2016 Annual Review of the AFOSR DDDAS Program

Dr. Frederica Darema | January 27-29, 2016| Arlington, VA

Basic Research Innovation and Collaboration Center (BRICC) 4075 Wilson Blvd., Suite 350 – Liberty Room Arlington, VA 22203

	Agenda Day 1 – January 27, 2016		
Time	Title	Speaker	
7:30-8:00	Registration		
8:00-8:30	Introduction to the Program	Frederica Darema	
	Air Vehicle Structural Health Monitoring – Environment Cognizant		
8:30-10:00	 Advanced Simulation, Optimization, and Health Monitoring of Large Scale Structural Systems PI: Yuri Bazilevs (UCSD), and Team Dynamic Data-Driven Methods for Self-Aware Aerospace Vehicles PI: Karen Willcox (MIT), and Team Progressive Fault Identification and Prognosis in Aircraft Structure Based on Dynamic Data Driven Adaptive Sensing and Simulation Shiyu Zhou (U. Wisconsin) 		
10:00-10:15	BREAK		
10:15-11:15	 Robust Data-Driven Aero-elastic Flight Envelope Tailoring Balachandran, University of Maryland Dynamic Data-driven Prediction, Measurement Adaptation, and Active Control of Combustion Instabilities in Aircraft Gas Turbine Engines Asok Poy, PennState 		
11:15-12:15	 An Integrated Approach to the Space Situational Awareness Problem PI: Suman Chakravorty (TAMU), and Team Cloud Computing Based Robust Space Situational Awareness Raktim Bhattacharya, TexasA&M 		
12:15-12:45	LUNCH (Pick-up Lunches)		
12:45-3:00	Spatial Situational Awareness (UAV Swarms + Ground Systems Coordination)		
	 EAGER- Real-time Discovery and Timely Even Multi-Modal Data Streams Schaar, UCLA Dynamic Data-Driven Motion Planning and Con Awareness Application Systems PI: Sertac Karaman (MIT), and Team An Adaptive Distributed Approach to DDAS for Swarms 	ntrol for Pervasive Situational	

	 EAGER- Adaptive Ensemble-Based Uncertainty Prediction for Satellite Collision Avoidance Ridley, University of Michigan Ann Arbor EAGER- Management of Dynamic Big Sensory Data Cai, Georgia State University EAGER- Generative Statistical Modeling for Dynamic and Distributed Data Li(Jia), Pennsylvania State Univ 	
3:00-3:15	BREAK	
	(UAV Swarms + Ground Systems Coordination)	
3:15-4:15	 Dynamic Data Driven Adaptation via Embedded Software Agents for Border Control Scenario Pl: Shashi Phoha (Penn State), and Team Multiscale Analysis of Multimodal Imagery for Cooperative Sensing Pls: Erik Blasch, Guna Seetharaman, RI Directorate, AFRL Energy-Aware Time Change Detection using Synthetic Aperture Radar on High-Performance Heterogeneous Architectures: A DDDAS Approach Ranka, UofFlorida 	
4:15-5:00	 EAGER- Subspace Learning From Binary Sensing Chi, Ohio State University Cloud-Based Preception and Control of Sensor Nets and Robot Swarms Geoffrey Fox 	
5:00-6:00	Discussion of all Projects Discussed in Day 1	
6:00	MEETING ADJOURNED FOR THE DAY	

	Agenda Day 2 – January 28, 2016	
Time	Title	Speaker
7:30-10:00	 Dynamic Data Driven Information Fusion For Situational Awareness Biao Chen, Syracuse University Collaborative Image Processing in Vehicle Ensembles via Probabilistic Graphical Models and a Self-optimizing Support System Jose Martinez, Cornell U. Dynamic Modality Switching Aided Object Tracking using an Adaptive Sensor Matthew Hoffman, RIT Software for Data Streaming Analytics and its Application to Safer Flight Systems Varela, RPI DDDAMS-based Urban Surveillance and Crowd Control via Aerostats & UAVs and UGVs PI: Young-Jun Son (University of Arizona), and Team 	
10:00-10:15	BREAK	
10:15-12:15	 Energy Efficiencies (YIP) DDDAMS-based Real-time Assessment and Control of Electric-Microgrids PI: Nurcin Celik (University of Miami) EAGER- A Scalable Framework for Data-Driven real-Time Event Detection in Power Systems Dominguez-Garcia, UIUC EAGER- A Hierarchical Approach to Dynamic Big Data Analysis in Power Infrastructure Security Mohsenian-Rad, UCRiverside EAGER- Data-Driven Operation and Maintenance of Wind Energy Systems under Uncertainty 	
12:15-1:00	LUNCH	
1:00-3:00	 Space Weather and Atmospheric Events – Modeling/Observations Fluid SLAM and the Robotic Reconstruction of Localized Atmospheric Phenomena Pl: Sai Ravela (MIT) Retrospective Cost Model Refinement and State Estimation for Space Weather Modeling and Prediction Dennis Bernstein, UMich Dynamic Data-Driven UAV Network for Plume Characterization Pl: Kamran Mohseni (U. of Florida) 	

	 Sensing Coen, NCAR EAGER- Dynamic Data-Driven Random Sampling and Consensus for Large-Scale Learning Algorithms 	
	Multi-Agent Networks o Yin(Wotoo), UCLA	
3:15-3:30	BREAK	
	Sensing &Tracking	
3:30-4:30	 Optimized Routing of Intelligent, Mobile Sensors for Dynamic, Data-Driven Sampling PI: Derek Paley (UMD) A Distributed Dynamic Data Driven Applications System (DDDAS) for Multi-Threat Tracking Schizas, UTArlington 	
4:30-5:15	Materials Modeling	
	 Dynamic, Data-Driven Modeling of Nanoparticle Self Assembly Processes Y. Ding (TAMU), and Team EAGER- A New Scalable Paradigm for Optimal resource Allocation in Dynamic Data Systems via Multi-Scale and Multi-Fidelity Simulation and Optimization Xu(Jie), George Mason U. 	
5:15-6:00	Discussion of all Projects Discussed in Day 2	
6:00	MEETING ADJOURNED FOR THE DAY	

Agenda Day 3 – January 29, 2016		
Time	Title	Speaker
8:00-10:00	 Dynamic Integration of Motion and Neural Data to Capture Human Behavior PI: Dimitri Metaxas (Rutgers U), and Team inadvertently Stateless Networking: Principles, Architectures, and Codes Wornell, MIT Stateless Networking: Principles, Architectures, and Codes, Parrilo, MIT Universal Laws and Architectures John Doyle, CalTech 	
10:00-10:15	BREAK	
10:15-12:15	 Using Trajectory Sensor Data Stream Cleaning to Ensure the Survivability of Mobile Wireless Sensor Networks in Cyberspace Pl: Niki Pissinou, Florida International University Adaptive Stream Mining: A Novel Dynamic Computing Paradigm for Knowledge Extraction Pl: Shuvra Bhattacharyya (U. Of Maryland) and Team Data-Adaptable Modeling and Optimization for Runtime Adaptable Systems Roman Lycesky Cloud support for Surveillance Alex Aved, AFR:/RI 	
12:15-1:00	LUNCH (Pick-up Lunches) Discussion of all Projects Discussed in Morning of Day 3	
1:00-2:00	 Systems Software CyberSecurity Data-Driven and Real-Time Verification for Industrial Control System Security Kevin Jin (Illinois Institute of Technology) DDDAS-based Resilient Cyberspace (DRCS) PI: Salim Hariri (University of Arizona. Tucson), and Team 	
2:00-3:00	Systems Software	
	 Performance Analysis and Diagnosis of Cloud- <i>Mohammad Khan, UConn</i> (YIP) From Sensor Data to High-value Information deriving inferences from complex embedded single Naveen Verma (Princeton U.) 	tion: ultra-low-energy platforms for
3:00-3:15	BREAK	
	Systems Software (cont'd)	

6:00		
4:45-6:00		
3:15-4:45	 Amorphous Polyhedral Model for Stochastic Control of Autonomous UAVs <i>PI: Sanjay</i> Rajopadhye (Colorado State) Architecture and Programming Models for High Performance Interactive Computation <i>PI: XiaoMing Li and Guang Gao</i> (U of Delaware) ; Jack Dennis and Arvind (MIT) Hybrid Systems Modeling and Middleware-enabled DDDAS for Next-generation US Air Force Systems <i>PI: Aniruddha Gokhale (Vanderbilt U.), and Team</i> 	