## 2016 Annual Review of the AFOSR DDDAS Program

Dr. Frederica Darema | January 27-29, 2016 | Arlington, VA

Basic Research Innovation and Collaboration Center (BRICC) 4075 Wilson Blvd., Suite 350 – Liberty Room Arlington, VA 22203

## Agenda Day 1 - January 27, 2016

Time	Title	Speaker
7:30-8:00	Registration	
8:00-8:30	Introduction to the Program	Frederica Darema and Chengshan Xiao
	Air Vehicle Structural Health Monitoring – Environn	nent Cognizant
8:30-10:00	<ul> <li>Advanced Simulation, Optimization, and Health Monitoring of Large Scale Structural Systems         <ul> <li>PI: Yuri Bazilevs (UCSD), and Team</li> </ul> </li> <li>Dynamic Data-Driven Methods for Self-Aware Aerospace Vehicles         <ul> <li>PI: Karen Willcox (MIT), and Team</li> </ul> </li> <li>Progressive Fault Identification and Prognosis in Aircraft Structure Based on Dynamic Data Driven Adaptive Sensing and Simulation         <ul> <li>Shiyu Zhou (U. Wisconsin)</li> </ul> </li> </ul>	
10:00-10:15	BREAK	
10:15-11:15	<ul> <li>Robust Data-Driven Aero-elastic Flight Envelope Tailoring         <ul> <li>Balachandran, University of Maryland</li> </ul> </li> <li>Dynamic Data-driven Prediction, Measurement Adaptation, and Active Control of Combustion Instabilities in Aircraft Gas Turbine Engines         <ul> <li>Asok Ray, PennState</li> </ul> </li> </ul>	
11:15-12:15	<ul> <li>An Integrated Approach to the Space Situation</li> <li>PI: Suman Chakravorty (TAMU), and</li> <li>Cloud Computing Based Robust Space Situation</li> <li>Raktim Bhattacharya, TexasA&amp;M</li> </ul>	Team
12:15-12:45	LUNCH (Pick-up Lunch	nes)
	Spatial Situational Awareness (UAV Swarms + Grou	und Systems Coordination)
12:45-3:00	<ul> <li>EAGER- Real-time Discovery and Timely Event Detection from Dynamic and Multi-Modal Data Streams         <ul> <li>Schaar, UCLA</li> </ul> </li> <li>Dynamic Data-Driven Motion Planning and Control for Pervasive Situational Awareness Application Systems         <ul> <li>PI: Sertac Karaman (MIT), and Team</li> </ul> </li> <li>An Adaptive Distributed Approach to DDAS for Surveillance Missions with UAV Swarms         <ul> <li>Gupta, U of NotreDame</li> </ul> </li> </ul>	

	<ul> <li>EAGER- Adaptive Ensemble-Based Uncertainty Prediction for Satellite Collision Avoidance         <ul> <li>Ridley, University of Michigan Ann Arbor</li> </ul> </li> <li>EAGER- Management of Dynamic Big Sensory Data         <ul> <li>Cai, Georgia State University</li> </ul> </li> <li>EAGER- Generative Statistical Modeling for Dynamic and Distributed Data         <ul> <li>Li(Jia), Pennsylvania State Univ</li> </ul> </li> </ul>	
3:00-3:15	BREAK	
	(UAV Swarms + Ground Systems Coordination)	
3:15-4:15	<ul> <li>Dynamic Data Driven Adaptation via Embedded Software Agents for Border Control Scenario         <ul> <li>PI: Shashi Phoha (Penn State), and Team</li> </ul> </li> <li>Multiscale Analysis of Multimodal Imagery for Cooperative Sensing         <ul> <li>PIs: Erik Blasch, Guna Seetharaman, RI Directorate, AFRL</li> </ul> </li> <li>Energy-Aware Time Change Detection using Synthetic Aperture Radar on High-Performance Heterogeneous Architectures: A DDDAS Approach         <ul> <li>Ranka, UofFlorida</li> </ul> </li> </ul>	
4:15-5:00	<ul> <li>EAGER- Subspace Learning From Binary Sensing         <ul> <li>Chi, Ohio State University</li> </ul> </li> <li>Cloud-Based Preception and Control of Sensor Nets and Robot Swarms         <ul> <li>Geoffrey Fox</li> </ul> </li> </ul>	
5:00-6:00	Discussion of all Projects Discussed in Day 1	
6:00	MEETING ADJOURNED FOR THE DAY	

	Agenda Day 2 – January 28, 2016	
Time	Title	Speaker
7:30-10:00	<ul> <li>Dynamic Data Driven Information Fusion For Some Biao Chen, Syracuse University</li> <li>Collaborative Image Processing in Vehicle Ensimoles and a Self-optimizing Support System Jose Martinez, Cornell U.</li> <li>Dynamic Modality Switching Aided Object Traction Matthew Hoffman, RIT</li> <li>Software for Data Streaming Analytics and its Active Varela, RPI</li> <li>DDDAMS-based Urban Surveillance and Crowand UGVs</li> <li>PI: Young-Jun Son (University of Arizon</li> </ul>	sembles via Probabilistic Graphical cking using an Adaptive Sensor Application to Safer Flight Systems rd Control via Aerostats & UAVs
10:00-10:15	BREAK	
10:15-12:15	Energy Efficiencies  > (YIP) DDDAMS-based Real-time Assessment	En real-Time Event Detection in  Big Data Analysis in Power  Ince of Wind Energy Systems under  Parcos Data-driven Morphing of Reduced  Chnology Ea-Driven Morphing of Nodal
12:15-1:00	LUNCH	
1:00-3:00	Space Weather and Atmospheric Events – Modeling/Observations  ➤ Fluid SLAM and the Robotic Reconstruction of Localized Atmospheric Phenomena  ○ Pl: Sai Ravela (MIT)  ➤ Retrospective Cost Model Refinement and State Estimation for Space Weather Modeling and Prediction  ○ Dennis Bernstein, UMich  ➤ Dynamic Data-Driven UAV Network for Plume Characterization  ○ Pl: Kamran Mohseni (U. of Florida)  ➤ EAGER- Transforming Wildfire Detection and Growth Forecasting with Smart	

	Sensing  Coen, NCAR  EAGER- Dynamic Data-Driven Random Sampling and Consensus for Large-Scale Learning Algorithms Giannakis, University of Minnesota  EAGER- Novel Approaches for Optimization, Control, and Learning in Distributed Multi-Agent Networks  Yin(Wotoo), UCLA	
3:15-3:30	BREAK	
	Sensing &Tracking	
3:30-4:30	<ul> <li>Optimized Routing of Intelligent, Mobile Sensors for Dynamic, Data-Driven Sampling         <ul> <li>PI: Derek Paley (UMD)</li> </ul> </li> <li>A Distributed Dynamic Data Driven Applications System (DDDAS) for Multi-Threat Tracking         <ul> <li>Schizas, UTArlington</li> </ul> </li> </ul>	
4:30-5:15	Materials Modeling	
	<ul> <li>Dynamic, Data-Driven Modeling of Nanoparticle Self Assembly Processes         <ul> <li>Y. Ding (TAMU), and Team</li> </ul> </li> <li>EAGER- A New Scalable Paradigm for Optimal Resource Allocation in Dynamic Data Systems via Multi-Scale and Multi-Fidelity Simulation and Optimization         <ul> <li>Xu(Jie), George Mason U.</li> </ul> </li> </ul>	
5:15-6:00	Discussion of all Projects Discussed in Day 2	
6:00	MEETING ADJOURNED FOR THE DAY	

	Agenda Day 3 – January 29,	, 2016	
Time	Title	Speaker	
8:00-10:00	<ul> <li>Dynamic Integration of Motion and Neural Operation of PI: Dimitri Metaxas (Rutgers U),</li> <li>Stateless Networking: Principles, Archite Operation Wornell, MIT</li> <li>Stateless Networking: Principles, Archite Parrilo, MIT</li> <li>Universal Laws and Architectures Operation John Doyle, CalTech</li> </ul>	and Team inadvertently ctures, and Codes	
10:00-10:15	BREAK		
10:15-12:15	<ul> <li>Using Trajectory Sensor Data Stream Cleaning to Ensure the Survivability of Mobile Wireless Sensor Networks in Cyberspace         <ul> <li>Pl: Niki Pissinou, Florida International University</li> </ul> </li> <li>Adaptive Stream Mining: A Novel Dynamic Computing Paradigm for Knowledge Extraction         <ul> <li>Pl: Shuvra Bhattacharyya (U. Of Maryland) and Team</li> </ul> </li> <li>Data-Adaptable Modeling and Optimization for Runtime Adaptable Systems         <ul> <li>Roman Lysecky</li> </ul> </li> <li>Cloud support for Surveillance         <ul> <li>Alex Aved, AFR:/RI</li> </ul> </li> </ul>		
12:15-1:00	LUNCH (Pick-up Lunches) Discussion of all F	Projects Discussed in Morning of Day 3	
1:00-2:00	Systems Software CyberSecurity  Data-Driven and Real-Time Verification for Industrial Control System Se  Kevin Jin (Illinois Institute of Technology)  DDDAS-based Resilient Cyberspace (DRCS)  Pl: Salim Hariri (University of Arizona. Tucson), and Team		
	Systems Software		
2:00-3:00	Performance Analysis and Diagnosis of Cloud-based DDDAS Application  Mohammad Khan, UConn  (YIP) From Sensor Data to High-value Information: Ultra-low-energy Platfing Deriving Inferences from Complex Embedded Signals  Naveen Verma (Princeton U.)		
3:00-3:15	BREAK		

6:00
4:45-6:00
3:15-4:45