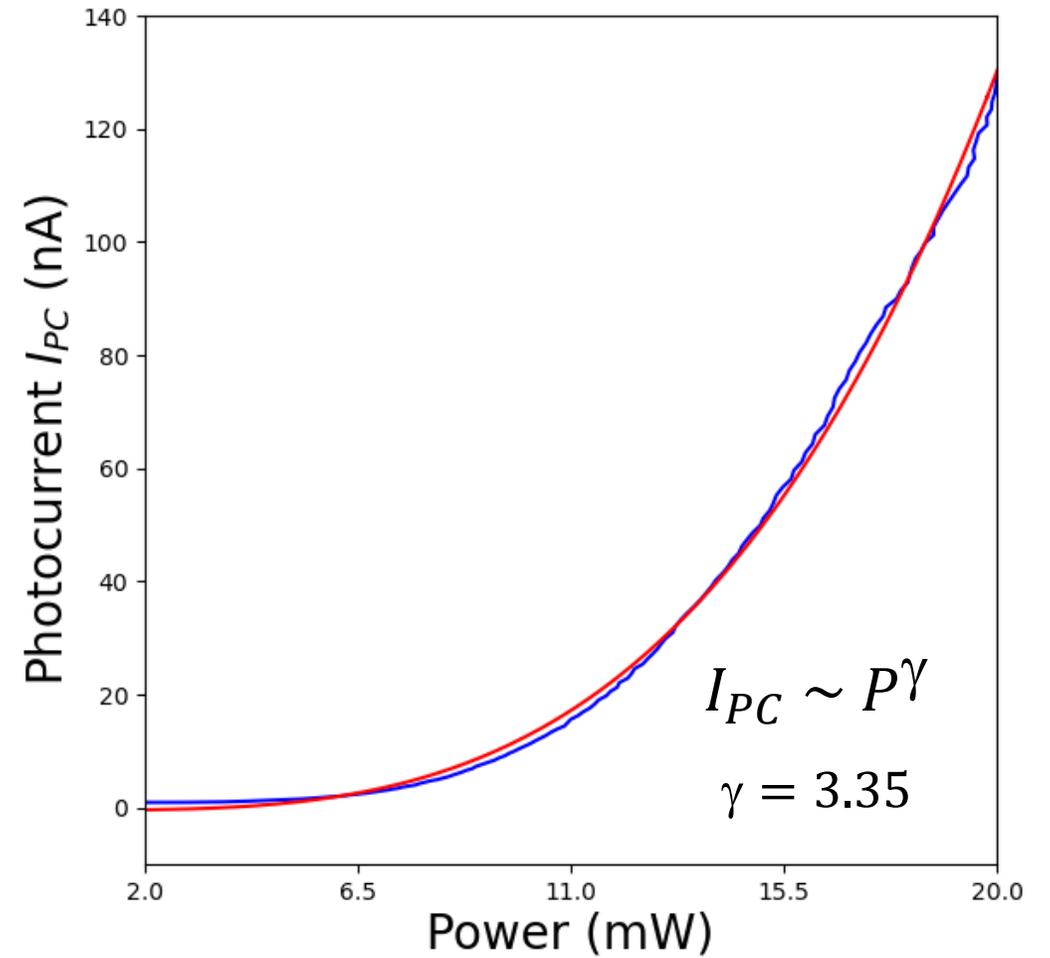
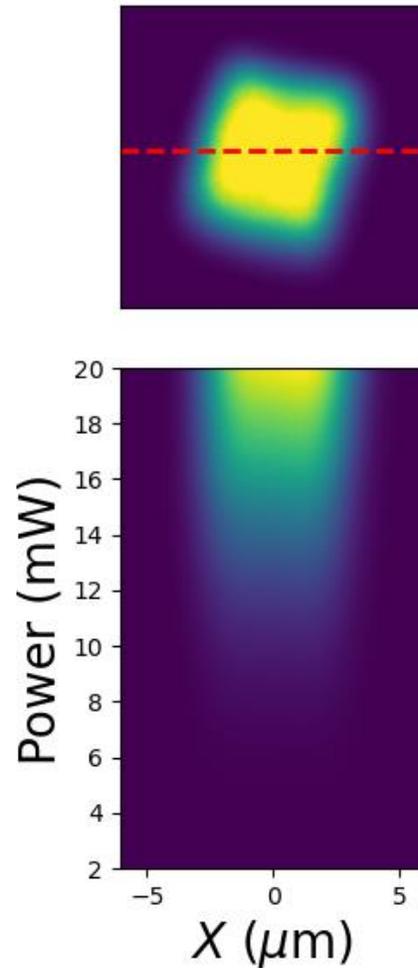
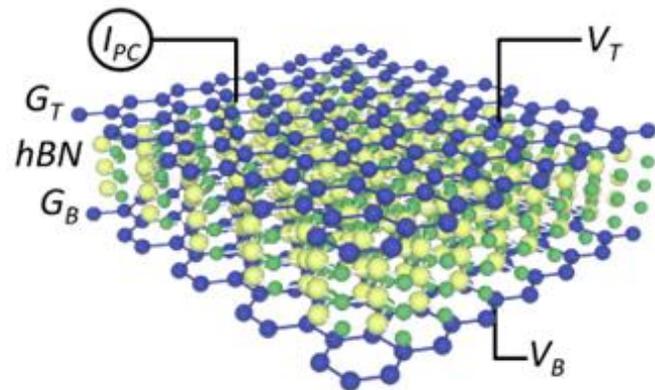
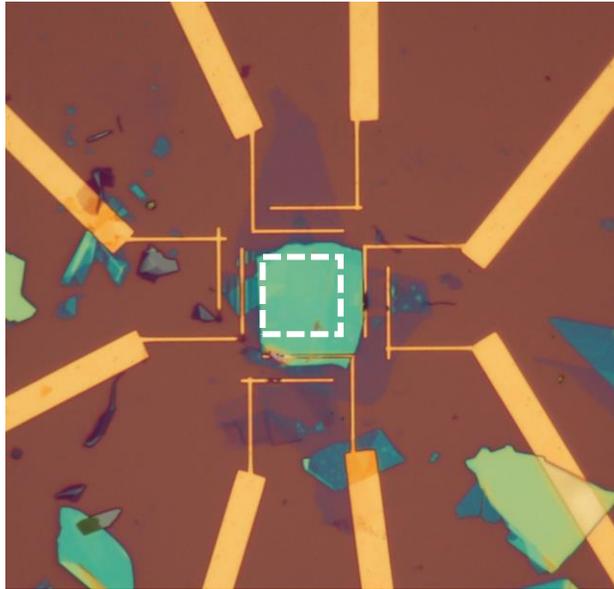


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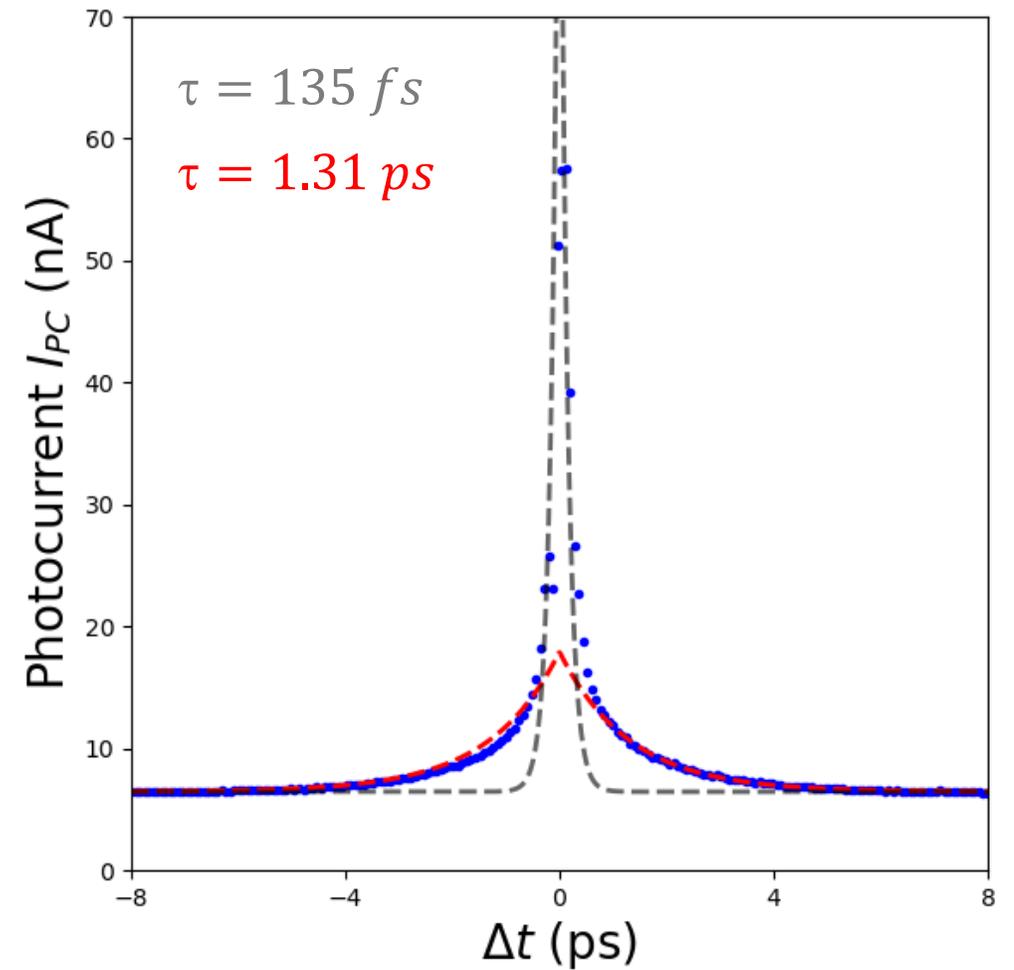
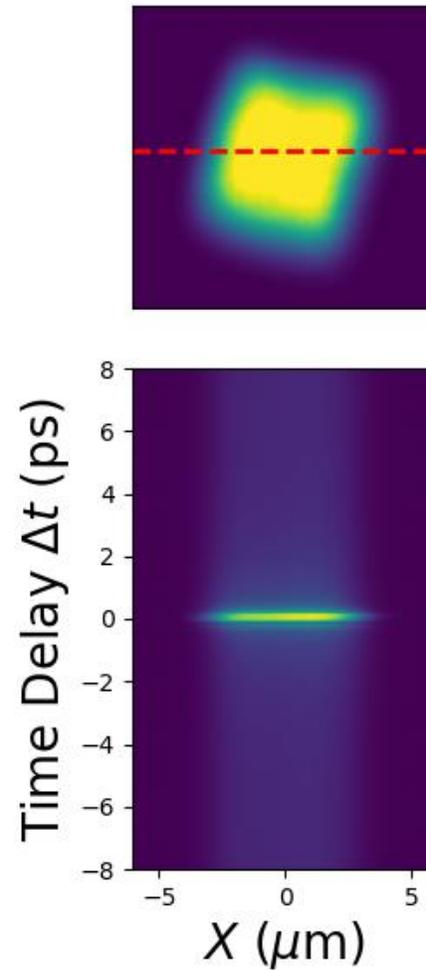
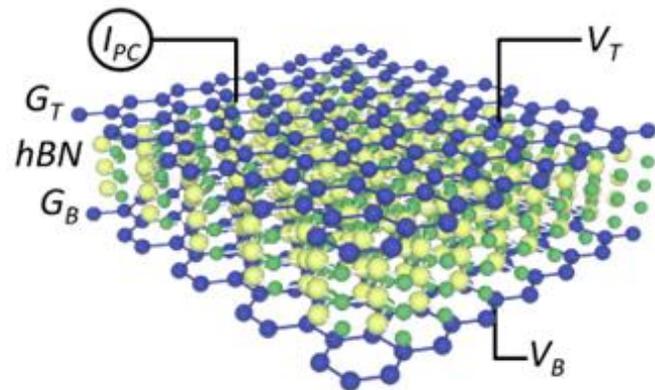
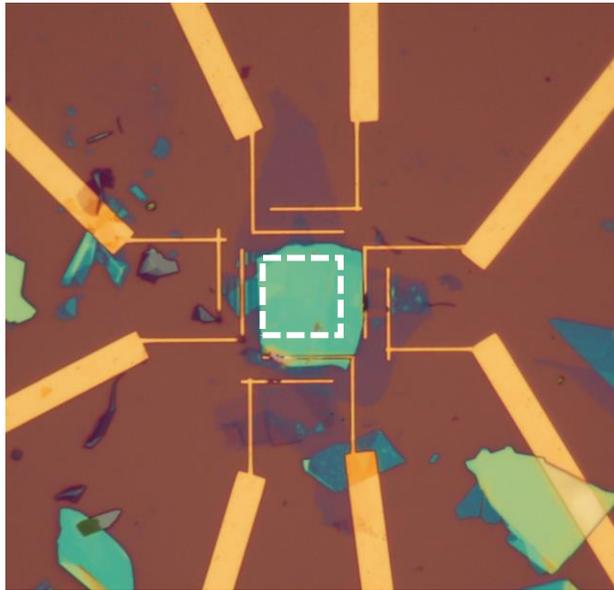
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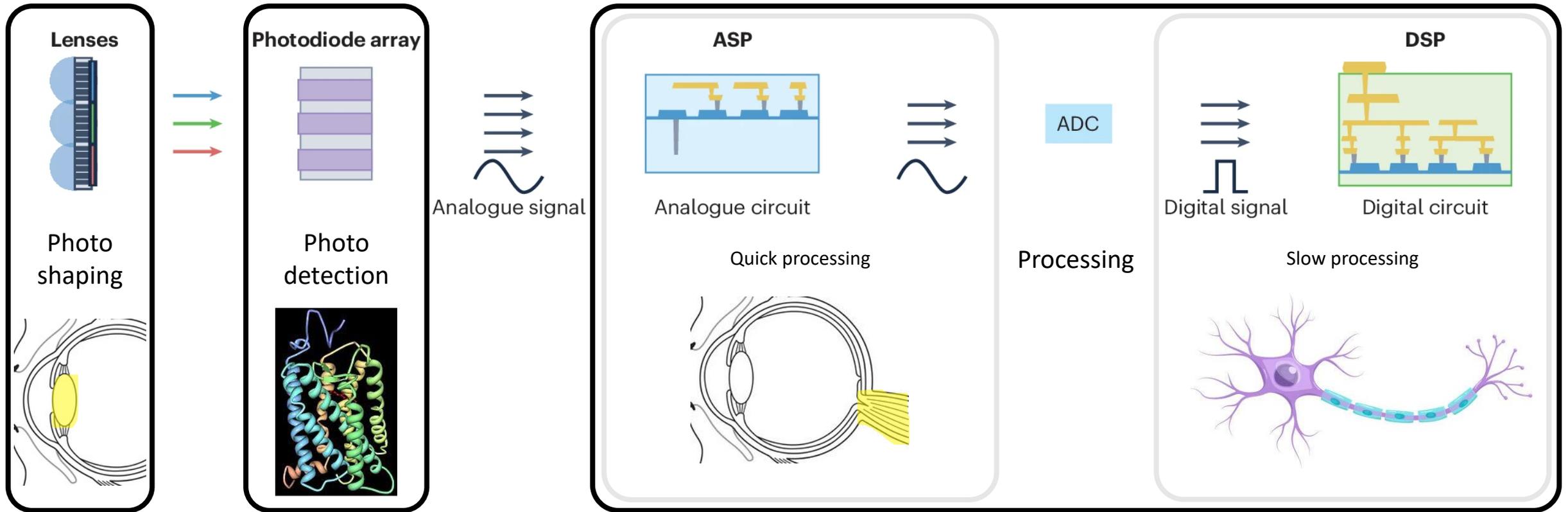
Infrared Nanoscale Optoelectronics Based on Graphene



(ultra)fast, nanoscale temperature sensor



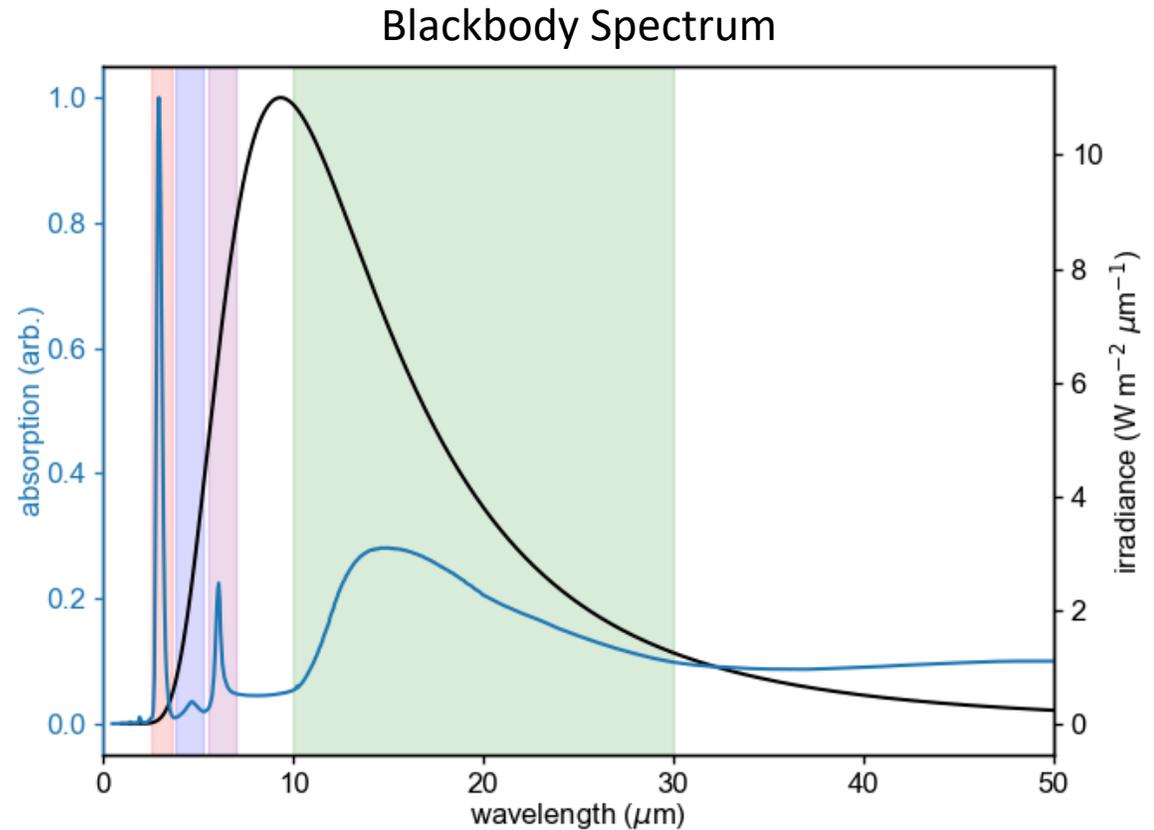
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Acknowledgements



QMO Lab



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Vivek Aji

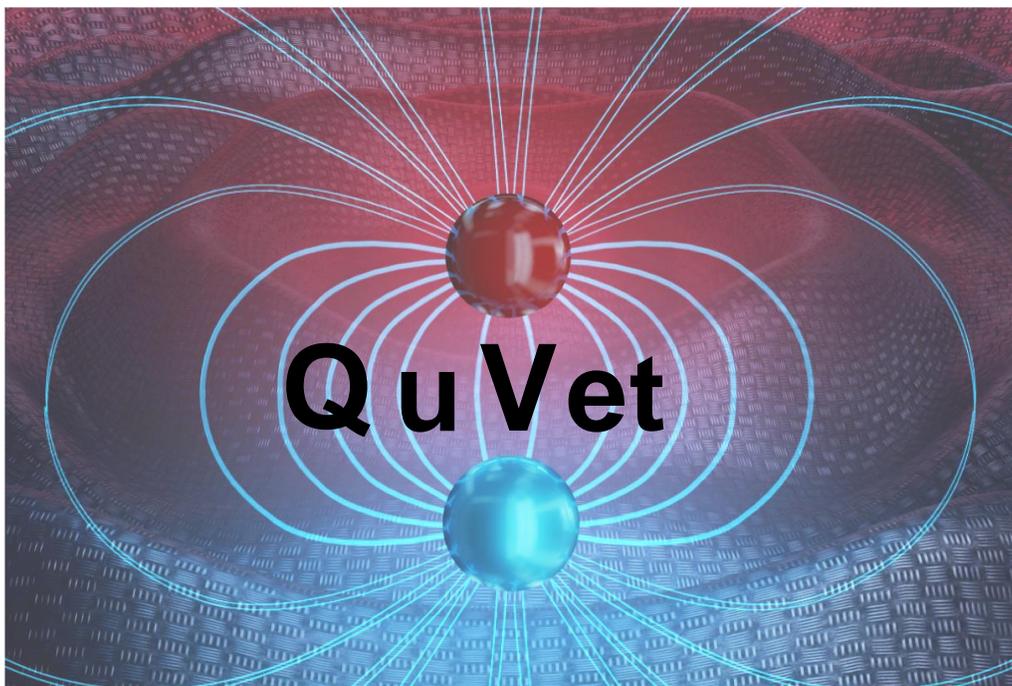


Zachary Miller



Trevor Arp

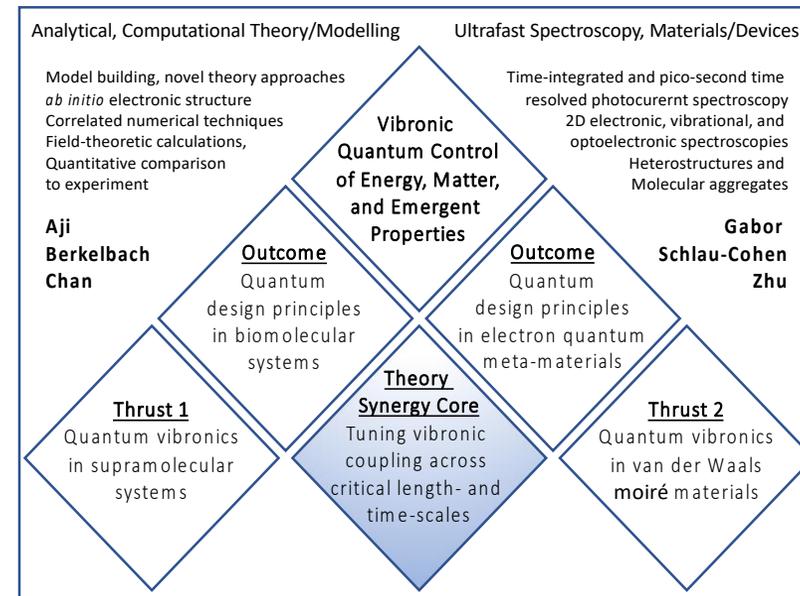




AMURI Center for
Quantum Vibrionics
in Energy and Time



PI: Nathaniel Gabor
(UCR)



Xiaoyang Zhu
(Columbia)



Gabriela Schlau-Cohen
(MIT)



Vivek Aji
(UCR)



Tim Berkelbach
(Columbia)



Garnet Chan
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